



(11)

EP 2 930 432 B1

(12)

EUROPEAN PATENT SPECIFICATION

(45) Date of publication and mention
of the grant of the patent:
19.09.2018 Bulletin 2018/38

(51) Int Cl.:
A47J 27/62 ^(2006.01) **F24C 7/08** ^(2006.01)

(21) Application number: **15162370.9**

(22) Date of filing: **02.04.2015**

(54) **OVEN COMPRISING WEIGHT SENSORS**

GAROFEN MIT GEWICHTSSENSOREN

FOUR COMPRENANT DES CAPTEURS DE POIDS

(84) Designated Contracting States:
**AL AT BE BG CH CY CZ DE DK EE ES FI FR GB
GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO
PL PT RO RS SE SI SK SM TR**

(30) Priority: **07.04.2014 IT TO20140292**

(43) Date of publication of application:
14.10.2015 Bulletin 2015/42

(73) Proprietor: **Whirlpool EMEA S.p.A.
20016 Pero (MI) (IT)**

(72) Inventors:
• **Matarazzi, Filippo
06023 Gualdo Tadino (PG) (IT)**
• **Ratti, Carlo Filippo
10131 Torino (IT)**

• **Pedrazzo, Marco Maria
12100 Cuneo (IT)**

(74) Representative: **Spina, Alessandro et al
Whirlpool EMEA SpA
Via Carlo Pisacane, 1
20016 Pero (MI) (IT)**

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Description**[TECHNICAL FIELD]**

[0001] The present invention relates to the field of household cooking appliances.

In particular, the invention relates to an oven comprising a heated cavity, with which sensors are associated for detecting characteristics of the foods in the cavity.

[PRIOR ART]

[0002] As is known, preparing food by means of an oven poses a number of problems: since food is cooked in a closed environment, it is always difficult to tell when cooking is complete. In fact, although ovens are usually provided with a door that is at least partially transparent, and with lighting means mounted inside the oven itself, evaluating the actual degree of cooking is still a complex operation.

Moreover, when the user tries to overcome this problem by opening the door to directly observe the food, he/she will risk to interrupt the cooking cycle in an uncontrolled manner, thus making the continuation of the same more difficult and less deterministic, while also risking burns and scalds caused by the high temperature that can be reached inside the oven in operation.

In addition, the user of an oven according to the prior art has no specific information at his/her disposal about the cooking of the food; in particular, in order to determine cooking temperatures and times the user must rely on recipe books. Such recipe books, however, may be inaccurate or anyway inadequate for the specific characteristics of the food, of the oven, or of the interaction between them.

[0003] DE102011009991 discloses a cooking appliance comprising a cooking chamber, in which several accessory parts are arranged, on which food is arranged, at least one antenna arranged in the cooking chamber, with which acoustic wave sensors are read and an evaluation unit for evaluating the signal of the acoustic wave sensors, in terms of a load detection.

[0004] EP1489887 discloses an oven that comprises a heated cavity for cooking a food, supporting means configured for supporting a shelf in said heated cavity and comprising at least one weight sensor apt to detect the weight of the food positioned on the shelf and a CCD camera apt to acquire information about the shape of the food.

[0005] EP1918643 discloses a cooking apparatus and method of displaying caloric information, capable of calculating fat removed by the cooking process in terms of caloric value and of displaying the removed caloric value information to a user.

[0006] DE20016793 discloses a cooking appliance with a cooking chamber and at least one sensor for detecting the mass and/or the mass changes of the food cooked in the cooking chamber.

[OBJECTS AND SUMMARY OF THE INVENTION]

[0007] It is the object of the present invention to overcome some of the problems of the prior art.

[0008] In particular, it is one object of the present invention to provide a system which allows a more reliable evaluation of the characteristics of the food being prepared, without requiring that the oven door be opened.

[0009] It is another object of the present invention to provide a system that allows the user to better evaluate the cooking conditions of the specific food in the oven.

[0010] It is a further object of the present invention to provide a system that improves the interaction between the user and the household appliance, so as to make the latter more pleasant to use.

[0011] These and other objects of the present invention are achieved through an oven incorporating the features set out in the appended claims, which are an integral part of the present description.

[0012] An idea at the basis of the present invention is to envisage that some characteristics of the food being cooked in the heated cavity of the oven can be detected through suitable sensors and then made available to the user in processed form.

[0013] A typology of sensors suitable for this purpose comprises a three-dimensional scanning system configured for acquiring information about the volume and/or shape of a food positioned in the heated cavity of the oven.

[0014] The three-dimensional scanning system is preferably arranged in the upper part of the heated cavity; by framing the food, it can reconstruct a three-dimensional model from which it can derive information such as the occupied volume; through a comparison with a database and image recognition algorithms, it is thus possible to identify the typology of the food in the cavity and a typical reference composition thereof, including nutritional values.

[0015] A sensor typology suitable for this purpose further comprises at least one weight sensor configured for detecting the weight of a food positioned on a shelf supported by supporting means positioned in the heated cavity of the oven.

[0016] The weight sensor incorporated in the oven, preferably associated with the shelf supporting guides, essentially measures the weight of the food positioned on the shelf.

[0017] Food typology and weight are important parameters that describe in a complete manner the food contained in the oven.

[0018] The user can thus obtain important information about the food in the oven, the cooking conditions, and the nutritional values of such food. With such information, the user can intervene, if necessary, in order to modify/stop/improve the cooking operation.

[0019] It is clear that the three-dimensional scanning system and the weight sensor may advantageously cooperate to define a plurality of pieces of information as-

sociated with the food; however, it should be taken into account that these two systems may also operate independently, in which case, of course, the returned information will cover a narrower range. In the following description a preferred but non-limiting embodiment will be described, wherein the three-dimensional scanning system and the weight sensor coexist in the same oven, resulting in advantages that will be immediately apparent.

[0020] Further particular and advantageous purposes and aspects of the present invention will be illustrated in the detailed description that follows, in the annexed drawings and in the appended claims, which are an integral part of the present description.

[BRIEF DESCRIPTION OF THE DRAWINGS]

[0021] Some preferred and advantageous embodiments will now be described by way of non-limiting example with reference to the annexed drawings, wherein:

- Figure 1 shows an oven according to the present invention.
- Figure 2 shows the operation of the oven of Figure 1, into which a food as been inserted.
- Figure 3 is a three-dimensional reconstruction of the food of Figure 2.
- Figure 4 shows some operating connections between units of the oven of Figure 1.
- Figure 5 shows some further operating connections between units of the oven of Figure 1.
- Figure 6 shows a further operating connection between the oven of Figure 2 and an associable device.

[0022] The drawings show different aspects and embodiments of the present invention and, where appropriate, similar structures, components, materials and/or elements in the various drawings are designated by the same reference numerals.

[DETAILED DESCRIPTION OF THE INVENTION]

[0023] Figure 1 illustrates an oven 101 representing as a whole a system for heating and/or cooking food in accordance with the present invention, of which only those components of most interest will be described herein.

[0024] The oven 101 comprises a heated cavity 102, which is heated by heating means (not shown) configured in accordance with known teachings. In particular, the oven 101 is just an explanatory example; as far as the heating means are concerned, this may be an electric or combined oven, but also a gas oven, a microwave oven, etc.

[0025] The oven 101 comprises, inside the heated cavity 102, a plurality of supporting means 103, i.e. a plurality of horizontal guides 103, which define support planes for a shelf 105 that can be inserted into the cavity 102.

[0026] In the embodiment of Figure 1, the shelf 105,

also referred to as dripping pan 105 or baking pan 105, can be inserted into the cavity 102 at five different heights, defined by respective horizontal guides 103 on the left and right sides of the cavity 102.

[0027] The oven 101 comprises at least one weight sensor 104, which is adapted to detect the weight of a food positioned on the shelf. In particular, the oven 101 comprises a plurality of load cells 104, which are associated with each one of the horizontal guides 103 to detect the weight of the shelf 105 when it is housed inside the heated cavity 102.

[0028] The load cells 104 are transducers that convert into an electric signal a force (in this case, the weight force of the shelf 105) to which they are subjected. Preferably, each one of the load cells 104 includes a mechanical assembly, whereby the force to which the load cell is subjected is transferred to a calibrated deformable element; the deformation of the element is measured by transducers, such as extensometers or the like, and possibly compensated for temperature variations in order to obtain the deformation and hence, through calibration, the force to which the load cell is subjected.

[0029] Preferably, the oven 101 has four load cells for each one of the various heights of the shelf 105, so as to estimate the weight of the shelf 105 and of the food placed thereon. In particular, the load cells 104 are adapted to measure the total weight of the shelf 105 and of any food present thereon, and to obtain the weight of the food being cooked in the cavity 102 by subtracting the weight of the shelf 105, which is known.

[0030] Preferably, the oven 101 includes a multi-cooking mode, wherein two or more shelves are inserted into the heated cavity 102, at different heights, supported by the supporting means 103. On such two or more shelves different foods can be positioned for cooking. The oven 101 is therefore configured for separately detecting the weight of the foods positioned on each one of the shelves, thanks to the plurality of weight sensors 104 located at respective different heights on the horizontal guides 103.

The oven 101 comprises a three-dimensional scanning system 106 positioned in the cavity 102 above the shelf 105, when the latter is in the oven 101.

[0031] The three-dimensional scanning system 106 is configured for acquiring information about the volume and/or shape of the food that may be positioned on the shelf 105, in manners that will be described more in detail below.

[0032] Of course, the oven 101 is provided with a door that can be opened/closed to allow access to the inside of the confined volume of the heated cavity 102, which door is not shown, for simplicity, in Figure 1.

[0033] Figure 2 represents the oven 101 in a schematic manner to illustrate the operation thereof.

[0034] When food 201 is inserted into the cooking cavity 102 on the shelf 105, its weight is evaluated by the load cells 104 as previously described.

[0035] Furthermore, the food 201 is subjected to the measurement carried out by the three-dimensional scan-

ning system 106.

[0036] In a preferred embodiment, the three-dimensional scanning system 106 comprises at least one image sensor for framing the food 201, and at least one light source for illuminating the food 201.

[0037] In a preferred embodiment, the three-dimensional scanning system 106 envisages the use of three-dimensional object recognition techniques, which allow high-definition scanning of objects arranged close to the sensor. In particular, it is envisaged to use a three-dimensional scanning system of the type called "leap motion", as will be described below.

[0038] The three-dimensional scanning system 106 preferably uses two monochromatic infrared (IR) cameras and three infrared (IR) LED light sources. The use of infrared light (in particular, near infrared light) allows illuminating the food 201 with rays that will not disturb the user's vision; on the contrary, they are "transparent" and colorless, resulting in more natural use. Different systems may however also be employed, e.g. operating in the visible light range.

[0039] Infrared cameras observe a substantially hemispherical area, at a maximum distance of 1 m from the sensor; such area is illuminated by the infrared LED light sources according to preset patterns. The data processing unit (not shown) of the system 106 can analyze the plurality of images acquired by the IR cameras in different illumination conditions provided by the IR LEDs.

[0040] As shown in Figure 3, the system 106 can then reconstruct a three-dimensional image of the food 201 and obtain, through further processing, additional information from the three-dimensional image of the food, as will be described below.

[0041] As shown in Figure 4, the oven 101 is associated with processing means 401 operationally connected to the three-dimensional scanning system 106.

[0042] The oven 101 is also associated with processing means 401 operationally connected to the load cells 104.

[0043] Preferably, the operating connection is established by means of a USB protocol, particularly for the three-dimensional scanning system 106.

[0044] The processing means 401, therefore, incorporate weight processing means for the information acquired by the weight sensor 104.

[0045] Likewise, the processing means 401 incorporate three-dimensional scan processing means for the information acquired by the three-dimensional scanning system 106.

[0046] The processing means 401 are further operationally connected to a memory 402.

[0047] The memory 402 comprises weight reference information, which allows the weight processing means to obtain indications about the weight of the food 201. For example, the weight processing means are adapted to recognize the characteristics of the shelf 105, including its weight, and to calculate the weight of the food 201 by taking into account the correct tare.

[0048] The memory 402 comprises reference three-dimensional scan information, which allows the three-dimensional scan processing means to obtain information about the shape and/or volume of the food 201, as previously described with reference to the sensor 106; in this case, the three-dimensional scan processing means integrate all or some of the functions of the above-mentioned data processing unit of the system 106.

[0049] The processing means 401 are associated with the oven 101, meaning by this that they may be comprised either in the oven 101 or in a separate electronic device associable therewith through various protocols, even wireless ones. Likewise, the memory 402 is associated with the oven 101, meaning by this that it may be comprised either in the oven 101 or in an electronic device, even a remote one.

[0050] As shown in Figure 5, the processing means 401 are further associated with a memory 502, which may coincide or not with the memory 402. Figure 4 is therefore connected to Figure 5 by the presence of the processing means 401, but such Figures are shown separately for better intelligibility.

[0051] The processing means 401 are then adapted to gather further information by comparing the information about the weight of the food 201 acquired by the weight sensor 104 with further information residing in the memory 502. In particular, the processing means 401 are adapted to provide indications about the cooking of the food 201, as shown in the screen 503; in fact, if the weight of a food is known, it becomes possible to estimate the time and/or temperature necessary for cooking it, by referring to appropriate information that can be represented in table form.

[0052] The processing means 401 are also adapted to gather further information by comparing the information about the shape and/or volume of the food 201 acquired by the three-dimensional scanning system 106 with further information residing in the memory 502. In particular, the processing means 401 are adapted to provide indications about the typology of the food 201, thus recognizing the type of food (e.g. "chicken, meat, casserole, pie, pizza, etc."). In particular, the processing means 401 are adapted to execute, in association with the information residing in the memory 502, image recognition algorithms for recognizing the typology of the food being observed by the three-dimensional scanning system.

[0053] Furthermore, the processing means 401 are also adapted to, by cooperatively exploiting the information gathered by the three-dimensional scan processing means and by the weight processing means, compare the detected volume of a food with the detected weight of a food, in order to obtain the specific weight of the same. It is thus possible, based on the specific weight of a food, to identify in a more accurate manner the type of food inserted in the cavity.

[0054] The processing means 401 are further adapted to provide indications about the average nutritional values of the food 201, once it has been recognized, as

shown in the screen 504; in fact, if the typology of a food is known, it becomes possible to estimate the nutritional values thereof by exploiting appropriate information that can be represented in table form, particularly when additional information is available, such as the recipe used for cooking the food. The processing means 401 are also adapted to provide indications about the cooking of the food 201, starting from the information gathered by the three-dimensional scanning system 106: in fact, if the volume and typology of a food are known, it becomes possible to estimate the weight thereof and the time and/or temperature necessary for cooking it, by exploiting appropriate average value information that can be represented in table form.

[0055] Furthermore, in particular, the processing means 401 are adapted to, by cooperatively exploiting the information gathered by the three-dimensional scanning means and by the weight processing means, provide the user with more accurate information. Such information comprises: cooking time of a food 201, the typology and weight of which are known; nutritional values of a food 201, the typology and weight and, preferably, the cooking mode of which are known.

[0056] In addition or as an alternative, the processing means 401 are configured for determining, based on the data obtained by the three-dimensional scanning system and/or by the weight sensor, one or more of the following characteristic parameters:

- a. a first parameter representative of the food typology;
- b. a second parameter representative of the food weight;
- c. a third parameter representative of the volume occupied by the food;
- d. a fourth parameter representative of the food cooking indications, such as time and temperature, and/or, more generally, of the cooking program;
- e. a set of parameters representative of a food composition, preferably comprising nutritional values of the food.

[0057] Furthermore, in particular, the processing means 401 are adapted to provide the user with information about the time evolution of the food cooking process, particularly by monitoring the variations in weight and/or volume and/or shape of the food over time, as described above. In this way, it is possible to further improve the information about the adopted cooking mode.

[0058] Such indications can be represented on a suitable user interface of the oven 101.

[0059] Moreover, should the processing means 401 be unable to accurately determine the typology of the food in the cavity, the user may be requested to confirm the food typology, choosing from a list prepared by the processing means 401. When observing croquettes, for example, the processing means 401 will be able to detect the shape and weight of the croquette, but will not be

able to accurately determine whether it is a chicken, fish or potato croquette. In such a case, a suitable user interface of the oven 101 will ask the user to give a confirmation indicating the typology of the food present in the cavity, i.e. in this example "chicken croquette" or "fish croquette" or "potato croquette". In this way, it is possible to improve the recognition of the food typology.

[0060] Figure 6 illustrates a further variant of the oven 101, which comprises a transmission unit (not shown), preferably a wireless one, adapted to transmit 601 information to a device 602.

[0061] The device 602 may advantageously be a display device, by means of which the information transmitted 601 by the oven 101 can be displayed, preferably in the form of an "app". In this embodiment, the processing means 401 are integrated into the oven 101.

[0062] In another embodiment, the device 602 may be a processing and display device through which all or some of the information can be processed as described with reference to the processing means 401, while also displaying the information provided by the oven 101, preferably in the form of an "app". In this embodiment, the processing means 401 are at least partially external to the oven 101, in particular at least partially comprised in the device 602.

[0063] Preferably, the association between the oven 101 and the device 602 is made in wireless mode, preferably through protocols such as Bluetooth or WiFi, or preferably through IP protocols, also over the Internet.

[0064] In the preferred embodiment, the auxiliary device 602 is a smartphone or a tablet, which can be connected to multiple apparatuses or household appliances within a household environment.

[0065] It is obvious that, in the light of the teachings of the present description, the man skilled in the art may conceive further variants of the present invention, without however departing from the protection scope as defined by the appended claims.

[0066] For example, the three-dimensional scanning processing means and the weight processing means may be separated into distinct units.

[0067] Also, the load cells may be replaced with various other types of weight sensors, by adopting technical measures known in the art.

Claims

1. Oven (101) comprising a heated cavity (102) for cooking a food (201), supporting means (103) positioned in said heated cavity (102) and configured for supporting a shelf (105) in said heated cavity (102), said supporting means (103) comprising at least one weight sensor (104) configured for detecting the weight of a food (201) positioned on said shelf (105), said oven being **characterized by** further comprising a three-dimensional scanning system (106) configured for acquiring information about the volume

of a food (201) positioned in said heated cavity (102).

2. Oven according to claim 1, comprising a plurality of said supporting means (103) configured for supporting a shelf (105) at different heights in said heated cavity (102), and further comprising a respective plurality of said weight sensors (104). 5
3. Oven according to claim 2, wherein said weight sensors (104) arranged at each height in said heated cavity (102) comprise a plurality of load cells (104), preferably four of them, configured for detecting the weight of a food positioned on said shelf (105). 10
4. Oven according to any one of claims 1 to 3, further associated with weight processing means (401) operationally connected to a memory (402, 502) storing reference weight information, and also operationally connected to said at least one weight sensor (104). 15
5. Oven according to claim 4, wherein said weight processing means (401) are adapted to provide indications (503) about the cooking of said food (201) by comparing said information about the weight of said food with said reference weight information. 20
6. Oven according to claim 4 or 5, wherein said weight processing means (401) are further adapted to provide information (503) about the weight of said food (201), netted of the tare weight of said shelf (105). 25
7. Oven according to any one of claims 1 to 6, wherein said three-dimensional scanning system (106) comprises at least one image sensor positioned in said heated cavity (102) and adapted to acquire images of said food (201), and further comprises at least one light source positioned in said heated cavity (102) and adapted to illuminate said food (201). 30
8. Oven according to claim 7, further associated with three-dimensional scan processing means (401) operationally connected to a memory (402, 502) storing reference three-dimensional scan information, and also operationally connected to said three-dimensional scanning system (106), wherein said three-dimensional scan processing means are adapted to determine the typology of said food (201) by comparing said information about the volume and/or shape of said food (201) with said reference three-dimensional scan information. 35
9. Oven according to any one of claims 1 to 8, further comprising transmission means (601) configured for sending information about said food (201) to an external device (602). 40

Patentansprüche

1. Ofen (101), umfassend einen erwärmten Hohlraum (102) zum Zubereiten eines Nahrungsmittels (201), wobei Tragmittel (103) in dem erwärmten Hohlraum (102) positioniert sind und zum Tragen eines Einlegebodens (105) in dem erwärmten Hohlraum (102) eingerichtet sind, wobei die Tragmittel (103) mindestens einen Gewichtssensor (104) umfassen, der zum Erfassen des Gewichts eines auf dem Einlegeboden (105) positionierten Nahrungsmittels (201) eingerichtet ist, wobei der Ofen **dadurch gekennzeichnet ist, dass** er weiter ein dreidimensionales Abtastsystem (106) umfasst, das zum Beschaffen von Informationen über das Volumen eines in dem erwärmten Hohlraum (102) positionierten Nahrungsmittels (201) eingerichtet ist. 45
2. Ofen nach Anspruch 1, umfassend eine Vielzahl der Tragmittel (103), die zum Tragen eines Einlegebodens (105) auf unterschiedlichen Höhen in dem erwärmten Hohlraum (102) eingerichtet sind, und weiter umfassend eine entsprechende Vielzahl der Gewichtssensoren (104). 50
3. Ofen nach Anspruch 2, wobei die Gewichtssensoren (104), die auf jeder Höhe in dem erwärmten Hohlraum (102) angeordnet sind, eine Vielzahl von Lastzellen (104) umfassen, vorzugsweise vier davon, die zum Erfassen des Gewichts eines auf dem Einlegeboden (105) positionierten Nahrungsmittels eingerichtet sind. 55
4. Ofen nach einem der Ansprüche 1 bis 3, weiter zugeordnet zu Gewichtsverarbeitern (401), die mit einem Speicher (402, 502) wirkverbunden sind, der Referenzgewichtsinformationen speichert, und auch wirkverbunden sind mit dem mindestens einen Gewichtssensor (104).
5. Ofen nach Anspruch 4, wobei die Gewichtsverarbeitern (401) dafür angepasst sind, Angaben (503) über die Zubereitung des Nahrungsmittels (201) durch Vergleichen der Informationen über das Gewicht des Nahrungsmittels mit Referenzgewichtsinformationen bereitzustellen.
6. Ofen nach Anspruch 4 oder 5, wobei die Gewichtsverarbeitern (401) weiter dafür angepasst sind, Informationen (503) über das Gewicht des Nahrungsmittels (201) bereitzustellen, verrechnet um das Taragewicht des Einlegebodens (105).
7. Ofen nach einem der Ansprüche 1 bis 6, wobei das dreidimensionale Abtastsystem (106) mindestens einen Bildsensor umfasst, der in dem erwärmten Hohlraum (102) positioniert ist und dafür angepasst ist, Bilder des Nahrungsmittels (201) zu beschaffen,

und weiter mindestens eine Lichtquelle umfasst, die in dem erwärmten Hohlraum (102) positioniert ist und dafür angepasst ist, das Nahrungsmittel (201) zu beleuchten.

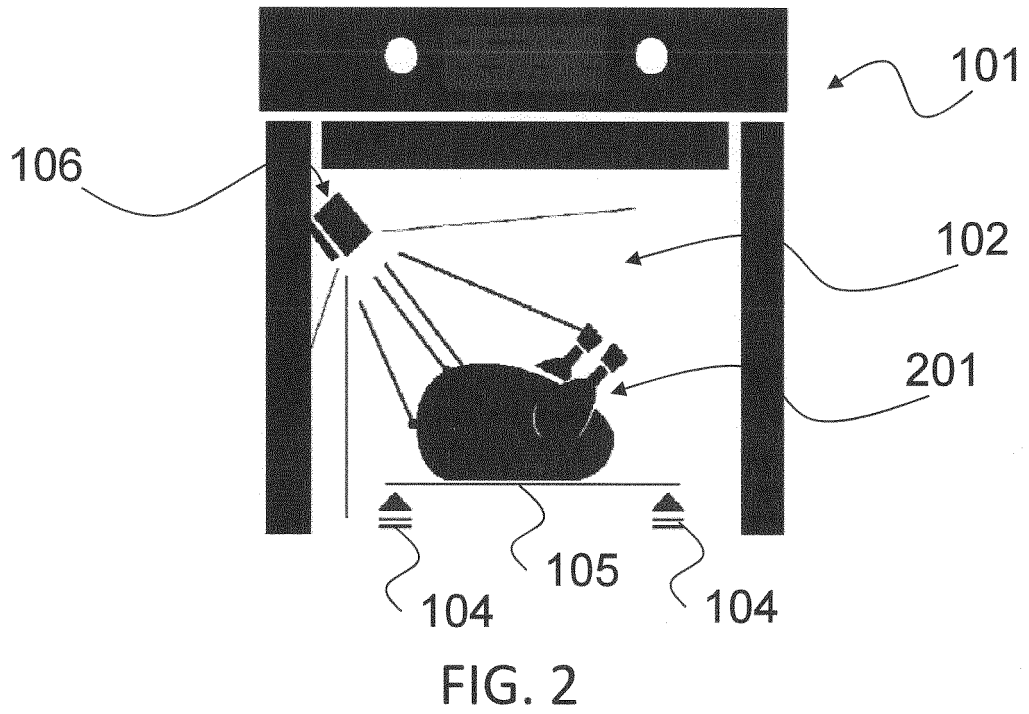
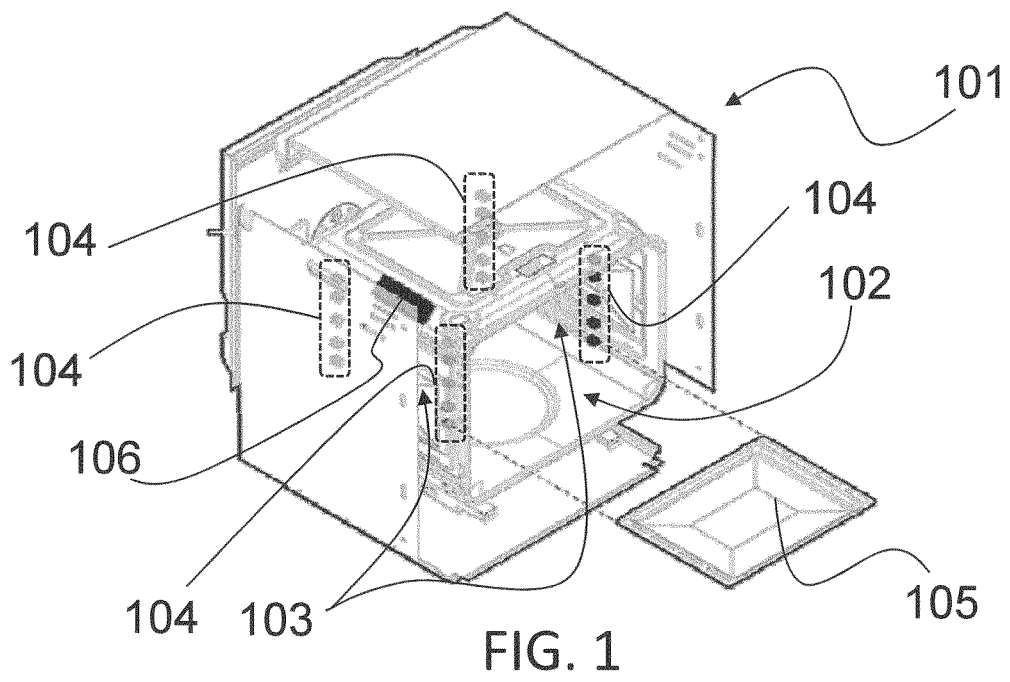
8. Ofen nach Anspruch 7, weiter zugeordnet zu dreidimensionalen Abtastungsverarbeitungsmitteln (401), die mit einem Speicher (402, 502) wirkverbunden sind, der dreidimensionale Referenzabtastungsinformationen speichert, und auch wirkverbunden sind mit dem dreidimensionalen Abtastsystem (106), wobei die dreidimensionalen Abtastungsverarbeitungsmittel dafür angepasst sind, die Typologie des Nahrungsmittels (201) durch Vergleichen der Informationen über das Volumen und/oder die Form des Nahrungsmittels (201) mit den dreidimensionalen Referenzabtastungsinformationen zu bestimmen.
9. Ofen nach einem der Ansprüche 1 bis 8, weiter umfassend Übertragungsmittel (601), die zum Senden von Informationen über das Nahrungsmittel (201) an ein externes Gerät (602) eingerichtet sind.

Revendications

1. Four (101) comprenant une cavité chauffée (102) pour cuire un aliment (201), un moyen de support (103) positionné dans ladite cavité chauffée (102) et configuré pour supporter une étagère (105) dans ladite cavité chauffée (102), ledit moyen de support (103) comprenant au moins un capteur de poids (104) configuré pour détecter le poids d'un aliment (201) positionné sur ladite étagère (105), ledit four étant **caractérisé en ce qu'il** comprend en outre un système de balayage tridimensionnel (106) configuré pour acquérir des informations concernant le volume d'un aliment (201) positionné dans ladite cavité chauffée (102).
2. Four selon la revendication 1, comprenant une pluralité desdits moyens de support (103) configurés pour supporter une étagère (105) à différentes hauteurs dans ladite cavité chauffée (102), et comprenant en outre une pluralité respective desdits capteurs de poids (104).
3. Four selon la revendication 2, dans lequel lesdits capteurs de poids (104) agencés à chaque hauteur dans ladite cavité chauffée (102) comprennent une pluralité de cellules dynamométriques (104), de préférence quatre d'entre elles, configurées pour détecter le poids d'un aliment positionné sur ladite étagère (105).
4. Four selon l'une quelconque des revendications 1 à 3, associé en outre à des moyens de traitement du poids (401) connectés de manière opérationnelle à

une mémoire (402, 502) stockant des informations de poids de référence, et également connectés de manière opérationnelle audit au moins un capteur de poids (104).

5. Four selon la revendication 4, dans lequel lesdits moyens de traitement de poids (401) sont adaptés pour fournir des indications (503) concernant la cuisson dudit aliment (201) en comparant lesdites informations concernant le poids dudit aliment auxdites informations de poids de référence.
6. Four selon la revendication 4 ou 5, dans lequel lesdits moyens de traitement de poids (401) sont en outre adaptés pour fournir des informations (503) concernant le poids dudit aliment (201), la tare de ladite étagère (105) étant déduite.
7. Four selon l'une quelconque des revendications 1 à 6, dans lequel ledit système de balayage tridimensionnel (106) comprend au moins un capteur d'image positionné dans ladite cavité chauffée (102) et adapté pour acquérir des images dudit aliment (201), et comprend en outre au moins une source lumineuse positionnée dans ladite cavité chauffée (102) et adaptée pour éclairer ledit aliment (201).
8. Four selon la revendication 7, associé en outre à des moyens de traitement à balayage tridimensionnel (401) connectés de manière opérationnelle à une mémoire (402, 502) stockant des informations de balayage tridimensionnel de référence, et également connectés de manière opérationnelle audit système de balayage tridimensionnel (106), dans lequel lesdits moyens de traitement de balayage tridimensionnel sont adaptés pour déterminer la typologie dudit aliment (201) en comparant lesdites informations concernant le volume et/ou la forme dudit aliment (201) auxdites informations de balayage tridimensionnel de référence.
9. Four selon l'une quelconque des revendications 1 à 8, comprenant en outre des moyens de transmission (601) configurés pour envoyer des informations concernant ledit aliment (201) à un dispositif externe (602).



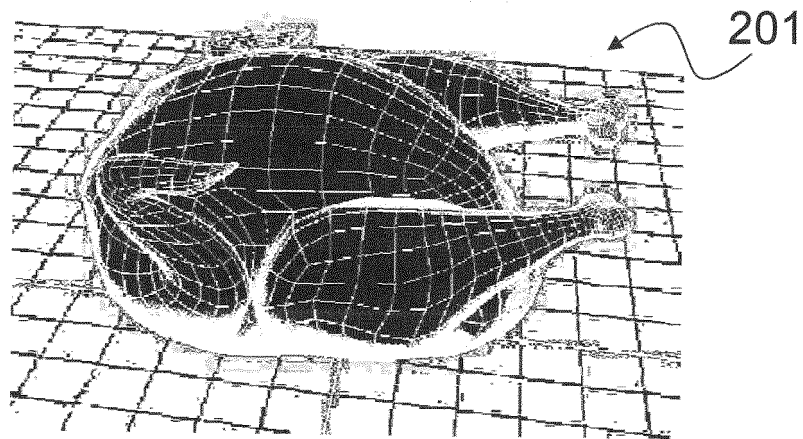


FIG. 3

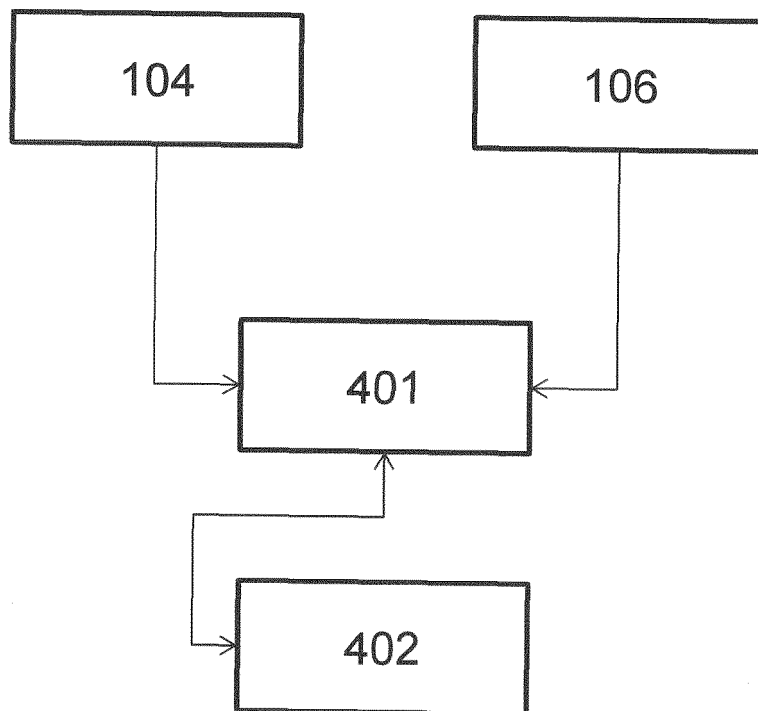


FIG. 4

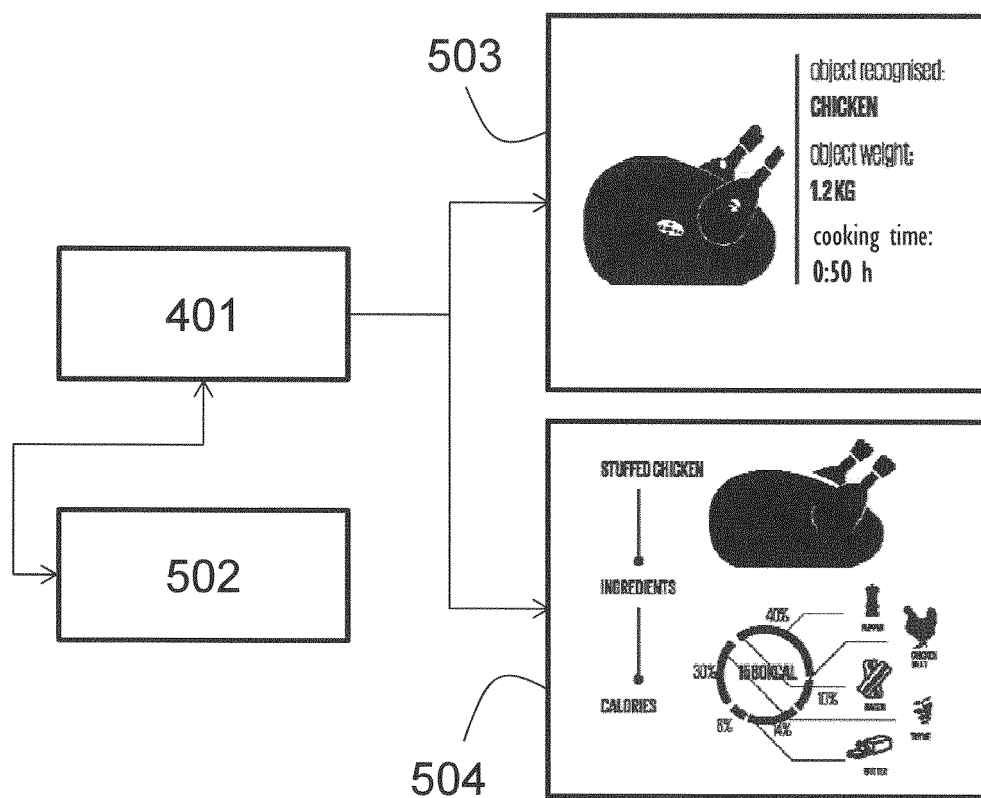


FIG. 5

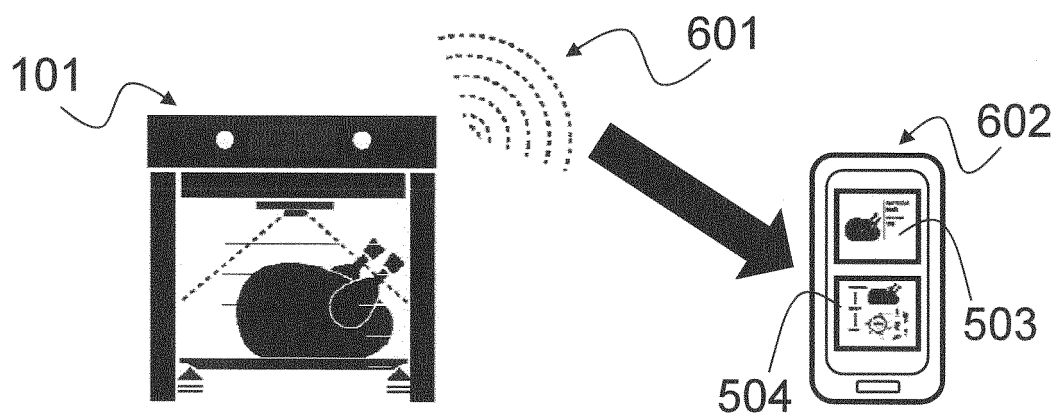


FIG. 6

REFERENCES CITED IN THE DESCRIPTION

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