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(54) **JOINT LOAD REDUCING FOOTWEAR**

(57) Footwear including a flexible sole having a series of flexure zones positioned to correspond to primary joint axes of the human foot approximating the characteristics of a bare foot in motion.

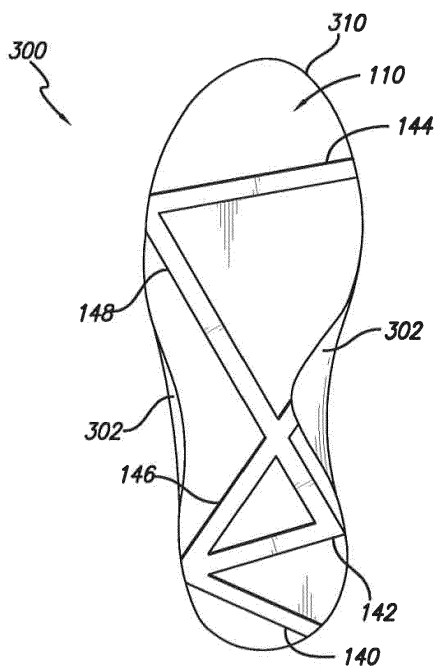


FIG. 5

Description

[0001] This application claims priority to U.S. provisional patent application Serial No. 60/827,168 filed September 27, 2006, herein incorporated by reference.

[0002] The U.S. Government has a paid-up license in this invention and the right in limited circumstances to require the patent owner to license others on reasonable terms as provided for by the terms of Grant No. 1P50 AR048941 awarded by the National Institutes of Health, Department of Health and Human Services.

BACKGROUND

[0003] The present disclosure relates to footwear that results in reduced joint loading compared to common walking shoes currently available. In particular, the present disclosure relates to footwear having a flexible sole with a series of flexure zones positioned to correspond to primary joint axes. The footwear of the present disclosure thus approximates the characteristics of a bare foot in motion.

[0004] Osteoarthritis (OA) of the lower extremity in humans is related to aberrant biomechanical forces. Dynamic joint loading is an important factor in the pathophysiology of OA of the knee. The prevalence and progression of knee OA are reported to be associated with high dynamic loading. One standard parameter assessed as a marker of dynamic knee loading is the external knee adduction moment, a varus torque on the knee that reflects the magnitude of medial compartment joint loading. This moment is considered to be important because nearly seventy percent of knee OA affects the medial tibiofemoral compartment of the knee. The peak external knee adduction moment has been reported to correlate both with the severity and with the progression of knee OA. Consequently, strategies that effectively reduce loads on the knee during gait would be useful.

[0005] Biomechanical interventions aimed at reducing medial compartment loading, such as lateral wedge shoe orthotics have been investigated as therapeutic options. Insertion of lateral wedge orthotics into regular shoes can induce significant decreases in knee moments by up to 5% to 7%, in subjects with medial compartment knee OA. Furthermore, since the lower extremity joints are interrelated, alterations of mechanics at the foot, may not only affect knee loads but may have consequences at the other lower extremity joints.

[0006] Loading at the knees may be affected by altering the ground reaction force. The ground reaction force is the upward force exerted on a human body from the ground in opposition to the force of gravity. It is equal and opposite to the force the human body exerts through the foot on the ground. Because ground reaction forces are transmitted through the feet, such forces are influenced by footwear.

[0007] Prior studies of the effects of footwear on joint loading have been restricted to control subjects without OA, and have demonstrated that even moderate-heeled shoes increase peak knee torques. In addition, one study suggested that common walking shoes may result in increased knee loads in normal individuals, but these effects were attributed to differences in walking speeds while wearing shoes. One study evaluated hip loads in a patient who had an instrumented prosthesis inserted at the time of joint replacement for hip OA. The instrumented prosthesis included a force transducer for obtaining force measurements. By obtaining direct force measurements from the force transducer of the prosthesis, the investigators were able to demonstrate that there were no differences in hip loads among nearly 15 different types of shoes, but the hip loads were lower when the subject was barefoot compared to any of the footwear.

[0008] Walking barefoot significantly decreases the peak external knee adduction moment compared to walking with common walking shoes. An 11.9% reduction was noted in the external knee adduction moment during barefoot walking. Reduction in loads at the hip were also observed. Stride, cadence, and range of motion at the lower extremity joints also changed significantly but these changes could not explain the reduction in the peak joint loads.

[0009] Common shoes detrimentally increase loads on the lower extremity joints. Therefore, it is desirable to mitigate factors responsible for the differences in loads between footwear and barefoot walking as applied to common shoes and walking practices to reduce prevalence and progression of OA.

SUMMARY

[0010] The present disclosure relates to footwear that simulates the motions, force applications and proprioceptive feedback of the natural foot for the express purpose of reducing the moments of force across lower extremity joint segments. The footwear allows for changing centers of rotations around the mobile joint axis in each of the lower extremity joints and reduces the effect that the footwear has on influencing these forces compared to common walking shoes.

[0011] The present disclosure relates to footwear having a sole that incorporates the essential unloading characteristics of barefoot walking. Barefoot walking reduces knee loading in normal healthy individuals as well as in individuals with OA. Therefore it is desirable to develop footwear that approximates the characteristics of barefoot walking, and thus reduces joint loads, compared to common walking shoes.

[0012] Shoes have three primary components, the upper, the outsole and the midsole. The upper is comprised of

materials of various flexibility that wrap around the foot superiorly. The upper includes the vamp, covering the instep and toes, heel counter around the back of the heel, toe box, tongue and foxing (extra-pieces). The midsole includes materials of various thickness and stiffness that connect the upper and the outsole. The outsole is connected to the midsole and is the most inferior portion of the shoe that comes in contact with the ground and is therefore made of various materials designed for resiliency.

[0013] The disclosed footwear allows for point application of the ground reactive force vector on the various footwear components, thereby reducing the ability of the footwear to transfer these external forces from one joint segment to the next along the leg (i.e. from foot to knee to hip). This is accomplished by having a thin flexible sole with flexure zones positioned therein to match the natural motion lines of the human foot, and thereby during walking, orienting the force vectors in the lower extremities in the same direction as they are in barefoot walking. The physiological effect includes alterations in the forces, pressures, and positions, of the lower extremity during the gait cycle and therefore produces proprioceptive and neuromuscular changes within the wearer.

[0014] In an embodiment of the disclosed footwear, the outsole and midsole are modified compared to existing shoes in that the thickness and properties of the sole material allow for motion around the primary joint axis of the lower extremity proximal to the weight bearing surface. In several prototypes this was achieved simply by removing some of the outsole and midsole material, forming grooves corresponding to the natural motion lines of the human foot. However, any modification that will allow for the remaining segments of the outsole and midsole of the footwear to redirect, or be allowed to move in response to, application of the force vector can be utilized. Also, a rounded heel is provided to contour the natural human heel.

BRIEF DESCRIPTION OF THE DRAWINGS

[0015] The present disclosure will be described hereafter with reference to the attached drawings which are given as non-limiting examples only, in which:

FIG. 1 is a plan view representation of a foot and a sole having flexure zones corresponding to primary joint axes of the human foot to approximate the characteristics of a bare foot;

FIG. 2a and 2b show illustrations comparing the ground reaction force (GRF) vectors for a leg in varus alignment with a rigid shoe, as shown in FIG. 2a, and a leg with a bare foot, as shown in FIG. 2b;

FIG. 3a and 3b show illustrations comparing the ground reaction force (GRF) vectors for a leg in varus alignment with a shoe of the present disclosure, as shown in FIG. 3a, and a leg with a bare foot, as shown in FIG. 3b;

FIG. 4 shows a shoe having a flexible sole of the present disclosure; and

FIG. 5 is a bottom view of the shoe of FIG. 4 showing the sole with a groove pattern corresponding to primary joint axes of the human foot to approximate the characteristics of a bare foot.

DETAILED DESCRIPTION

[0016] While the present disclosure may be susceptible to embodiment in different forms, there is shown in the drawings, and herein will be described in detail, embodiments with the understanding that the present description is to be considered an exemplification of the principles of the disclosure and is not intended to be exhaustive or to limit the disclosure to the details of construction and the arrangements of components set forth in the following description or illustrated in the drawings.

[0017] The present disclosure relates to footwear having a flexible sole 110 with a number of flexure zones, or lines of reduced rigidity, that allow the sole 110 to flex more like the natural human foot during barefoot walking. These flexure zones are configured to be aligned with the primary joint axes of the human foot resulting in a sole 110 that flexes similar to a natural foot.

[0018] In an embodiment of the present disclosure, the outsole and midsole have grooves configured to approximate the properties of the primary joint axis of the lower extremity proximal to the weight bearing surface. In several prototypes this was achieved simply by removing some of the outsole and midsole material. However, any construction that allows for the segments of the outsole and midsole to move away from the direction of the application of the force vector can be utilized. For example, it is envisioned that the sole 110 of the present disclosure may be constructed from an integral piece of molded material such as rubber, ethylene vinyl acetate (EVA), polyurethane, neoprene, or other suitable material. A mold may have incorporated grooves to produce the sole, or the grooves may be cut into the material after forming. Another example may include a sole of composite material, wherein the flexure zones are formed from a less rigid material than the surrounding outsole.

[0019] The locations of the flexure zones were determined by starting with the anatomical locations of the proximal joint axis and widening the area to allow for the dynamic changes in the rotational centers of the joint axis during gait. Referring to FIG. 1, a first reference line called the base of forefoot 122 is determined by measuring and establishing

the widest part of the weight bearing surface of the forefoot from the plantar surface of the sole. The midpoint 124 of the base of forefoot 122 is determined by dividing the width of the base of forefoot 122 in half.

[0020] Similarly, a second reference line called the base of heel 126 is determined by measuring and establishing the widest part of the hindfoot. The midpoint 128 of the base of heel 126 is determined by dividing the width of the base of heel in half.

[0021] A third reference line called the longitudinal axis of the foot 130 is determined by drawing a line through the midpoints 124, 128 of the base of forefoot 122 and base of heel 126, respectively.

[0022] A first flexure zone 140 is positioned within the sole 110 along a line from an apex A at the lateral edge of the base of heel 126, and oriented at an angle α , which is 30 degrees posterior to the base of heel. The configuration for the first flexure zone 140 is determined by establishing the ground reaction force vector position at heel strike, the instant that the heel strikes the ground. The subtalar joint is 16 degrees externally rotated, the leg is approximately 12 degrees externally rotated and, depending on the walking speed, the lower leg strikes the ground in a 2-5 degree varus position. In order for the sole of a shoe not to produce a larger lever arm on the subtalar joint axis 132, a line perpendicular to the subtalar joint axis 134 was established and the added effect of the varus position of the subject's leg at heel strike combined with an externally rotated leg produces a measured line approximately 30 degrees posteriorly rotated to the heel coronal (frontal) plane bisection of the heel (base of heel 126).

[0023] Using the lateral edge of the base of heel 126 as an apex A, a second flexure zone 142 is positioned within the sole 110 at an angle β , which is approximately 15 degrees anterior to the base of heel 126. First flexure zone 140 and second flexure zone 142 are thus oriented to form an angle γ of approximately 45 degrees. Second flexure zone 142 is positioned collinear with a line representing the transverse plane projection of the ankle joint axis onto the plantar sole.

[0024] From an apex B at the medial base of the forefoot 122, a third flexure zone 144 is positioned within the sole 110 at an angle δ which is approximately 10 degrees anterior to the base of the forefoot 122. Third flexure zone 144 is thus positioned collinear with a line representing the axis of the first metatarsal phalangeal joint during propulsion in an externally rotated abducted foot.

[0025] A fourth flexure zone 146 is positioned within the sole 110 from apex A extending from the lateral edge of the base of the heel 126 to apex B at the medial edge of the base of the forefoot 122. Fourth flexure zone 146 is thus positioned collinear with a line representing a transverse plane projection of the oblique axis of the midtarsal joint. Fourth flexure zone 146 and first flexure zone 140 are oriented to form an angle ϵ which is approximately 90 degrees.

[0026] A fifth flexure zone 148 is positioned within the sole 110 extending from apex B' at the lateral edge of the base of the forefoot 122 to apex C at the medial edge of the second flexure zone 142. Fifth flexure zone 148 is positioned collinear with a line representing the transverse plane projection of the first ray (medial column) and will intersect the longitudinal axis 130 of the foot at approximately 45 degrees.

[0027] The human foot has numerous proprioceptive receptors for detecting stimuli such as motion and/or position and responding to the stimuli. An embodiment of the sole 110 of the present disclosure is made of either ethylene vinyl acetate (EVA) or polyurethane and is approximately 0.25 inches thick. While providing flexion corresponding to the natural motion lines of the human foot, the sole 110 must be of sufficient thickness to provide protection to the foot over numerous encountered walking surfaces. However, the sole 110 must also be thin enough to provide adequate proprioceptive input to the foot. In addition to a flat bottom, the sole of the present disclosure has a rounded heel without any flaring to contour the natural heel.

[0028] FIG. 2a shows an illustration of a human leg 260 in varus alignment with a common walking shoe S known in the art that restricts motion with medial reinforced components. The ground reaction force (GRF) vector is at an angle θ from the leg and located at a distance d from the center of rotation of the knee 262. The proximal end of the GRF vector is at a distance Δ from the center of rotation 262, resulting in a knee adduction moment 264. This also applies a greater moment around the hip joint axis (not shown), and to a lesser degree at the ankle/subtalar joint axis 266. FIG. 2b shows an illustration of a human leg 260 without a shoe in a barefoot configuration. The offset distance Δ is smaller than in FIG. 2a. The result at the knee is larger moments with rigid shoe S that would cause larger compressive loads at the medial knee.

[0029] FIG. 3a shows an illustration of a human leg 260 in varus alignment with an embodiment of a shoe 300 of the present disclosure. The ground reaction force (GRF) vector is at an angle θ from the leg and located at a distance d from the center of rotation of the knee 262. The proximal end of the GRF vector is at a distance Δ from the center of rotation 262, resulting in a knee adduction moment 264. FIG. 3b shows an illustration of a human leg 260 without a shoe in a barefoot configuration, similar to FIG. 2b discussed previously. The barefoot configuration, without restriction, allows the foot segments to move in response to the ground reactive force thereby allowing motion and minimizing knee adduction moment 264. As can be seen, the shoe 300 of the present disclosure approximates the location of the ground reaction force (GRF) vector of the natural bare foot.

[0030] Referring to FIGS. 4 and 5, an embodiment of the present disclosure includes a shoe 300 having a sole 110 as described above. As shown in FIG. 4, the shoe 300 has a lightweight flexible upper 302 configured to surround a

human foot. The upper 302 may be constructed of any material that can provide flexibility without interfering with the natural movement of the foot, such as nylon, cotton fabric, canvas, or leather. The upper 302 includes an opening 304 configured for insertion of a human foot. The opening 304 may be secured about the foot by fasteners 306 such as laces, hook-and-loop fasteners such as VELCRO®, buttons, snaps, or other fastening means known in the art.

[0031] Sole 110 is attached to upper 302 and may include an outer sole 310 a mid-sole (not shown), and an inner sole (not shown). Outer sole 310 may include a plurality of traction members such as knobs or treads (not shown) to reduce slipping between the outsole 310 and a walking surface such as a floor or ground. Referring to FIG. 5, the sole 110 has a plurality of flexure zone 140, 142, 144, 146, and 148 that allow the sole 110 to flex more like the natural foot in barefoot walking.

EXAMPLES

[0032] As examples, data was collected during separate studies. Example 1, compares joint loading, in particular the external knee adduction moment, in subjects with symptomatic OA of the knee while walking with the subjects' own walking shoes and walking barefoot. Example 2, compares joint loading in healthy subjects and subjects having knee OA while walking in the subjects' own walking shoes and while walking in a shoe having a sole of the present disclosure. The third study, described in Example 3 below, compared joint loading in subjects having knee OA while walking in footwear of the present disclosure, while walking barefoot, and while wearing common walking shoes.

[0033] **Example 1: Walking Shoes vs. Barefoot Walking.** In the first analysis, subjects were participants in an ongoing double-blind randomized controlled trial of the efficacy of lateral wedge orthotics for the treatment of knee OA [NLM Identifier: NCT00078453, at www.clinicaltrials.gov]. Inclusion criteria included the presence of *symptomatic* OA of the knee, which was defined by the American College of Rheumatology's Clinical Criteria for Classification and Reporting of OA of the knee and by the presence of at least 20 mm of pain (on a 100 mm visual analog scale) while walking (corresponding to question 1 of the visual analog format of the knee-directed Western Ontario and McMaster Universities Arthritis Index (WOMAC). Although all subjects had bilateral knee OA, the most symptomatic knee on the day of the initial study visit was considered the "index" knee. Subjects had OA of the index knee documented by weight-bearing full extension anterior posterior knee radiographs, of grade 2 or 3 as defined by the modified Kellgren-Lawrence (KL) grading scale. The contralateral knee also had radiographic OA of KL grade 1 to 3 in severity. Subjects had medial compartment OA defined as medial joint space narrowing (JSN) of greater than or equal to 1 as well as medial JSN greater than lateral JSN by greater than or equal to 1 grade (according to the Atlas of Altman et al., Diagnostic and Therapeutic Criteria Committee of the American Rheumatism Association, *Arthritis Rheum* 1986; 29(8): 1039-1049).

[0034] Major exclusion criteria were: flexion contracture of greater than 15 degrees at either knee; clinical OA of either ankle or the hip; significant intrinsic foot disease per a podiatric exam; and a body mass index (BMI) greater than 35.

[0035] All subjects underwent baseline gait analysis (before the use of orthotics). Motion during gait was measured with a multi-camera optoelectronic system (Qualysis AB Gothenburg, Sweden) and force with a multi-component force plate (Bertec, Columbus, OH)(10). The walking surface consisted of 2-inch thick wooden pressboard covered with linoleum. Reflective markers were placed on the lower extremity including the iliac crest, greater trochanter, lateral joint line of the knee, lateral malleolus, calcaneus, and base of the fifth metatarsal, and joint centers were estimated on the basis of measurements of each subject. Subjects were instructed to walk at a range of speeds from slow to fast and data from 6 stride lengths on each side were collected.

[0036] These position and force data were then utilized to assess range of motion at the joints and to calculate three-dimensional external moments using inverse dynamics. The external moments that act on a joint during gait are, according to Newton's second law of motion, equal and opposite to the net internal moments produced primarily by the muscles, soft tissues, and joint contact forces. The external moments are normalized to the subjects body weight (BW) multiplied by height (Ht) times 100 (%BW*Ht) to allow for comparisons between subjects.

[0037] All subjects were asked to wear their own comfortable "walking shoes." Subjects had gait analyses performed wearing shoes. The shoes were then removed. Subjects walked for several minutes on the gait analysis platform while barefoot. After the subjects felt comfortable, gait analyses were repeated barefoot. Subjects were instructed to walk at their "normal" walking speed for the barefoot analyses. "With shoe" and "barefoot" runs were chosen for comparison from the "index" knee limb and similarly from the "contralateral" limb. "Normal" speed barefoot runs were matched for speed with "normal" speed footwear runs for analysis.

[0038] Statistical analyses were performed using SPSS software. Paired samples t-test was used to compare moments and gait parameters between footwear and barefoot walking. Relationships between differences in gait parameters and differences in joint moments during footwear and barefoot walking were evaluated using linear regression. A significance level of <0.05 was established *a priori*.

[0039] Seventy-five subjects underwent gait analyses while walking barefoot and with shoes. Of these, 40 subjects also had gait data (with and without shoes) available for the contralateral knee.

[0040] Walking speed did not change between "with shoe" and "barefoot" trials. Increased speed can increase loads

during gait at the joints. Stride length was significantly decreased during barefoot walking. Meanwhile, cadence significantly increased, suggesting that although subjects were taking shorter steps, they were taking more steps per unit time. Range of motion at the major lower extremity joints as well as the toe-out angle were significantly reduced during barefoot walking.

[0041] Barefoot walking significantly decreased dynamic loads at the knees. There was an 11.9% reduction in the peak external knee adduction moment while walking barefoot compared to with shoes ($p<0.001$). There was also a significant decrease in the peak knee extension moment ($p=0.006$), while the peak knee flexion moment did not significantly change ($p=0.435$) between "with shoe" and "barefoot" trials.

[0042] Similar reductions in dynamic loads were observed at the hips during barefoot walking. The peak hip adduction moment decreased by 4.3% ($p=0.001$). The peak hip internal and external rotation moments decreased by 11.2% and 10.2% respectively ($p=0.001$).

[0043] Evaluation of gait parameters and peak moments among the contralateral knees yielded comparable results. There were notable reductions in stride length, increase in cadence, and reductions in hip, knee and ankle range of motion during barefoot walking ($p<0.05$). There were also significant reductions in peak external knee adduction moment, knee extension, hip internal rotation, and hip external rotation moments during barefoot walking ($p<0.05$). The only differences in the results at the contralateral knee were that the toe-out angle and hip AddM did not significantly change.

[0044] To assess whether the reduced loading at the knees and hips while barefoot could be explained by gait alterations alone, step-wise linear regression was used to evaluate the influence of the change in cadence, stride, toe-out angle, and hip, knee and ankle range of motion (independent variables) on the reduction in peak joint moments during barefoot walking (dependent variables). There were no significant relationships noted among any of these variables singly or collectively. This was further confirmed using backwards linear regression, in which all the independent variables were eliminated as having a significant influence on the change in peak moments. Therefore, although the character of the gait was somewhat altered, none of these measurable aspects of gait could explain the significant reductions in peak joint moments during "barefoot" trials.

[0045] Excessive loading of the lower extremities is associated with the onset and progression of knee OA. However, there has not been previous attention to the effects that common shoes may play in potentiating these aberrant loads. Differences in gait and in joint loads that occur when patients with knee OA walk barefoot compared to when they walk with shoes are disclosed. Such patients undergo a significant reduction in their joint loads at both the knees and the hips while walking barefoot compared to when walking with their normal shoes. Moreover, whereas significant changes in several gait parameters were observed during barefoot walking, including changes in stride, cadence, joint range of motion and toe-out angle, these changes in gait could not explain the significant reduction in loads at the joints. The design of common footwear may intrinsically predispose such patients to excessive loadings of their lower extremities.

[0046] Walking speed has been shown to affect loads at joints. Subjects disclosed herein had equal speeds during both "with shoe" and "barefoot" trials. There may be several differences between "with shoe" and "barefoot" walking that could account for the noted differences. For example, heels on shoes can increase peak knee torques. Most common walking shoes have a partial lift at the heel; thus, the complete lack of a "heel" during barefoot walking may be effective at reducing peak torques at the knee. Another factor is the "stiffness" imposed by the sole of most shoes. Another explanation for the biomechanical advantages of barefoot walking may be attributed to increased proprioceptive input from skin contact with the ground compared to an insulated foot contacting the ground.

[0047] Example 2: Footwear or the Present Disclosure vs. Common Walking Shoes. A gait analysis was performed on fourteen test subjects having knee OA. The analysis consisted of measuring the loading of moments or torques on the knee joints, and in particular, the external knee adduction moment. A higher external knee adduction moment correlates with greater OA severity and greater progression of OA over time. In general, higher moments represent higher loads. Subjects were evaluated for gait while wearing their self-selected "usual" walking shoes and then while wearing footwear of the present disclosure. In each case, subjects were permitted to acclimate to the new condition prior to gait testing. Subjects walked at their normal walking speed, and comparisons were performed on runs matched for speed. The peak external knee adduction moment (%body weight * height) was calculated at the knee and used as the primary endpoint. Paired t-tests were used to compare differences in the moments during the different "footwear" conditions. There were no significant differences in speed during the walking conditions. Overall, a significant reduction in the peak external knee adduction moment was noted while walking with footwear of the present disclosure compared to "usual" walking shoes (2.6 ± 0.6 vs. 2.9 ± 0.6 , $p=0.006$). These results correspond to a 10% reduction in the peak external knee adduction moment with the "unloading" shoe. An analysis of the data, summarized below in Tables 1-3, indicates a 10 percent decrease in the knee loading while walking in a shoe having a sole in accordance with the present disclosure over the test subjects' ordinary walking shoes. Also observed was a 7 percent reduction in hip loading.

[0048] Further study confirmed that the footwear of the present disclosure reduced dynamic knee loads during gait. Thirty-one subjects with radiographic and symptomatic knee OA underwent gait analyses using an optoelectronic camera system and multi-component force plate. Subjects were evaluated for gait while 1) wearing footwear of the present disclosure, and 2) wearing their self-chosen walking shoes. Subjects walked at their normal walking speed, and com-

parisons were performed on runs matched for speed. The primary endpoints for the study were gait parameters that reflected the extent of medial compartment knee loading and included the peak external knee adduction moment (PAddM) and the adduction angular impulse (AddImp). The PAddM is the external adduction moment of greatest magnitude during the stance phase of the gait cycle. The AddImp is the integral of the knee adduction moment over time and has recently been shown to be more sensitive than the PAddM in predicting the radiographic severity of medial compartment knee OA. There were no significant differences in speed during the walking conditions (1.16 ± 0.23 vs. 1.15 ± 0.25 m/sec, $p=0.842$). There was an 8% reduction in the PAddM (2.73 ± 0.76 vs. 2.51 ± 0.80 %BW*ht, $p<0.001$) and a 7% reduction in the AddImp (0.96 ± 0.45 vs. 0.89 ± 0.45 %BW*ht, $p<0.016$) with the footwear of the present disclosure compared to subjects' self-chosen walking shoes.

[0049] Yet a further analysis concludes that footwear of the present disclosure reduces joint loading in healthy individuals without OA. Twenty-six normal subjects underwent gait analyses of their dominant limb using an optoelectronic camera system and a multi-component force plate. Subjects were evaluated for gait while wearing their self-selected "usual" walking shoes. In addition, all of the subjects underwent gait analyses while barefoot and 19 underwent analyses wearing footwear of the present disclosure. In each case, subjects were permitted to acclimate to the new condition prior to gait testing. Subjects walked at their normal walking speed, and comparisons were performed on runs matched for speed. The peak external knee adduction moment (%body weight * height) was calculated at the knee and used as the primary endpoint. Paired t-tests were used to compare differences in the moment during the different "footwear" conditions. There were no significant differences in speed during the three walking conditions. Overall, a significant reduction in the peak external knee adduction moment was noted during barefoot walking (2.0 ± 0.7 vs. 2.3 ± 0.8 , $p=0.023$) and while walking with footwear of the present disclosure (2.0 ± 0.9 vs. 2.3 ± 0.8 , $p=0.009$) compared to "usual" walking shoes. These results corresponded to a 13% reduction the peak external knee adduction moment during the barefoot and load reducing footwear conditions.

[0050] Example 3: Footwear of the Present Disclosure vs. Common Walking Shoes vs. Barefoot Walking.

Nineteen subjects were studied with radiographic and symptomatic knee OA underwent gait analyses using an optoelectronic camera system and multi-component force plate. Subjects were evaluated for gait while 1) wearing footwear of the present disclosure, 2) wearing a "control" shoe, a commonly prescribed walking shoe, engineered to provide foot stability and comfort and 3) walking barefoot. In each case, subjects were permitted to acclimate to the new condition prior to gait testing. Subjects walked at their normal walking speed, and comparisons were performed on runs matched for speed. The peak external knee adduction moment (%body weight * height) was calculated at the knee and used as the primary endpoint. There were no significant differences in speed during the walking conditions. Overall, a significant reduction in the peak external knee adduction moment was noted while walking with footwear of the present disclosure compared to the "control" walking shoes (2.6 ± 0.7 vs. 3.1 ± 0.7 , $p<0.001$). These results correspond to a 16% reduction in the peak external knee adduction moment. There was no significant difference in peak knee adduction moment between the footwear of the present disclosure and barefoot walking (2.6 ± 0.7 vs. 2.7 ± 0.7 , $p=0.386$).

[0051] Therefore, it is advantageous to incorporate the teachings of the present disclosure into footwear to effectively reduce dynamic knee loads during gait.

Table 1: Paired Samples Statistics

		Mean	N	Std. Deviation	Std. Error Mean
Pair 1	KMYADD	2.90064	14	0.594602	0.158914
	sKMYADD	2.62421	14	0.581111	0.155308
Pair 2	KMYADD	3.88514	14	0.968716	0.258900
	sKMYADD	3.62357	14	0.824524	0.220363
Pair 3	KMYADD	0.60607	14	0.236105	0.063102
	sKMYADD	0.53986	14	0.228314	0.061019

Table 2: Paired Sample Correlations

		N	Correlation	Sig.
Pair 1	KMYADD & sKMYADD	14	0.856	0.000
Pair 2	HMYADD & sHMYADD	14	0.921	0.000
Pair 3	HMZEXT & sHMZEXT	14	0.865	0.000

Table 3: Paired Sample Differences

		Paired Differences					t	df	Sig. (2-tailed)
		Mean	Std. Deviation	Std. Error Mean	95% Confidence Interval of the Difference				
					Lower	Upper			
Pair 1	KMYADD & sKMYADD	0.276429	0.316157	0.084497	0.093885	0.458972	3.271	13	0.006
Pair 2	HMYADD & sHMY ADD	0.261571	0.384422	0.102741	0.039613	0.483530	2.546	13	0.024
Pair 3	HMZEXT & sHMZEXT	0.066214	0.120986	0.032335	-0.003641	0.136070	2.048	13	0.061

[0052] Wherein:

KMYADD is the peak knee adduction moment when subjects walking with their own walking shoes (the variable that has been correlated with knee arthritis- both severity and progression);

sKMYADD is the peak knee adduction moment while wearing footwear of the present disclosure;

HMYADD is the peak hip adduction moment;

sHMYADD is the peak hip adduction moment while wearing footwear of the present disclosure;

HMZEXT is the peak hip external rotation moment; and

sHMZEXT is the peak hip external rotation moment while wearing footwear of the present disclosure.

[0053] Additional data was also collected during the studies for the following parameters:

speed: m/sec

stride: length of step (meters/height)

cadence: steps/minute

kmyadd: peak knee adduction moment (%BW*ht)

hrom: hip range of motion (degrees)

arom: ankle range of motion (degrees)

krom: knee range of motion (degrees)

hmxflex: peak hip flexion moment (%BW*ht)

hmtext: peak hip extension moment (%BW*ht)

kmxflex: peak knee flexion moment (%BW*ht)

kmxext: peak knee extension moment (%BW*ht)

hmyadd: peak hip adduction moment (%BW*ht)

hmyabd: peak hip abduction moment (%BW*ht)

kmyabd: peak knee abduction moment (%BW*ht)

hmzint: peak hip internal rotation moment (%BW*ht)

hmzext: peak hip external rotation moment (%BW*ht)

DISCLOSED ITEMS

[0054]

1. A sole for an article of footwear that simulates the motions, force applications, and proprioceptive feedback of a natural human foot, the foot defining a base of forefoot and a base of heel, the sole therein reducing moments across lower extremity joint segments, the sole comprising:

a first flexure zone positioned within the sole and extending posteriorly from the base of heel;
a second flexure zone positioned within the sole and extending anteriorly from the base of heel;
a third flexure zone positioned within the sole and extending anteriorly from the base of forefoot;
a fourth flexure zone positioned within the sole and extending anteriorly from the base of heel; and
a fifth flexure zone positioned within the sole and extending posteriorly from the base of forefoot.

2. The sole of item 1 wherein the first flexure zone and the base of heel define a first angle of approximately 30 degrees.

3. The sole of item 1 wherein the second flexure zone and the base of heel define a second angle of approximately 15 degrees.

4. The sole of item 1 wherein the third flexure zone and the base of forefoot define a third angle of approximately 10 degrees.

5. The sole of item 1, wherein the fourth flexure zone extends posteriorly from the base of forefoot.

6. The sole of item 1 wherein the fourth flexure zone extends between the base of heel and the base of forefoot.

7. The sole of item 1 wherein the fifth flexure zone extends between the base of forefoot and the second flexure zone.

8. The sole of item 1 further including a plurality of traction members.

9. The sole of item 1 further including a rounded heel portion.

10. A sole for an article of footwear that simulates the motions, force applications, and proprioceptive feedback of the natural human foot, the foot defining a base of forefoot and a base of heel, the sole therein reducing moments across lower extremity joint segments, the sole comprising:

- a first flexure zone positioned within the sole and extending from the lateral edge of the base of heel and oriented at an angle approximately 30 degrees posterior to the base of heel;
- a second flexure zone positioned within the sole and extending from the lateral edge of the base of heel and oriented at an angle approximately 15 degrees anterior to the base of heel;
- a third flexure zone positioned within the sole and extending from the base of forefoot and oriented at an angle approximately 10 degrees anterior to the base of forefoot;
- a fourth flexure zone positioned within the sole and extending from the medial edge of the base of forefoot to the lateral edge of the base of heel; and
- a fifth flexure zone positioned within the sole and extending from the lateral edge of the base of forefoot to the medial edge of the second flexure zone.

11. The sole of item 10 further including a plurality of traction members.

12. The sole of item 10 further including a rounded heel portion.

13. An article of footwear that simulates the motions, force applications, and proprioceptive feedback of the natural human foot, the foot defining a base of forefoot and a base of heel, the article of footwear therein reducing moments across lower extremity joint segments, the article of footwear comprising:

- an upper portion configured to be disposed about a human foot; and
- a sole attached to the upper portion, the sole comprising

- a first flexure zone positioned within the sole and extending posteriorly from the lateral edge of the base of heel;
- a second flexure zone positioned within the sole and extending anteriorly from the lateral edge of the base of heel;
- a third flexure zone positioned within the sole and extending anteriorly from the medial edge of the base of forefoot;
- a fourth flexure zone positioned within the sole and extending anteriorly from the lateral edge of the base of heel; and
- a fifth flexure zone positioned within the sole and extending posteriorly from the lateral edge of the base of forefoot.

14. The article of footwear of item 13 wherein the first flexure zone and the base of heel define a first angle of approximately 30 degrees.

15. The article of footwear of item 13 wherein the second flexure zone and the base of heel define a second angle of approximately 15 degrees.

16. The article of footwear of item 13 wherein the third flexure zone and the base of forefoot define a third angle of approximately 10 degrees.

17. The article of footwear of item 13 wherein the fourth flexure zone extends between the lateral edge of the base of heel and the medial base of forefoot.

18. The article of footwear of item 13 wherein the fifth flexure zone extends between the lateral edge of the base of forefoot and the medial edge of the second flexure zone.

19. The article of footwear of item 13 wherein the sole further includes a plurality of traction members.

20. The article of footwear of item 13 wherein the sole further includes a rounded heel portion.

Claims

1. A sole [110] for an article of footwear that simulates the motions, force applications, and proprioceptive feedback of a natural human foot, the foot defining a base of forefoot [122] and a base of heel [126], the sole therein reducing moments across lower extremity joint segments, the sole [110] comprising:

a first flexure groove [140] positioned within the sole [110] and extending posteriorly from a first apex at a base of the heel [126];
 a second flexure groove [142] positioned within the sole [110] and extending anteriorly from the first apex;
 a third flexure groove [144] positioned within the sole [110] and extending anteriorly from a second apex at a medial base of the forefoot [122];
 a fourth flexure groove [146] positioned within the sole [110] and having a first end beginning at the first apex and a second end terminating at the second apex; and
 a fifth flexure groove [148] positioned within the sole [110] and extending posteriorly from a base of the forefoot [122].

2. A sole [110] for an article of footwear that simulates the motions, force applications, and proprioceptive feedback of a natural human foot, the foot defining a base of forefoot [122] and a base of heel [126], the sole therein reducing moments across lower extremity joint segments, the sole [110] comprising:

a first flexure groove [140] positioned within the sole [110] and extending posteriorly from an apex at a lateral edge of the base of the heel [126];
 a second flexure groove [142] positioned within the sole [110] and extending anteriorly from the apex, the second flexure zone intersecting the first flexure zone at the apex;
 a third flexure groove [144] positioned within the sole [110] and extending anteriorly from the base of forefoot [122];
 a fourth flexure groove [146] positioned within the sole [110] and extending anteriorly from the apex, the fourth flexure zone intersecting the first flexure zone and the second flexure zone at the apex; and
 a fifth flexure groove [148] positioned within the sole [110] and extending posteriorly from a base of the forefoot [122].

3. The sole [110] of claim 2 wherein the first flexure groove [140] and the base of heel [126] define a first angle of approximately 30 degrees.

4. The sole [110] of claim 2 wherein the second flexure groove [142] and the base of heel [126] define a second angle of approximately 15 degrees.

5. The sole [110] of claim 2 wherein the third flexure groove [144] and the base of forefoot [122] define a third angle of approximately 10 degrees.

6. The sole [110] of claim 2, wherein the fourth flexure groove [146] extends posteriorly from the base of forefoot [122].

7. The sole [110] of claim 2, wherein the fourth flexure groove [146] extends between the base of heel and the base of forefoot [122].

8. The sole [110] of claim 2 wherein the fifth flexure groove [148] extends between the base of forefoot [122] and the second flexure groove [142].

9. The sole [110] of claim 2 further including a plurality of traction members.

10. The sole [110] of claim 2 further including a rounded heel portion.

11. The sole [110] of claim 2 further including a first material disposed between one or more of the flexure grooves that is different than a second material disposed between one or more of the flexure grooves.

12. A sole [110] for an article of footwear that simulates the motions, force applications, and proprioceptive feedback of a natural human foot, the foot defining a base of forefoot [122] and a base of heel [126], the sole therein reducing moments across lower extremity joint segments, the sole [110] comprising:

a first flexure groove [140] positioned within the sole [110] and extending from an apex at the lateral edge of the base of heel [126] and oriented at an angle approximately 30 degrees posterior to the base of heel [126];
a second flexure groove [142] positioned within the sole [110] and extending from the apex at the lateral edge of the base of heel [126] and oriented at an angle approximately 15 degrees anterior to the base of heel [126];
a third flexure groove [144] positioned within the sole [110] and extending from the base of forefoot [122] and oriented at an angle approximately 10 degrees anterior to the base of forefoot [122];
a fourth flexure groove [146] positioned within the sole [110] and extending from the medial edge of the base of forefoot [122] to the apex at the lateral edge of the base of heel [126]; and
a fifth flexure groove [148] positioned within the sole [110] and extending from the lateral edge of the base of forefoot [122] to the medial edge of the second flexure groove [142].

13. The sole [110] of claim 12 further including a plurality of traction members.

14. The sole [110] of claim 12 further including a rounded heel portion.

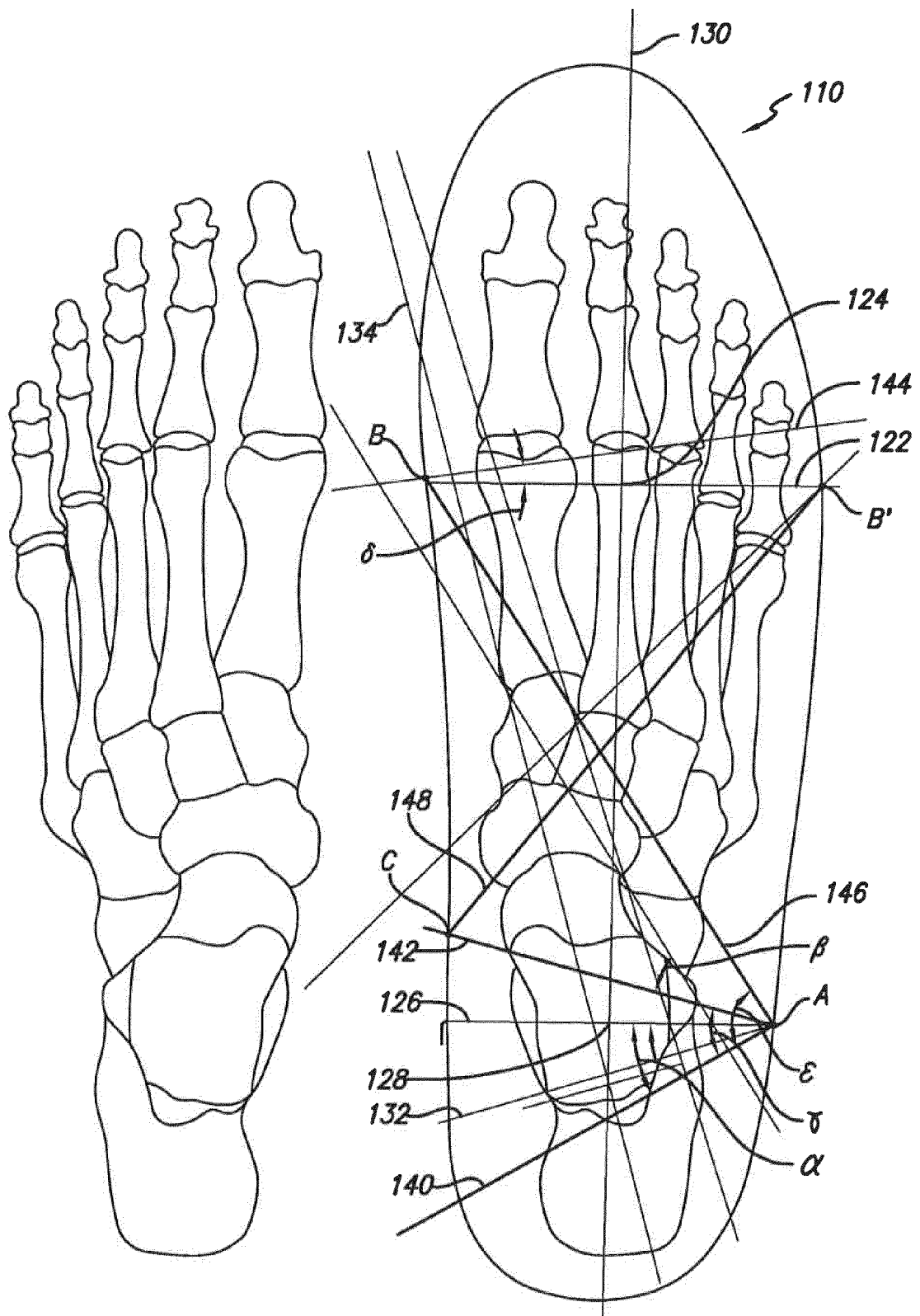
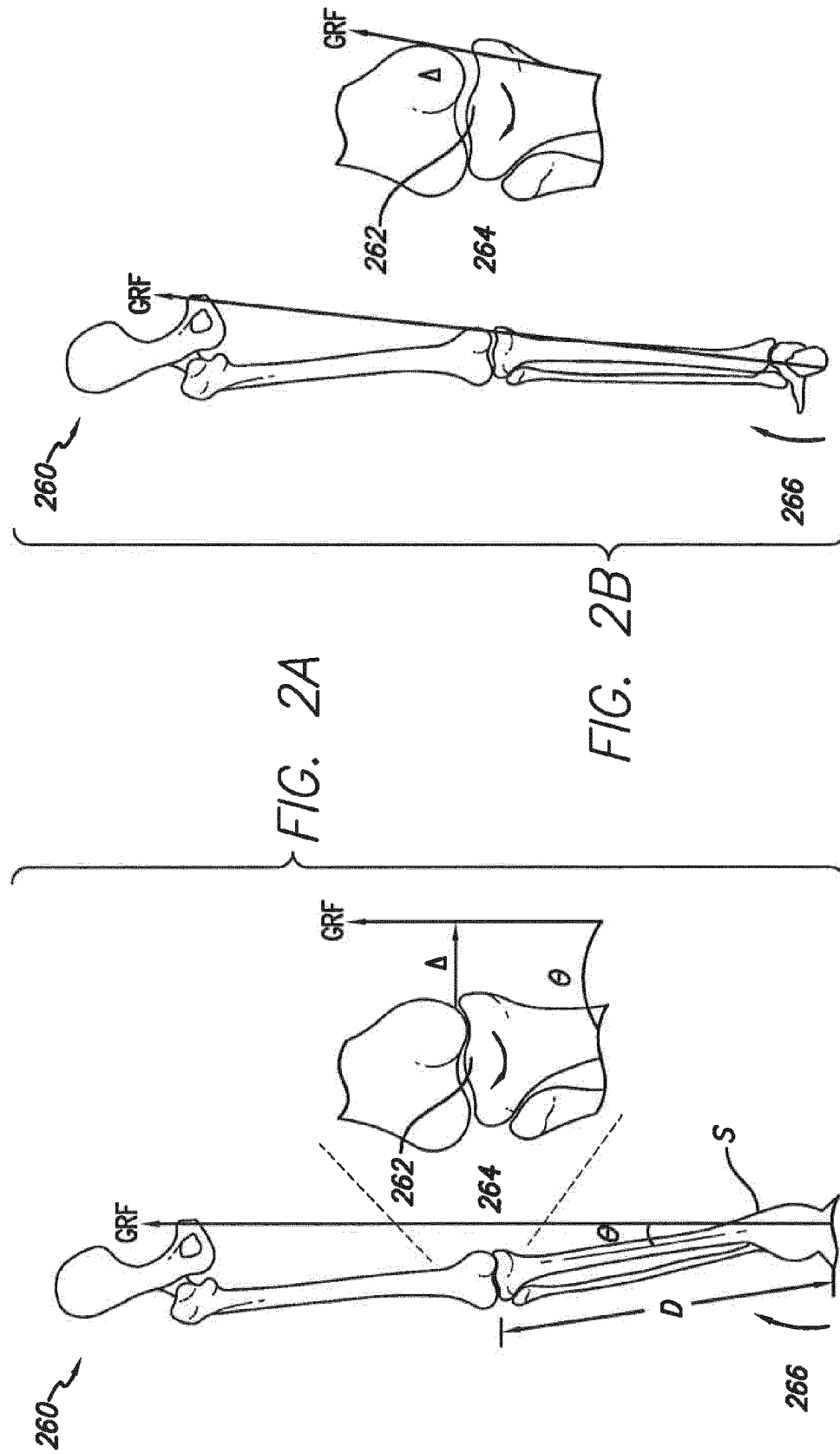
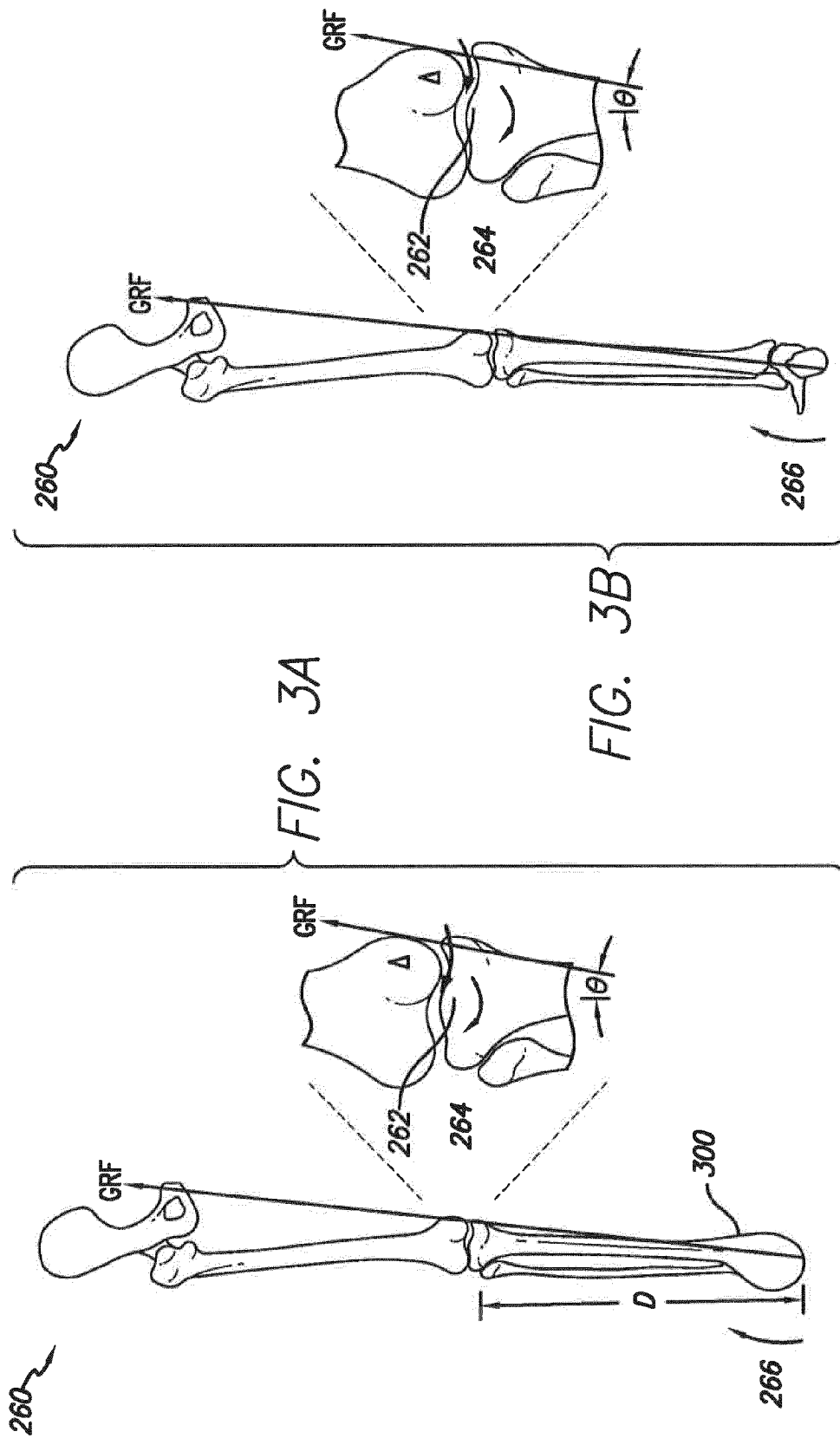


FIG. 1





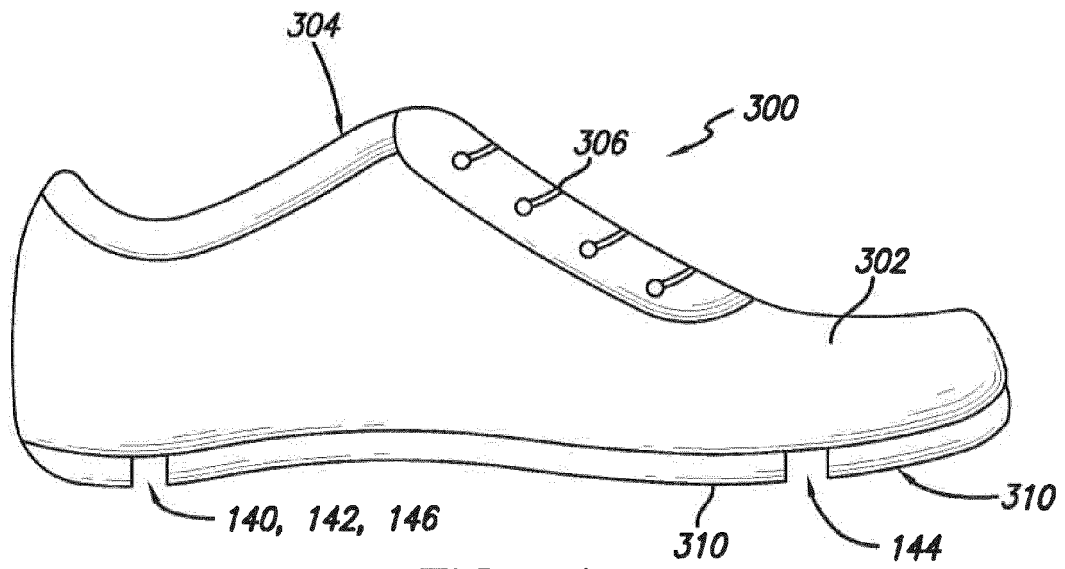


FIG. 4

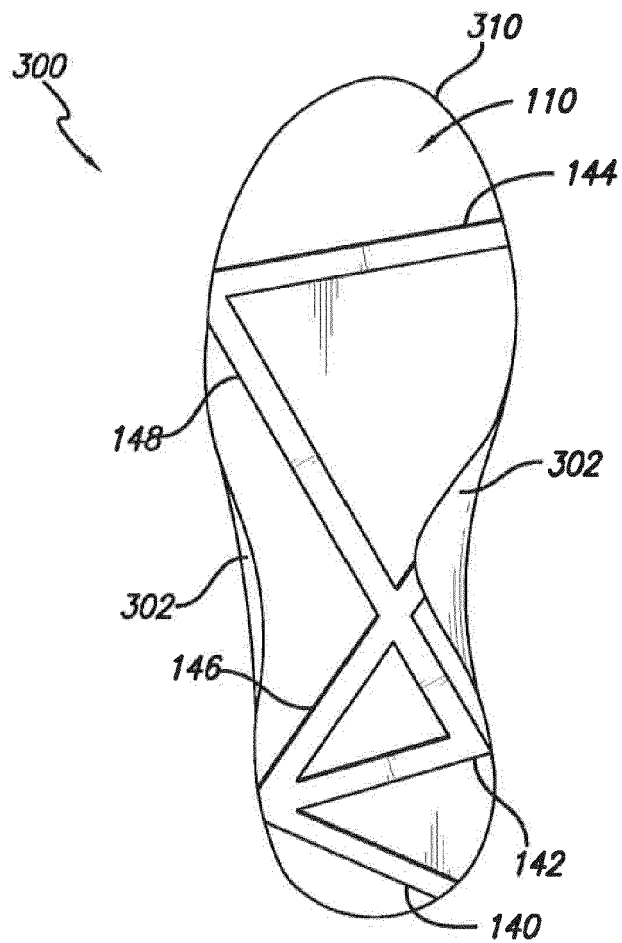


FIG. 5

**PARTIAL EUROPEAN SEARCH REPORT**

Application Number

under Rule 62a and/or 63 of the European Patent Convention.
This report shall be considered, for the purposes of
subsequent proceedings, as the European search report

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DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (IPC)
A	US 2005/076536 A1 (HATFIELD TOBIE D [US] ET AL) 14 April 2005 (2005-04-14) * paragraph [0038]; claims; figures *	2-11	INV. A43B13/14
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			A43B

INCOMPLETE SEARCH

The Search Division considers that the present application, or one or more of its claims, does/do not comply with the EPC so that only a partial search (R.62a, 63) has been carried out.

Claims searched completely :

Claims searched incompletely :

Claims not searched :

Reason for the limitation of the search:

see sheet C

1

EPO FORM 1503 03/82 (P04E07)

Place of search	Date of completion of the search	Examiner
The Hague	10 January 2017	Claudel, Benoît
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		
T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document		

**INCOMPLETE SEARCH
SHEET C**

Application Number

EP 16 15 7939

Claim(s) completely searchable:
2-11

Claim(s) not searched:
1, 12-14

Reason for the limitation of the search:

After invitation pursuant Rule 62a EPC, the applicant filed justification for multiple independent claims.

The applicant mentions claim 12 is dependent on claim 1. This is not the case, as claim 12 does not have the feature of a second apex. There is indeed only one apex defined in claim 12, and 2 apexes in claim 1. Besides, claim 1 contravenes Article 123(2) EPC, because the first Apex is clearly defined at the lateral edge of the base of the heel, in the parent PCT application, [0027]. Claim 1 is including only a part of the feature, leading to an intermediate generalization.

The applicant argues that claim 1 covers the embodiment of Figure 1. This is not the case, as it misses at least the feature of the fourth groove extending from the lateral base of the heel to the medial base of the forefoot. Claim 1 simply defines a line between a first apex somewhere at the base of the heel. Leaving a lot of interpretation on where this first apex is. Besides, the parent application was granted covering the embodiment of figure 1.

Based on this, the application has been restricted to the auxiliary request of the applicant, i.e. claim 2, and dependent claims 3-11.

**ANNEX TO THE EUROPEAN SEARCH REPORT
ON EUROPEAN PATENT APPLICATION NO.**

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10-01-2017

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For more details about this annex : see Official Journal of the European Patent Office, No. 12/82

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