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  G06T 17/30<sup>(2006.01)</sup>
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# (54) METHOD AND APPARATUS FOR PROCESSING TRAJECTORY, ROADSIDE DEVICE AND CLOUD CONTROL PLATFORM

(57) The present disclosure discloses a method and apparatus for processing a trajectory, a roadside device, and a cloud control platform, relates to the field of intelligent transportation, and in particular to the field of computer vision. An implementation scheme is: acquiring a to-be-processed trajectory, the to-be-processed trajectory comprising at least three sequential position points;

determining an auxiliary line based on the position points and a preset number of interpolation points; determining positions of the interpolation points based on the preset number of interpolation points; and determining and outputting a target trajectory based on the auxiliary line and the positions of the interpolation points.

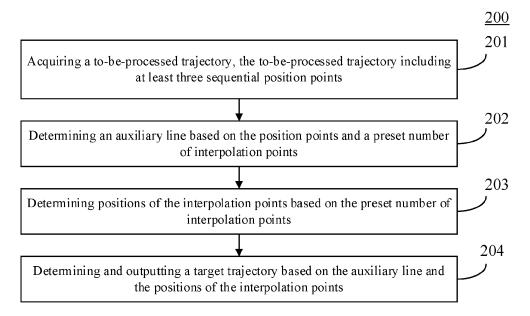


Fig. 2

**DOCUMENTS CONSIDERED TO BE RELEVANT** 



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#### ANNEX TO THE EUROPEAN SEARCH REPORT ON EUROPEAN PATENT APPLICATION NO.

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