



(11)

EP 3 969 745 B9

(12)

CORRECTED EUROPEAN PATENT SPECIFICATION

(15) Correction information:

Corrected version no 1 (W1 B1)
Corrections, see
Claims EN 1

(48) Corrigendum issued on:

06.11.2024 Bulletin 2024/45

(45) Date of publication and mention of the grant of the patent:

03.07.2024 Bulletin 2024/27

(21) Application number: 20734432.6

(22) Date of filing: 14.05.2020

(51) International Patent Classification (IPC):

F03D 7/02(2006.01) F03D 1/06(2006.01)

(52) Cooperative Patent Classification (CPC):

F03D 7/0296; F03D 1/0633; F05B 2240/30; F05B 2240/3042; F05B 2260/96; Y02E 10/72

(86) International application number:

PCT/GB2020/051178

(87) International publication number:

WO 2020/229829 (19.11.2020 Gazette 2020/47)

(54) A METHOD FOR FORMING AN ADD-ON COMPONENT FOR AN AEROFOIL

VERFAHREN ZUR HERSTELLUNG EINES ZUSATZBAUTEILS FÜR EINE TRAGFLÄCHE

PROCÉDÉ DE FORMATION D'UN COMPOSANT RAPPORTÉ POUR UNE SURFACE PORTANTE

(84) Designated Contracting States:

**AL AT BE BG CH CY CZ DE DK EE ES FI FR GB
GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO
PL PT RO RS SE SI SK SM TR**

(30) Priority: 16.05.2019 GB 201906920

(43) Date of publication of application:
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EP-A1- 3 205 874 US-A1- 2012 027 590

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DescriptionBackground

5 [0001] The present application relates to a method for forming an add-on component for an aerofoil.

[0002] It is widely known that unwanted noise is essentially a form of pollution that affects health and wellbeing, especially near airports and wind farm sites. Studies have shown that both aviation and wind farm noise pollution have adverse health effects resulting in annoyance, sleep disturbance and cognitive impairment. To protect the public, strict noise regulations have been implemented to both the aviation and wind energy sectors. The European Commission outlines aviation targets that in year 2050 aviation noise emission will be reduced by 65% compared to the level produced in 2000. However, civil aviation traffic is expected to expand worldwide between 4% and 5% annually with higher growth in the Middle East and Asia. Similarly, Wind Europe issued a report in 2014 on the projected energy capacity scenarios in 2030, where their central scenario outlines that 320 GW electricity will be generated by wind energy and that 78% of this would be produced by onshore wind farms.

10 [0003] The significant growth within the aviation industry and the onshore wind farms in the European Union (EU) member states will inevitably increase the aerodynamic noise pollution. Aircraft noise is mainly caused by the jet engine and high lift devices during take-off and landing. However, development in the technology of jet engines has seen a reduction in jet noise, but an increase in noise generated by the high bypass-ratio fan blades. Wind turbine mechanical noise is mainly caused by the moving parts inside the gearbox and generator. However, the recent development of high precision gear tooth profile designs and acoustic insulation of casings has reduced the source of mechanical noise. In contrast, the aerodynamic noise generated from the wind turbine blade is more difficult to reduce. To protect local settlements, maximum noise levels are currently set at 35-45 dB(A) at 350 m from the wind turbines. As a result, wind turbine companies often reduce the rotation speed of their turbines in high wind speed scenarios in order to curb the aerodynamic noise level and not exceed the prescribed limit. This practice essentially leads to a lower utilisation of the available wind energy source. Reduction of noise without reducing the rotor-speed would therefore make wind energy cheaper and, hence, a more attractive alternative for fossil energy. In quantitative terms, a further 1 dB noise reduction from the current level could lead to significant increase in wind energy production.

15 [0004] Aerodynamic noise can emanate from the aerofoils' leading and trailing edges. The aerofoil noise is generated either at the leading edge of the blades, through interaction with the atmospheric turbulence, or at the trailing edges, where turbulence in the boundary layer develops on the blade's surface and scatters into sound. Leading edge noise and trailing edge noise are different noise sources and not related to each other. Trailing edge noise (also commonly referred to self-noise), remains one of the most relevant noise sources related to the aviation and wind turbine industries.

20 [0005] It is known from the prior art that trailing edge noise reduction can be achieved by use of a simple sawtooth trailing edge. First, noise reduction by a serrated trailing edge is partly related to destructive interference caused by a phase lag mechanism of turbulence noise scattering on the slanted/oblique edge. Second, the root of the serrated trailing edge is effective in turbulence noise radiation. Third, two noise sources that are displaced by 180° phase angle in the longitudinal direction, such as the leading edge slit case, have been shown to be able to maximise the destructive interference for the aerodynamic noise reduction.

25 [0006] CN 109292076 A1 (Harbin Inst. Technology) discloses a low self-noise aerofoil structure having a multi-wavelength serrated trailing edge. The aerofoil body is detachably connected to the noise reduction trailing edge plate through a connector.

30 [0007] WO 2017/220594 A1 (LM Wind Power) discloses a wind turbine blade comprising two or more serrations provided along a section of the trailing edge.

35 [0008] US 2012/027590 A1 (Bonnet) discloses a rotor blade assembly and a method for reducing the noise of a rotor blade for a wind turbine.

40 [0009] WO 2019/158876 A1 (Safran Aircraft Engines) discloses a profiled air flow structure comprising a body and acoustically absorbent porous regions.

45 [0010] US 2017/0174320 (Amazon Tech Inc.) discloses systems, methods, and apparatus for actively adjusting the position of one or more propeller blade treatments of a propeller blade of an aerial vehicle during operation of the aerial vehicle.

50 [0011] US 2017/0022820 A1 (Rolls-Royce plc) discloses an aerofoil for a gas turbine which has a series of first and second recesses cut into the leading edge of the aerofoil itself. A formula is given for how to cut the recesses in order to reduce noise at the leading edge of the aerofoil, the formula being:

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$$f_0 = U/2h_{tt}$$

where f_0 is the frequency of noise that is reduced, U is the velocity of air passing over the leading edge, and h_{tt} is the

distance in height of the adjacent troughs of the first and second recesses.

[0012] Gruber, Azarpeyvand and Joseph "Airfoil trailing edge noise reduction by the introduction of sawtooth and slotted trailing edge geometries" (Proceedings of 20th International Congress on Acoustics, ICA 2010) compares the measurements of the trailing edge self-noise reduction obtained using sawtooth and slit serrations on a NACA651210 aerofoil.

Summary of the Invention

[0013] The inventive realisation of the present application is that the formula disclosed in US 2017/0022820 A1 is incorrect and that a more accurate formula is as defined in claim 1. Furthermore, it has been discovered that improved results can be obtained by constructing a separate component for an aerofoil according to the inventive formula and attaching it to the aerofoil at the trailing edge of the aerofoil, rather than cutting recesses into the aerofoil itself as in US 2017/0022820 A1.

[0014] Furthermore, it has been realised that an equivalent inventive formula can be used to tune the noise reduction obtainable from an aerofoil having slit serrations (as disclosed in Gruber, Azarpeyvand and Joseph referred to above).

[0015] According to the invention, there is provided a method for forming an add-on component for an aerofoil having a leading edge and a trailing edge, said component being formed in order to reduce the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of the aerofoil over the trailing edge of the component at a freestream velocity U_∞ , the method including the steps of:

- 20 (a) selecting a frequency f_{peak} of sound that is to be reduced;
- (b) selecting a freestream velocity U_∞ of air;
- (c) providing a component having a joining edge for joining to a trailing edge of an aerofoil and a trailing edge opposite said joining edge;
- 25 (d) forming the trailing edge of the component into a plurality of pairs of peaks, each of said pairs having a first trough, a first peak, a second trough, a second peak, which is a greater distance from the joining edge than the first peak, and a third trough, wherein the first trough is on one side of the first peak, the second trough is between the first and second peak, and the third trough is on the other side of the second peak to the second trough;
- (e) wherein the first and third troughs of each pair of peaks lie substantially on a first axis, the second troughs of 30 each pair of peaks lie substantially on a second axis, and the second peaks of each pair of peaks lie on a third axis;
- (f) and wherein the component is formed according to the formula:

$$h' = \frac{\hat{c} \cdot U_\infty \cdot \kappa}{2f_{peak}},$$

35 where \hat{c} is from 0.4 to 0.8 and $\kappa = \left(\frac{h''}{h'}\right)^{0.4}$

40 where h' is the shortest distance between the first axis and the second axis, h'' is the shortest distance between the 2nd and 3rd axis, f_{peak} is the frequency of sound to be reduced and U_∞ is the freestream velocity in the flow direction of air flowing over the trailing edge of the component.

[0016] In one embodiment, $h' = h''$.

[0017] The shortest distance from the first peak to the first axis may be identical for each of said pair of peaks within the plurality of pairs.

[0018] The third trough of first pair of peaks may be the first trough of a second pair of peaks which is adjacent to said first pair of peaks.

[0019] A method for reducing the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of an aerofoil over the trailing edge of an aerofoil at freestream velocity U_∞ , includes the steps of:

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- (a) forming an add-on component for an aerofoil according to a method as defined above and
- (b) attaching said component to said aerofoil.

[0020] The method may additionally include the steps of forming a plurality of components and attaching said plurality of components to said aerofoil. For example, three components may be formed and attached to said aerofoil, the first component proximate the tip of the aerofoil, the second component proximate the middle of the aerofoil and the third component proximate the other end of the aerofoil to the tip.

[0021] In one embodiment the components may be identical. However, in an alternative embodiment said components have different values of h' and/or h'' .

[0022] According to a realisation mode not in accordance with the present invention (which relates to the slits component referred to above), there is provided a method for forming an add-on component for an aerofoil having a leading edge and a trailing edge, said component being formed in order to reduce the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of the aerofoil over the trailing edge of the component at freestream velocity U_∞ , the method including the steps of:

- (a) selecting a frequency f_{peak} of sound that is to be reduced;
- (b) selecting a freestream velocity U_∞ of air;
- (c) providing a component having a joining edge for joining to a trailing edge of an aerofoil and a trailing edge opposite said joining edge;
- (d) forming the trailing edge of the component into a plurality of peaks separated by troughs, with each peak being connected to each trough on either side of the peak by a wall which is substantially perpendicular to the trailing edge, wherein the peaks each have a width (a) which is substantially parallel to the trailing edge and the troughs each have a width (W) which is substantially parallel to the trailing edge, said width also being the gap between adjacent peaks wherein the peaks lie substantially on a first axis and the troughs lie substantially on a second axis and wherein the shortest distance from the first axis to the second axis is defined as H ,
- (e) and wherein the component is formed according to the formula:

$$H = \frac{\hat{c} \cdot U_\infty}{2f_{peak}},$$

where \hat{c} is from 0.4 to 0.8.

[0023] In one embodiment, the ratio of the gap between adjacent peaks (W) and the spanwise correlation length scale of the turbulent eddies (L_y) is governed by the expression $0.2 \leq W/L_y \leq 0.5$.

[0024] A method for reducing the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of an aerofoil over the trailing edge of an aerofoil at freestream velocity U_∞ includes the steps of:

- (a) forming an add-on component for an aerofoil according to a method as defined above and
- (b) attaching said component to said aerofoil.

[0025] The method may additionally include the steps of forming a plurality of components and attaching said plurality of components to said aerofoil. For example, three components may be formed and attached to said aerofoil, the first component proximate the tip of the aerofoil, the second component proximate the middle of the aerofoil and the third component proximate the other end of the aerofoil to the tip.

[0026] In one embodiment the components may be identical. However, in an alternative embodiment said components have different values of H .

[0027] In another aspect not in accordance with the invention, there is provided a method for forming an add-on component for an aerofoil having a leading edge and a trailing edge, said component being formed in order to reduce the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of the aerofoil over the trailing edge of the component at flow velocity U , the method including the steps of:

- (a) selecting a frequency f_{peak} of sound that is to be reduced;
- (b) selecting a flow velocity U of air;
- (c) providing a component having a joining edge for joining to a trailing edge of an aerofoil and a trailing edge opposite said joining edge;
- (d) forming the trailing edge of the component into a plurality of pairs of peaks, each of said pairs having a first trough, a first peak, a second trough, a second peak, which is a greater distance from the joining edge than the first peak, and a third trough, wherein the first trough is on one side of the first peak, the second trough is between the first and second peak, and the third trough is on the other side of the second peak to the second trough;
- (e) wherein the first and third troughs of each pair of peaks lie substantially on a first axis, the second troughs of each pair of peaks lie substantially on a second axis, and the second peaks of each pair of peaks lie on a third axis;
- (f) and wherein the component is formed according to the formula:

$$h' = U \kappa / 4f_{peak}$$

$$\text{where } \kappa = \left(\frac{h''}{h'} \right)^{0.4}$$

5 where h' is the shortest distance between the first axis and the second axis, h'' is the shortest distance between the 2nd and 3rd axis, f_{peak} is the frequency of sound to be reduced and U is the flow velocity in the flow direction of air flowing over the trailing edge of the component.

10 [0028] In yet a further aspect there is provided a method for reducing the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of an aerofoil over the trailing edge of an aerofoil at flow velocity U , the method including the steps of providing at least one component which has been formed according to a method as defined above and attaching said component to said aerofoil.

15 [0029] In yet a further still aspect there is provided add-on component for an aerofoil having a leading edge and a trailing edge, said component being formed in order to reduce the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of the aerofoil over the trailing edge of the component at flow velocity U , the component including

16 a joining edge for joining to a trailing edge of an aerofoil,

17 a trailing edge opposite said joining edge,

18 and a surface between the joining edge and the trailing edge,

23 wherein the trailing edge of the component is formed into a plurality of pairs of peaks, each of said pairs having a first trough, a first peak, a second trough, a second peak, which is a greater distance from the joining edge than the first peak, and a third trough, wherein the first trough is on one side of the first peak, the second trough is between the first and second peak, and the third trough is on the other side of the second peak to the second trough,

28 wherein the first and third troughs of each pair of peaks lie substantially on a first axis, the second troughs of each pair of peaks lie substantially on a second axis, and the second peaks of each pair of peaks lie on a third axis,

33 where h' is the shortest distance between the first axis and the second axis, h'' is the shortest distance between the 2nd and 3rd axis, and

38 wherein the maximum thickness of the component in a direction perpendicular to said surface is from 0.5mm to 10mm.

43 [0030] A number of preferred embodiments of the present invention will now be described with reference to the drawings, in which:

48 Figure 1A is a schematic drawing showing the geometric parameters of the SRooTES, DRooTES and Slit trailing edge add-ons;

53 Figure 1B is a schematic drawing of DRooTES and slit trailing edge add-ons for carrying out the method according to the invention;

58 Figure 1C is a schematic drawing of the experimental set-up of the far-field noise measurement described herein;

63 Figure 2 depicts graphs comparing the performance of slit trailing edges at various slit amplitudes, H , where $\lambda = 3$ mm, for ΔPWL , dB, at $20 \text{ m/s} \leq U_{\infty} \leq 60 \text{ m/s}$;

68 Figure 3 depicts graphs comparing non-dimensional frequency at various slit amplitudes, H ; where λ is kept at 3 mm, W is kept at 0.3 mm and $\hat{c} = 0.45$; at $20 \text{ m/s} \leq U_{\infty} \leq 60 \text{ m/s}$;

73 Figure 4 depicts graphs comparing the performance of slit trailing edges at various slit wavelength, λ (mm), and width of slit root, W kept at 0.3 mm. $\hat{c} = 0.45$, for ΔPWL , dB, at $U = 30 \text{ m/s}$ and $U_{\infty} = 60 \text{ m/s}$;

78 Figure 5 depicts graphs comparing the performance of between the baseline and slit (different W/A , but with the same λ) trailing edges for ΔPWL , dB; where $H = 15 \text{ mm}$; $\lambda = 3 \text{ mm}$; at $20 \leq U_{\infty} \leq 60 \text{ m/s}$;

Figure 6 depicts graphs showing the comparison between the baseline and DRooTES (with different h') trailing edges, Δ PWL (dB); where $\lambda = 3$ mm; at $20 \leq U_{\infty} \leq 60$ m/s;

5 Figure 7 depicts graphs showing the non-dimensional frequency of the DRooTES when $h' = h''$, i.e. $\kappa = 1$, at various root-to-root amplitude $h', \lambda = 6$ mm and $\hat{c} = 0.45$, at $20 \leq U_{\infty} \leq 60$ m/s;

Figure 8 depicts graphs showing the non-dimensional frequency of the DRooTES when $h' \neq h''$, i.e. $\kappa \neq 1$, at various amplitude H , $\lambda = 6$ mm and $\hat{c} = 0.45$, at $20 \leq U_{\infty} \leq 60$ m/s;

10 Figure 9 depicts graphs comparing SRooTES, DRooTES and Slit trailing edges where amplitude, H , and wavelength, λ , were kept at 15 mm and 3 mm for Δ PWL, dB, at $20 \text{ m/s} < U_{\infty} < 60$ m/s; and

15 Figure 10 depicts graphs comparing SRooTES, DRooTES and Slit trailing edges where amplitude, H , and wavelength, λ , were kept at 30 mm and 3 mm for Δ PWL, dB, at $20 \text{ m/s} < U_{\infty} < 60$ m/s.

20 [0031] An aerofoil add-on component for carrying out the method in accordance with the invention is referred to herein as Double-Rooted Trailing Edge Serration (abbreviated to "DRooTES"), where for the first time, not only the level of trailing edge noise reduction can be improved, but also fine-tuning of the frequency of interest for the self-noise reduction becomes a possibility. This nomenclature has been adopted by analogy with a standard sawtooth serration, which is referred to herein as "SRooTES" (Single Rooted Trailing Edge Serration).

Nomenclature

[0032]

25	/	= frequency, Hz
30	H	= amplitude, m
35	λ	= wavelength, m
40	h'	= root-root longitudinal displacement, mm
45	h''	= root-tip longitudinal displacement, mm
50	ϕ	= angle of the secondary serration tip, degrees
55	λ_0	= root-mid root lateral displacement, mm
	h	= half of amplitude, m
	c_0	= chord length, m
	W	= slit width at root, mm
	a	= slit width at tip, mm
	AoA, θ	= Angle of Attack
	Θ	= Polar Angle, degrees
	U_{∞}	= Freestream Velocity, m/s
	x	= Position on aerofoil
	n	= convection velocity factor
	\bar{c}	= factor for the propagation of the pressure driven turbulent eddies

PWL	= Sound Power Level, dB
Δ PWL	= Difference in Sound Power Level, dB
5 OAPWL	= Overall Sound Power Level, dB
L_y	= spanwise correlation length scale of the turbulent eddies

Scientific theory

[0033] This application focuses on the characteristics and mechanisms of acoustic interferences on turbulent boundary layer trailing edge noise by DRooTES and slit trailing edges. The fundamental theory that underpins this work is based on interference in wave theory. There are two forms of interference: constructive and destructive. In theory, a perfect destructive interference occurs when acoustic radiation from two sources, S_1 and S_2 as shown in Figure 1B, are 180° (π) out-of-phase. The relevant phase difference (or phase angle) can be expressed as $n\pi$, where $n = 1, 3, 5$, and so on. This results in the cancellation of the acoustic radiation. In contrast, a perfect constructive interference occurs when acoustic radiation is in-phase between the two sources (i.e. when $n = 2, 4, 6$, and so on), which results in amplification of the acoustic radiation to the far field. As a generic term, the following equation is applied to determine the phase angle, ω , defined as:

$$\hat{\omega} = \frac{\omega \cdot l}{U_\infty}, \text{ where } \omega = 2\pi f \quad \text{Eqn. 1}$$

25 where ω is oscillation frequency, f is the frequency, l is the longitudinal displacement between the two sources and U is the freestream velocity. Therefore, applying an "out-of-phase" angle (destructive interference) to Eqn. 1, based on the distance between S_1 and S_2 (scatter sources) defined as h' for the DRooTES, and H for the Slit trailing edge in Fig. 1A, the following equations are derived:

$$\frac{2\pi f \cdot l}{U_\infty} = n\pi$$

$$35 St = \frac{f \cdot l}{U_\infty} = \frac{1}{2}n \quad \begin{array}{l} \text{for destructive interference, } n = 1, 3, 5, \dots \\ \text{for constructive interference, } n = 2, 4, 6, \dots \end{array} \quad \text{Eqn. 2}$$

where St is known as the Strouhal number, which demonstrates the respective values of non-dimensional frequency at which destructive interference occurs at odd numbers, and for the constructive interference occurs at even numbers.

Details of the Trailing Edge Parameters

[0034] The acronyms used herein as follows: Slits, and Double-Rooted Serrations (DRooTES).

Experimental set-up

[0035] A NACA65-(12)10 cambered aerofoil has a chord-length of $c_0 = 0.145$ m to $c_0 = 0.170$ m for serrated trailing edge cases, except for the Baseline (B), (un-serrated) chord length of $c_0 = 0.1425$ m to $c_0 = 0.155$ m, and a span-wise length of 0.45 m. To ensure similar wetted surface areas, different chord lengths were used for the baseline and serrated cases. The chord-lengths of the un-serrated trailing edge cases (Baseline) were half of the chord lengths for the serrated trailing edges in Slits and Double-Rooted Serrations (DRooTES). Note that, basically, the SRooTES represents a simple sawtooth trailing edge. The aerofoil was constructed in two main parts: the main aerofoil body and the detachable flat plate trailing edge. The main aerofoil was manufactured from aluminium alloy with surface pressure taps across the upper and lower surfaces, and a 0.8 mm slot along the trailing edge. A detachable, flat plate of 0.8 mm thickness was laser cut to form various trailing edge shapes.

[0036] A illustrates the geometric parameters of the trailing edge flat plate cases. These are defined as the serration amplitude (H), serration wavelength (λ), root1-root2 longitudinal displacement (h'), root2-tip2 longitudinal displacement (h''), angle of the serration tip (ϕ) and lateral-displacement serration roots (λ_0). Unless otherwise stated, the root1-root2

longitudinal displacement (h') and root1-root2 lateral displacement (λ_0) are half the amplitude (H) and wavelength (λ) respectively. For the Slit, the geometrical parameters are the slit amplitude (also defined by H), slit wavelength (also defined by λ), width of slip tip (a) and width of slit gap (W). The present study investigated four cases: Baseline, SRooTES, DRooTES and Slit. Figure 1B compares more closely the DRooTES and Slit geometries and will be referred to below.

[0037] A 0.8 mm slot along the rear end of the main aerofoil body allows for insertion of 0.8 mm thickness flat plate trailing edges. The ranges of serration amplitude (H) and wavelength (λ) of the Slit, SRooTES and DRooTES were 5 mm $\leq H \leq$ 30 mm intervals of 5 mm, and 3 mm $\leq \lambda \leq$ 35 mm respectively. The root1-root2 lateral displacement and angle of the serration tip of the DRooTES were 1.5 mm $\leq \lambda_0 \leq$ 4.5 mm interval of 1.5 mm and $0^\circ \leq \phi \leq 84.3^\circ$. The Baseline trailing edge was half the amplitude of the serrated case, to ensure similar wetted surface area to both SRooTES and DRooTES. For the ease of comparison between SRooTES and DRooTES to the slit trailing edge the Baseline trailing edge would also be assumed to be half the amplitude. A coarse sandpaper was permanently applied to the upper and lower surfaces at 30 mm from the aerofoil leading edge to ensure the boundary layers were fully tripped to turbulent. The sandpaper strip had a width of 10 mm and a thickness of 0.95 mm.

15 Wind Tunnel Facilities and Instrumentation

[0038] The wind tunnel facilities and instrumentation setup for the far-field noise measurement were performed in the aero-acoustics facility at Brunel University London, which consisted of an open jet wind tunnel within an anechoic chamber of 4 m \times 5 m \times 3.4 m. The open jet nozzle dimension was 0.3 m \times 0.1 m (width \times height). The aerofoil was attached to the side plates flush to the nozzle lips. The open jet wind tunnel had an operation capacity of up to $U = 80$ m/s, with typical low turbulence flow between 0.1% and 0.2%. The background noise (without aerofoil, but with side plates) was largely contributed by the open jet noise, which was very low in comparison to the aerofoil self-noise level produced at the identical flow speed. All far-field noise measurements were performed at the geometric angle of attack (AoA) $\theta = 0^\circ$.

25 Far-Field Array Noise Measurements

[0039] The far-field array noise measurements were performed with eight G.R.A.S. half-inch condenser microphones (46AE) mounted at polar angles from $\theta = 50^\circ$ to $\theta = 120^\circ$ intervals of $\theta = 10^\circ$. The $\theta = 90^\circ$ microphone was positioned at the mid-span of the aerofoil and at 0.97 m above the trailing edge. Figure 1C illustrates the experimental setup of the far-field array. A gain of ± 20 dB was applied to each microphone signal through the G.R.A.S. 12AX 4-Channel CCP amplifier. The data were acquired using a 16-bit analogue-digital card manufactured by National Instruments. The sampling frequency was 40 kHz with a sampling time of 20 seconds. The data were windowed and the Power Spectral Density (PSD) of 1 Hz bandwidth was computed from a 1024 points FFT and a 50% overlap time. The noise was calculated to obtain the Sound Power Level (PWL) assuming a spherical spreading of the sound waves from the trailing edge. Noise measurements were taken at various freestream velocities from $U = 20$ m/s to $U = 60$ m/s, at $U = 10$ m/s intervals.

[0040] A illustrates the geometric parameters of the trailing edge flat plate cases. For the DRooTES, these are defined as the serration amplitude (H), serration wavelength (λ), root1-root2 longitudinal displacement (h'), root2-tip2 longitudinal displacement (h''), angle of the serration tip (ϕ) and lateral-displacement serration roots (λ_0). Unless otherwise stated, the root1-root2 longitudinal displacement (h') and root1-root2 lateral displacement (λ_0) are normally half the amplitude (H) and wavelength (λ) respectively. For the Slit, the geometrical parameters are the slit amplitude (also defined by H), slit wavelength (also defined by λ), width of slip tip (a) and width of slit gap (W).

45 Experimental set-up

[0041] A NACA65-(12)10 cambered aerofoil has a chord-length of $c_0 = 0.145$ m to $c_0 = 0.170$ m for serrated trailing edge cases, except for the Baseline (B), (un-serrated) chord length of $c_0 = 0.1425$ m to $c_0 = 0.155$ m, and a span-wise length of 0.45 m. To ensure similar wetted surface areas, different chord lengths were used for the baseline and serrated cases. The chord-lengths of the un-serrated trailing edge cases (Baseline) were half of the chord lengths for the serrated trailing edges in Slits and Double-Rooted Serrations (DRooTES). Note that, basically, the SRooTES represents a simple sawtooth trailing edge. The aerofoil was constructed in two main parts: the main aerofoil body and the detachable flat plate trailing edge. The main aerofoil was manufactured from aluminium alloy with surface pressure taps across the upper and lower surfaces, and a 0.8 mm slot along the trailing edge. A detachable, flat plate of 0.8 mm thickness was laser cut to form various trailing edge shapes.

[0042] A illustrates the geometric parameters of the trailing edge flat plate cases. These are defined as the serration amplitude (H), serration wavelength (λ), root1-root2 longitudinal displacement (h'), root2-tip2 longitudinal displacement (h''), angle of the serration tip (ϕ) and lateral-displacement serration roots (λ_0). Unless otherwise stated, the root1-root2 longitudinal displacement (h') and root1-root2 lateral displacement (λ_0) are half the amplitude (H) and wavelength (λ)

respectively. For the Slit, the geometrical parameters are the slit amplitude (also defined by H), slit wavelength (also defined by λ), width of slit tip (a) and width of slit gap (W). The present study investigated four cases: Baseline, SRooTES, DRooTES and Slit. Figure 1B compares more closely the DRooTES and Slit geometries and will be referred to below.

[0043] A 0.8 mm slot along the rear end of the main aerofoil body allows for insertion of 0.8 mm thickness flat plate trailing edges. The ranges of serration amplitude (H) and wavelength (λ) of the Slit, SRooTES and DRooTES were 5 mm $\leq H \leq$ 30 mm intervals of 5 mm, and 3 mm $\leq \lambda \leq$ 35 mm respectively. The root1-root2 lateral displacement and angle of the serration tip of the DRooTES were 1.5 mm $\leq \lambda_0 \leq$ 4.5 mm interval of 1.5 mm and $0^\circ \leq \phi \leq 84.3^\circ$. The Baseline trailing edge was half the amplitude of the serrated case, to ensure similar wetted surface area to both SRooTES and DRooTES. For the ease of comparison between SRooTES and DRooTES to the slit trailing edge the Baseline trailing edge would also be assumed to be half the amplitude. A coarse sandpaper was permanently applied to the upper and lower surfaces at 30 mm from the aerofoil leading edge to ensure the boundary layers were fully tripped to turbulent. The sandpaper strip had a width of 10 mm and a thickness of 0.95 mm.

Wind Tunnel Facilities and Instrumentation

[0044] The wind tunnel facilities and instrumentation setup for the far-field noise measurement were performed in the aero-acoustics facility at Brunel University London, which consisted of an open jet wind tunnel within an anechoic chamber of 4 m x 5 m x 3.4 m. The open jet nozzle dimension was 0.3 m \times 0.1 m (width x height). The aerofoil was attached to the side plates flush to the nozzle lips. The open jet wind tunnel had an operation capacity of up to $U = 80$ m/s, with typical low turbulence flow between 0.1% and 0.2%. The background noise (without aerofoil, but with side plates) was largely contributed by the open jet noise, which was very low in comparison to the aerofoil self-noise level produced at the identical flow speed. All far-field noise measurements were performed at the geometric angle of attack (AoA) $\theta = 0^\circ$.

Far-Field Array Noise Measurements

[0045] The far-field array noise measurements were performed with eight G.R.A.S. half-inch condenser microphones (46AE) mounted at polar angles from $\theta = 50^\circ$ to $\theta = 120^\circ$ intervals of $\theta = 10^\circ$. The $\theta = 90^\circ$ microphone was positioned at the mid-span of the aerofoil and at 0.97 m above the trailing edge. Figure 1C illustrates the experimental setup of the far-field array. A gain of ± 20 dB was applied to each microphone signal through the G.R.A.S. 12AX 4-Channel CCP amplifier. The data were acquired using a 16-bit analogue-digital card manufactured by National Instruments. The sampling frequency was 40 kHz with a sampling time of 20 seconds. The data were windowed and the Power Spectral Density (PSD) of 1 Hz bandwidth was computed from a 1024 points FFT and a 50% overlap time. The noise was calculated to obtain the Sound Power Level (PWL) assuming a spherical spreading of the sound waves from the trailing edge. Noise measurements were taken at various freestream velocities from $U = 20$ m/s to $U = 60$ m/s, at $U = 10$ m/s intervals.

Results and Discussion

[0046] The results are presented in this section. The section covers the noise measurements obtained by the DRooTES and Slit trailing edges at U_∞ between 20 m/s and 60 m/s, with an interval of 10 m/s, at angle of attack $\theta = 0^\circ$.

[0047] So far, when describing the flow velocity, we only refer to the freestream value U_∞ in the generic equations (Eqn. 1 and Eqn. 2). However, when describing the acoustical destructive mechanism for the DRooTES and Slits, the main parameter is the convection speed of the turbulent eddies U_c , not the freestream velocity U_∞ . It should be noted that the convection speed of the turbulent eddies would also be affected by pressure-driven secondary flow structure along the edge. It has been determined that the net convection speed of the turbulent eddies u_c is between 40% and

$$\frac{u_c}{U_\infty} = 0.4 \quad \text{and} \quad \frac{u_c}{U_\infty} = 0.8$$
80% of the freestream velocity, i.e. between $\frac{u_c}{U_\infty} = 0.4$ and $\frac{u_c}{U_\infty} = 0.8$. Therefore, for the present DRooTES and Slit trailing edge, the generic expression in Eqn. 2 can be modified as:

$$St = \frac{f \cdot l}{u_c}, \quad u_c = \hat{c} \cdot U_\infty \quad \text{Eqn. 3}$$

where \hat{c} is the convection velocity factor, whose values lie between 0.4 and 0.8. As per the definition in Eqn. 3, the destructive interference mechanisms should occur at $St = 0.5, 1.5$ and so on, between the roots of the DRooTES, and roots and tips of the slit trailing edge.

SLIT TRAILING EDGESlit Amplitude (H)

5 [0048] Figure 2 illustrates a comparison of the sensitivity of slit trailing edges at various H at different freestream velocities, U_∞ . Δ PWL is defined as the difference between sound power levels, as a function of frequency, between the Baseline and Slit trailing edges: Δ PWL = PWL_B(f) - PWL_{Slit}(f). Note that the positive value of Δ PWL represents reduction in noise level, and the opposite is true for a negative value of Δ PWL to be treated as noise level increases. The results clearly show that slit trailing edge are the most effective in producing noise reduction up to 7 dB across the low to mid-
10 frequency range. The slit trailing edge can also result in significant degradation in performance, compared to the Baseline trailing edge, at high frequencies up to 5 dB. In addition, distinctive peaks of noise reduction Δ PWL achieved by individual slit trailing edges appears not to follow a trend of slit amplitude H across various U_∞ . The individual slit trailing edges observed that the maximum Δ PWL exhibited a relationship f to U_∞ and to H as follows:

15 1.

$$f \propto U_\infty$$

20 2.

$$f \propto \frac{1}{H}$$

25 [0049] Thus, the acoustic frequency where the maximum noise reduction occurs has a relationship to freestream velocity and the longitudinal displacement between either end of the slit (root and tip), H .

Non-Dimensional Frequency - Slit Amplitude, H

30 [0050] Figure 3 illustrates whether application of non-dimensional frequency against the broadband noise reduction of the slit trailing edge, at various slit amplitude (H), can be generalised. In theory, perfect destructive interference occurs when the acoustic radiations are at 180° out-of-phase between two sources, resulting in cancellation of the acoustic radiation. This is illustrated in Figure 1B, which shows the initial hypothesis of the destructive interference between two sources at the root and tip of the slit trailing edge. This means that the non-dimensional frequency ($f.H/u_c$, where $I = H$ for the slit trailing edge), defined in Eqn. 3, should be equal to 0.5. Figure 4 shows that the peak Δ PWL indeed takes place at around the $St \approx 0.5$ for different slit amplitudes (except for the $U = 60$ m/s, where a slight fluctuation of Strouhal number is evident). These results obtained experimentally confirm that the destructive interference mechanism pertaining to the 180° out of phase cancellation between the two sources (root and tip) is responsible for the maximum noise reduction.

35 [0051] Furthermore, Figure 3 clearly demonstrates that all the peaks Δ PWL pertaining to the slit configurations are followed by a significant dip of Δ PWL (noise increase) at $St \approx 1$, which is twice the value for the Strouhal number for maximum noise reduction discussed in the previous paragraph. This is another evidence of the acoustical interference mechanisms being present between the sources of the slit trailing edges. In summary, the destructive interference mechanisms (noise reduction) should occur at $St = 0.5, 1.5$, and so on, between the roots and tips of the slit trailing edge. This is consistent with the experimentally observed destructive interference at $St \approx 0.5$ and $St \approx 1.5$. On the other hand, a constructive interference (noise increase) occurs at $St \approx 1$.

Non-Dimensional Frequency - Wavelength (λ) with Constant Width of Slit Root (W)

40 [0052] Figure 4 shows a comparison of the sensitivity of non-dimensional frequency at various λ of the slit trailing edges, where the slit width, W , was kept constant at 0.3 mm. The results shown in Figure 4 are observed at all freestream velocities. The results clearly demonstrate that λ has no effect on the non-dimensional frequency with good comparison of the collapse Δ PWL peaks. Furthermore, the Δ PWL peak corresponds to the destructive interference at $St \approx 0.5$ and $St \approx 1.5$, and constructive interference at $St = 1$ for all cases. The effects of acoustic interference mechanism were still observable at the largest λ slit trailing edge cases, however, the effects of the mechanism were greatly weakened in comparison to the smallest λ .

Width of Slit Root (W) with a Constant Wavelength (λ)

[0053] Figure 5 presents a comparison of the broadband noise radiation for slit trailing edges at different aspect ratios of W/λ , where λ was kept constant at 3 mm. The results clearly demonstrate that as W increases, significant degradation of the noise performance (negative Δ PWL) occurs at low-to-mid frequencies across all freestream velocities. When W increases, the slit geometry becomes less compact, and eventually exceeds the spanwise integral length scale of the turbulent eddies. In this case, the slit at the root region slowly reverts to a straight trailing edge noise mechanism, which in turn diminishes the noise reduction capability.

[0054] In these experiments, the best performer is $W/\lambda = 0.15$ with reduction up to 6 dB, whereas the worst performer is with the largest $W/\lambda = 0.5$. At mid-to-high frequencies, 600 Hz $< f < 20$ kHz, it can be observed that the largest $W/\lambda (= 0.5)$ is the only configuration that does not result in noise increase. It can even achieve a slight broadband noise reduction up to 4 dB at low velocity. All the smaller W/λ configurations, on the other hand, only produce noise increase. Whereas, the slit trailing edges with smaller W/λ configuration result in a larger noise increase. Based on the results presented thus far, the following statements can be summarised:

- 1) Small W/λ configuration is desirable for broadband noise reduction at low-to-mid frequency. This is to avoid the slit width becoming comparable with the spanwise integral length scale of the turbulent eddies, which will weaken the destructive interference mechanism.
- 2) Large W/λ configuration is desirable to avoid noise increase at high frequency. This is to reduce the tendency of cross-flow across the slits and minimise flow leakage.

[0055] The noise reduction is subjected to the boundary condition of the ratio between the slit gap (W), and the incoming spanwise correlation length scale of the turbulent eddies (L_y) near the trailing edge. It is found from the experiments that the optimal condition for noise reduction at f_{peak} to occur is approximately when $0.2 \leq W/L_y \leq 0.5$. The lower and upper limits of W/L_y may fluctuate depending on the flow condition (such as Reynolds numbers, Mach numbers, etc).

DRooTESComparison of the Noise Results by DRooTES with Different Root-to-Root Amplitude (h')

[0056] The next investigation is to examine a new geometry feature, additional root, also utilising acoustic interference. This new geometry is called the DRooTES. Figure 6 presents a comparison of the broadband noise reduction (as well as noise increase) by the DRooTES against the baseline trailing edge at different root-to-root amplitude, h' (see Figure 1B). The best performer amongst all the DRooTES cases is the largest amplitude $h' = 15$ mm with noise reduction up to 7 dB at $U_\infty = 60$ m/s. The smallest $h' = 2.5$ mm exhibits noise reduction against the baseline trailing edge only at high frequency. The overall trend witnessed a degradation of the level of noise reduction with the decrease in amplitude of the DRooTES. At high frequencies, DRooTES exhibit an increase in noise, up to 2 dB, with the increase in amplitude.

Non-dimensional frequency - when the Root1-to-Root2 (h') = Root2-to-tip (h'') for DRooTES

[0057] Assuming that destructive interference between the two sources as per the Figure 1B exists for the DRooTES, the distance between them (h') should be used for the Strouhal number St . For destructive interference of a DRooTES, the following condition must be fulfilled:

$$St = \frac{f h'}{u_c} \kappa = \frac{1}{2} n$$

where $\omega = 2\pi f$. u_c is the same definition used for the slit trailing edge earlier, which is the convection speed of the turbulent eddies after subjected to the interaction with the pressure-driven secondary flow. The empirical factor $\kappa = \left(\frac{h''}{h'}\right)^{0.4}$, accounts for the possible non-equal value between the h' and h'' in the frequency scaling for the DRooTES.

[0058] Figure 7 shows the spectra of Δ PWL with non-dimensional frequencies $f h' / u_c$. Note that because $h' = h''$, $\kappa = 1$. It can be seen that the maximum noise reduction (maximum Δ PWL) occurs at $St \approx 0.5$, which is very close to the values observed for the slit trailing edge. This demonstrates the same acoustical destructive mechanism is also valid for the DRooTES.

Non-dimensional Frequency - when the Root1-to-Root2 (h') \neq Root2-to-tip (h'') for DRoOTES, with constant $H = 30$ mm

5 [0059] When $h' \neq h''$, then κ is no longer unity. Applying the factor of $\kappa = \left(\frac{h''}{h'}\right)^{0.4}$ into the frequency scaling, Figure 8 shows the sensitivities of broadband noise radiation at non-dimensional frequency at various h' , where h' is then adjusted accordingly to produce the overall H constant at 30 mm. The results demonstrate that the different curves collapse well. The increase of h' affects the maximum noise reduction peak. The best performer was $h' = 20$ mm with 8 dB reduction in comparison to the $h' = 5$ mm which achieved only 5 dB at same freestream velocity. However, the acoustic performance is depended on both the geometrical parameters and flow conditions.

SUMMARY

10 [0060] To determine the optimal geometrical dimension for the slits and DRoOTES (H for the slit, and h' for the DRoOTES), the following equations apply:

15 For slit,

$$20 H = \frac{\hat{c} \cdot U_\infty}{2f_{peak}}, \text{ where } \hat{c} = 0.4 - 0.8 \quad \text{Eqn. 4}$$

25 For DRoOTES,

$$25 h' = \frac{\hat{c} \cdot U_\infty \cdot \kappa}{2f_{peak}}, \text{ where } \hat{c} = 0.4 - 0.8 \text{ and } \kappa = \left(\frac{h''}{h'}\right)^{0.4} \quad \text{Eqn. 5}$$

30 [0061] Overall, the factors that potentially affect the exact values of \hat{c} and f_{peak} (sources of uncertainty) are:

35 1) Turbulent eddies scatter into pressure waves in close proximity to the roots, not exactly at the root, which can affect the "true" longitudinal displacement between roots and tips of the slit.
 2) Variation of the convection velocity factor ranges for the turbulent eddies
 3) An additional factor affecting the convection speed of the turbulent eddies due to the presence of secondary flows (e.g. the cross-flow within the slit), defined as \hat{c} .

Comparison of the SRoOTES, DRoOTES and Slit trailing edges

40 [0062] Figure 9 illustrates a comparison of the trailing edges at various freestream velocities at amplitude of $H = 15$ mm. The best performer based on the maximum Δ PWL was the slit trailing edge case with reduction up to 4.8 dB in comparison to the baseline trailing edge. Alternatively, the DRoOTES produced significant broadband noise reduction up to 4.5 dB across a significant greater frequency range, 100 Hz $< f < 4$ kHz, at all freestream velocities in comparison to the slit trailing edge. This compares to the slit achieving reduction across a small frequency range of 100 $< f < 1.5$ kHz based on the freestream velocity. The worst case is the SRoOTES which produced the least noise reduction at the low to mid frequency. However, at high frequency the SRoOTES produced the least noise increase in comparison to DRoTES and slit trailing edge. At high frequency, the slit trailing edge produced the greatest noise increase, followed by DRoTES.

45 [0063] Figure 10 presents a comparison of the trailing edges at various freestream velocities at amplitude of $H = 30$ mm. The best performer was the DRoOTES with the largest noise reduction up to 7.2 dB. Furthermore, the DRoOTES produced the smallest noise increase and noise reduction across all frequency ranges in comparison to baseline. The SRoOTES produced similar noise reduction across the low to mid frequency range, however, it produced the greatest noise increase. The slit trailing edge produced significant reduction at specific frequencies at the low to mid frequency range and produced similar reductions to the DRoTES at high frequency.

50 [0064] In conclusion, the results shown in Figure 9 and Figure 10 clearly demonstrates the following:

55 1. DRoTES offers significant benefits at improving noise performance amongst all trailing edge cases, where DRoTES achieve noise reduction up to 4.5 dB and 7.2 dB for $H = 15$ mm and $H = 30$ mm respectively.
 2. The optimization of geometry parameter, depending on the flow conditions, offer significant benefits in improving noise performance for all the trailing edge cases.

Claims

1. A method for forming an add-on component for an aerofoil having a leading edge and a trailing edge, said component being formed in order to reduce the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of the aerofoil over the trailing edge of the component at a freestream velocity U_∞ , the method including the steps of:

- 5 (a) selecting a frequency f_{peak} of sound that is to be reduced;
- 10 (b) selecting a freestream velocity U_∞ of air;
- (c) providing a component having a joining edge for joining to a trailing edge of an aerofoil and a trailing edge opposite said joining edge;
- 15 (d) forming the trailing edge of the component into a plurality of pairs of peaks, each of said pairs having a first trough, a first peak, a second trough, a second peak, which is a greater distance from the joining edge than the first peak, and a third trough, wherein the first trough is on one side of the first peak, the second trough is between the first and second peak, and the third trough is on the other side of the second peak to the second trough;
- (e) wherein the first and third troughs of each pair of peaks lie substantially on a first axis, the second troughs of each pair of peaks lie substantially on a second axis, and the second peaks of each pair of peaks lie on a third axis;

20 (f) and **characterised in that** the component is formed according to the formula:
$$h' = \frac{\hat{c} \cdot U_\infty \cdot \kappa}{2f_{peak}}$$
 where \hat{c} is from 0.4 to 0.8 and

$$\kappa = \left(\frac{h''}{h'} \right)^{0.4}$$

25 where h' is the shortest distance between the first axis and the second axis, h'' is the shortest distance between the 2nd and 3rd axis, f_{peak} is the frequency of sound to be reduced and U_∞ is the freestream velocity in the flow direction of air flowing over the trailing edge of the component.

- 30 2. A method as claimed in claim 1, wherein $h'=h''$.
- 35 3. A method as claimed in claim 1 or 2, wherein the shortest distance from the first peak to the first axis is identical for each of said pair of peaks within the plurality of pairs.
- 40 4. A method as claimed in any preceding claim, wherein the third trough of first pair of peaks is the first trough of a second pair of peaks which is adjacent to said first pair of peaks.
- 5. A method for reducing the amplitude of sound produced at frequency f_{peak} when air flows in a flow direction from the leading edge of an aerofoil over the trailing edge of an aerofoil at freestream velocity U_∞ , the method including the steps of:
 - 45 (a) forming an add-on component for an aerofoil according to a method as claimed in any of claims 1 to 4 and
 - (b) attaching said component to said aerofoil.
- 6. A method as claimed in claim 5, including the steps of forming a plurality of components and attaching said plurality of components to said aerofoil.
- 55 7. A method as claimed in claim 6, wherein three components are formed and attached to said aerofoil, the first component proximate the tip of the aerofoil, the second component proximate the middle of the aerofoil and the third component proximate the other end of the aerofoil to the tip.
- 8. A method as claimed in claim 6 or 7, wherein said components are identical.
- 5. A method as claimed in claim 6 or 7, wherein said components have different values of h' and/or h'' .

Patentansprüche

1. Verfahren zum Bilden einer Zusatzkomponente für eine Tragfläche mit einer Vorderkante und einer Hinterkante, wobei die Komponente gebildet wird, um die Amplitude des Schalls zu verringern, der mit der Frequenz f_{peak} erzeugt wird, wenn Luft in einer Strömungsrichtung von der Vorderkante der Tragfläche über die Hinterkante der Komponente mit einer Freistromgeschwindigkeit U_∞ strömt, wobei das Verfahren die folgenden Schritte umfasst:

- 5 (a) Auswählen einer Frequenz f_{peak} des Schalls, der verringert werden soll;
- 10 (b) Auswählen einer Freistromgeschwindigkeit U_∞ der Luft;
- (c) Bereitstellen einer Komponente mit einer Verbindungskante zum Verbinden mit einer Hinterkante einer Tragfläche und einer Hinterkante gegenüber der Verbindungskante;
- 15 (d) der Hinterkante der Komponente die Form mehrerer Paare von Erhebungen geben, wobei jedes der Paare eine erste Senke, eine erste Erhebung, eine zweite Senke, eine zweite Erhebung, die einen größeren Abstand von der Verbindungskante hat als die erste Erhebung, und eine dritte Senke aufweist, wobei die erste Senke auf einer Seite der ersten Erhebung liegt, die zweite Senke zwischen der ersten und der zweiten Erhebung liegt und die dritte Senke auf der anderen Seite der zweiten Erhebung als die zweite Senke liegt,
- 20 (e) wobei die ersten und dritten Senken jedes Paares von Erhebungen im Wesentlichen auf einer ersten Achse liegen, die zweiten Senken jedes Paares von Erhebungen im Wesentlichen auf einer zweiten Achse liegen, und die zweiten Erhebungen jedes Paares von Erhebungen auf einer dritten Achse liegen,

25 (f) und dadurch gekennzeichnet, dass die Komponente gemäß der Formel:

$$h' = \frac{c \cdot U_\infty \cdot \kappa}{2 f_{peak}}$$

worin von 0,4 bis 0,8 \hat{c} ist, und

$$\kappa = \left(\frac{h''}{h'} \right)^{0.4}$$

wobei h' der kürzeste Abstand zwischen der ersten Achse und der zweiten Achse ist, h'' der kürzeste Abstand zwischen der zweiten und der dritten Achse ist, f_{peak} die Frequenz des zu verringernden Schalls ist, und U_∞ die Freistromgeschwindigkeit in Strömungsrichtung der über die Hinterkante der Komponente strömenden Luft ist.

30 2. Verfahren gemäß Anspruch 1, wobei $h' = h''$.

35 3. Verfahren gemäß Anspruch 1 oder 2, wobei der kürzeste Abstand zwischen der ersten Erhebung und der ersten Achse für jedes Paar von Erhebungen innerhalb der mehreren Paare identisch ist.

40 4. Verfahren gemäß einem der vorangehenden Ansprüche, wobei die dritte Senke des ersten Paars von Erhebungen die erste Senke eines zweiten Paars von Erhebungen ist, das an das erste Paar von Erhebungen angrenzt.

45 5. Verfahren zum Verringern der Amplitude des Schalls, der mit der Frequenz f_{peak} erzeugt wird, wenn Luft in einer Strömungsrichtung von der Vorderkante einer Tragfläche über die Hinterkante einer Tragfläche mit der Freistromgeschwindigkeit U_∞ strömt, wobei das Verfahren die folgenden Schritte umfasst:

- (a) Bilden einer Zusatzkomponente für eine Tragfläche gemäß einem Verfahren gemäß einem der Ansprüche 1 bis 4 und
- 45 (b) Anbringen der Komponente an der Tragfläche.

50 6. Verfahren gemäß Anspruch 5, umfassend die Schritte des Ausbildens einer Mehrzahl von Bauteilen und des Anbringens der mehreren Bauteile an der Tragfläche.

55 7. Verfahren gemäß Anspruch 6, wobei drei Komponenten gebildet und an der Tragfläche angebracht werden, die erste Komponente in der Nähe der Spitze der Tragfläche, die zweite Komponente in der Nähe der Mitte der Tragfläche und die dritte Komponente in der Nähe des anderen Endes der Tragfläche als der Spitze.

8. Verfahren gemäß Anspruch 6 oder 7, wobei die Komponenten identisch sind.

55 9. Verfahren gemäß Anspruch 6 oder 7, wobei die Komponenten unterschiedliche Werte von h' und/oder h'' aufweisen.

Revendications

1. - Procédé de formation d'un composant rapporté pour une surface portante ayant un bord d'attaque et un bord de fuite, ledit composant étant formé afin de réduire l'amplitude du son produit à une fréquence f_{peak} lorsque de l'air 5 s'écoule dans une direction d'écoulement à partir du bord d'attaque de la surface portante sur le bord de fuite du composant à une vitesse d'écoulement libre LL, le procédé comprenant les étapes :

- (a) choisir une fréquence f_{peak} du son à réduire ;
- (b) sélectionner une vitesse d'écoulement libre U_∞ de l'air ;
- 10 (c) disposer un composant ayant un bord d'assemblage à assembler à un bord de fuite d'une surface portante et un bord de fuite opposé audit bord d'assemblage ;
- (d) former le bord de fuite du composant en une pluralité de paires de pics, chacune desdites paires ayant un premier creux, un premier pic, un deuxième creux, un deuxième pic, qui est plus éloigné du bord d'assemblage que le premier pic, et un troisième creux, le premier creux se trouvant sur un côté du premier pic, le deuxième creux se trouvant entre les premier et deuxième pics, et le troisième creux se trouvant sur l'autre côté du deuxième pic par rapport au deuxième creux ;
- 15 (e) les premier et troisième creux de chaque paire de pics se situant sensiblement sur un premier axe, les deuxième creux de chaque paire de pics se situant sensiblement sur un deuxième axe, et les deuxième pics de chaque paire de pics se situant sur un troisième axe ;

20 (f) et caractérisé par le fait que le composant est formé selon la formule :
$$h' = \frac{\hat{c} \cdot U_\infty \cdot \kappa}{2f_{peak}}$$
, où \hat{c} est compris

25 entre 0,4 et 0,8 et $\kappa = \left(\frac{h''}{h'}\right)^{0.4}$ où h' est la distance la plus courte entre le premier et le deuxième axe, h'' est la distance la plus courte entre les 2^{ème} et 3^{ème} axes, f_{peak} est la fréquence du son à réduire et U_∞ est la vitesse d'écoulement libre dans la direction d'écoulement de l'air s'écoulant sur le bord de fuite du composant.

2. - Procédé selon la revendication 1, dans lequel $h'=h''$.

30 3. - Procédé selon la revendication 1 ou 2, dans lequel la distance la plus courte du premier pic au premier axe est identique pour chacune de ladite paire de pics de la pluralité de paires.

35 4. - Procédé selon l'une quelconque des revendications précédentes, dans lequel le troisième creux de la première paire de pics est le premier creux d'une deuxième paire de pics qui est adjacente à ladite première paire de pics.

40 5. - Procédé de réduction de l'amplitude du son produit à une fréquence f_{peak} lorsque de l'air s'écoule dans une direction d'écoulement à partir du bord d'attaque d'une surface portante sur le bord de fuite d'une surface portante à une vitesse d'écoulement libre LL, le procédé comprenant les étapes :

- (a) former un composant rapporté pour une surface portante selon un procédé selon l'une quelconque des revendications 1 à 4 : et
- (b) fixer ledit composant à ladite surface portante.

45 6. - Procédé selon la revendication 5, comprenant les étapes de formation d'une pluralité de composants et de fixation de ladite pluralité de composants à ladite surface portante.

50 7. - Procédé selon la revendication 6, dans lequel trois composants sont formés et fixés à ladite surface portante, le premier composant à proximité de la pointe de la surface portante, le deuxième composant à proximité du milieu de la surface portante, et le troisième composant à proximité de l'autre extrémité de la surface portante par rapport à la pointe.

8. - Procédé selon la revendication 6 ou 7, dans lequel les composants sont identiques.

55 9. - Procédé selon la revendication 6 ou 7, dans lequel lesdits composants ont des valeurs différentes de h' et/ou h'' .

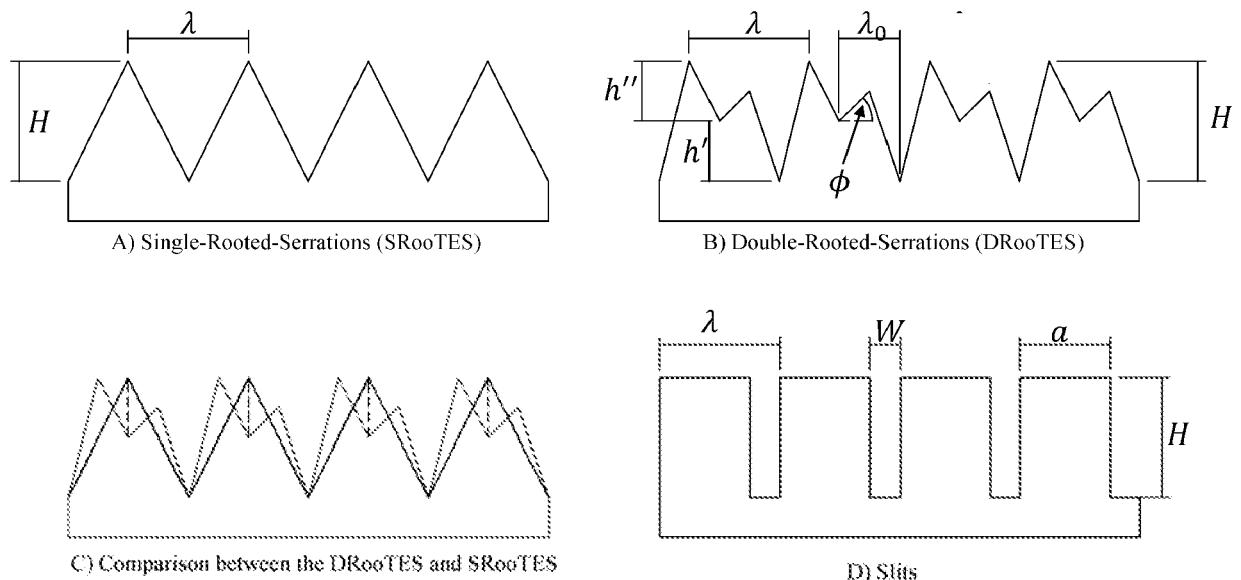


Fig. 1A

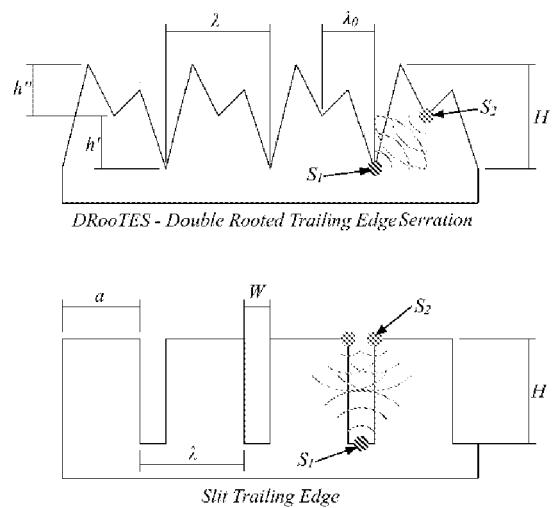


Fig. 1B

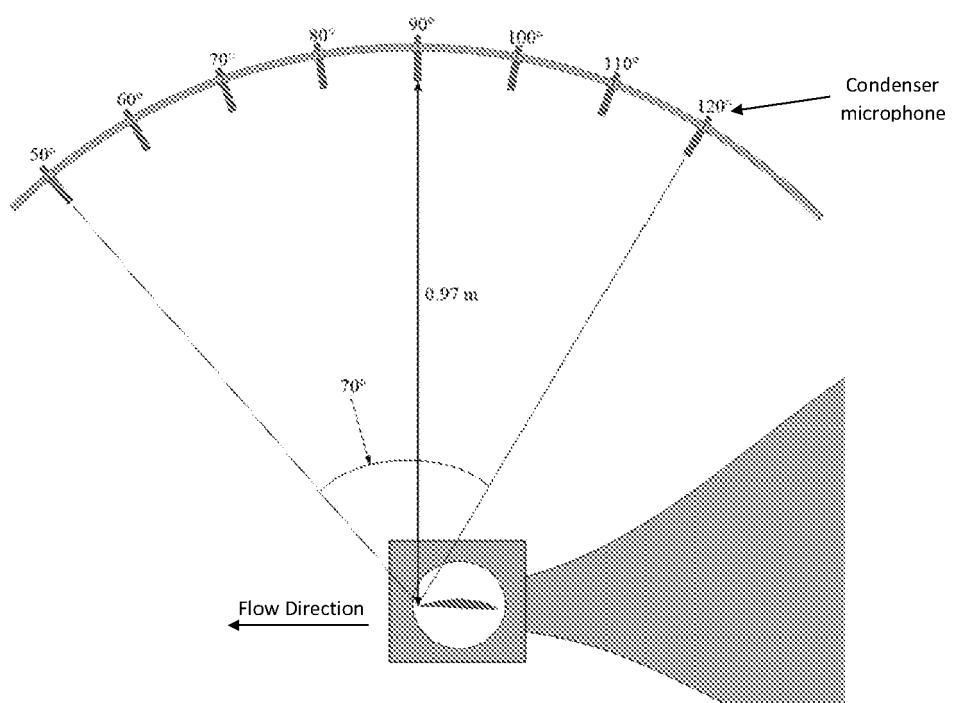


Fig. 1C

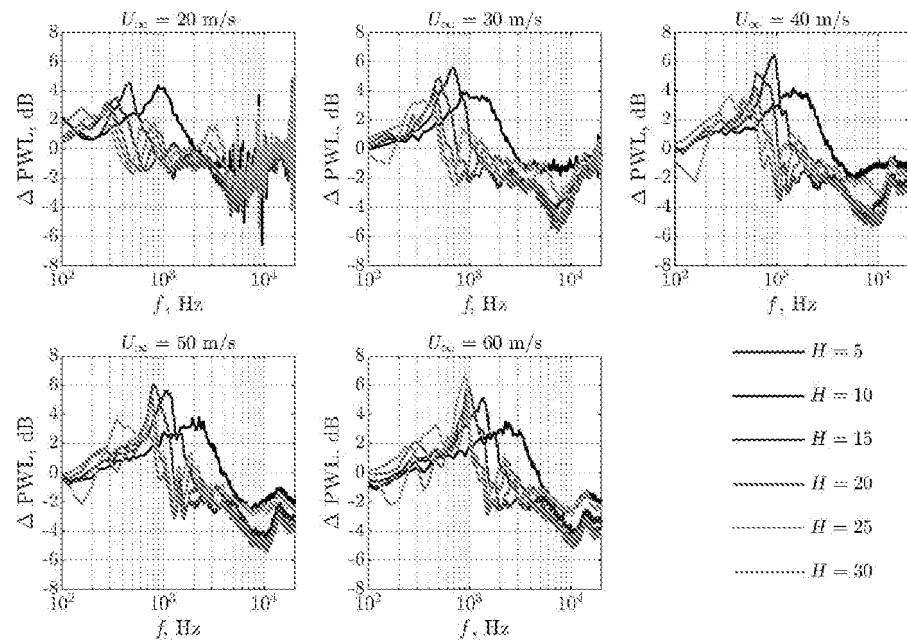


Fig. 2

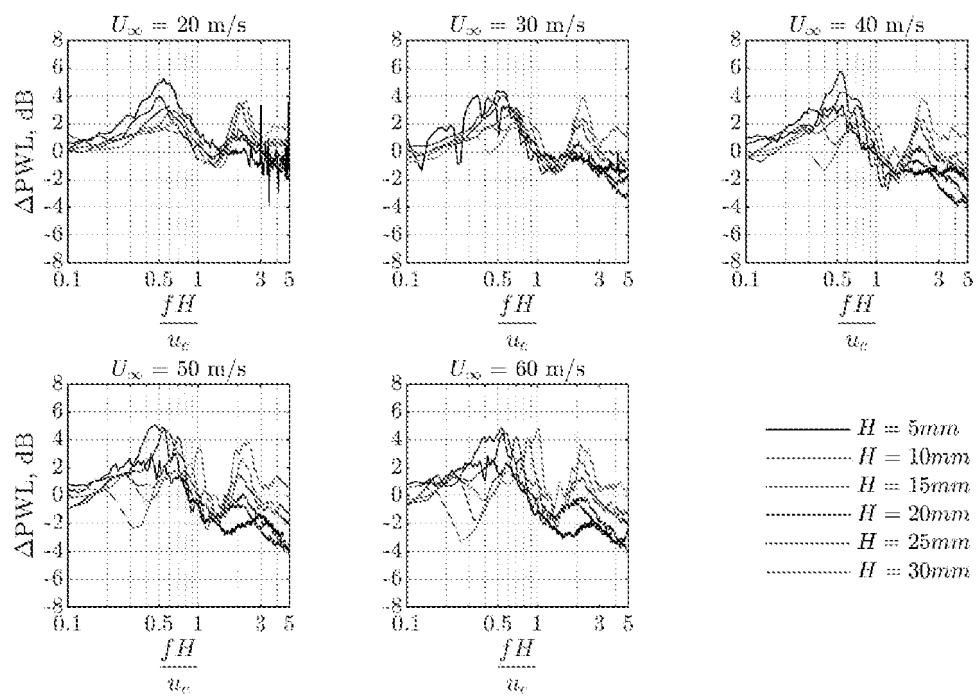


Fig. 3

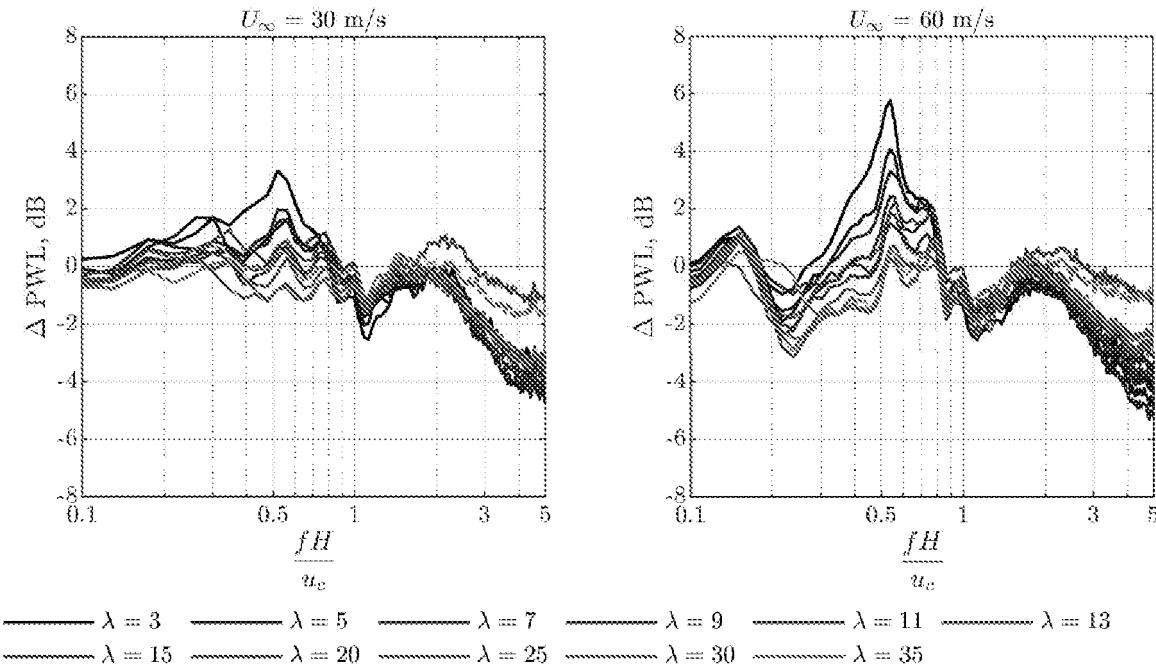


Fig. 4

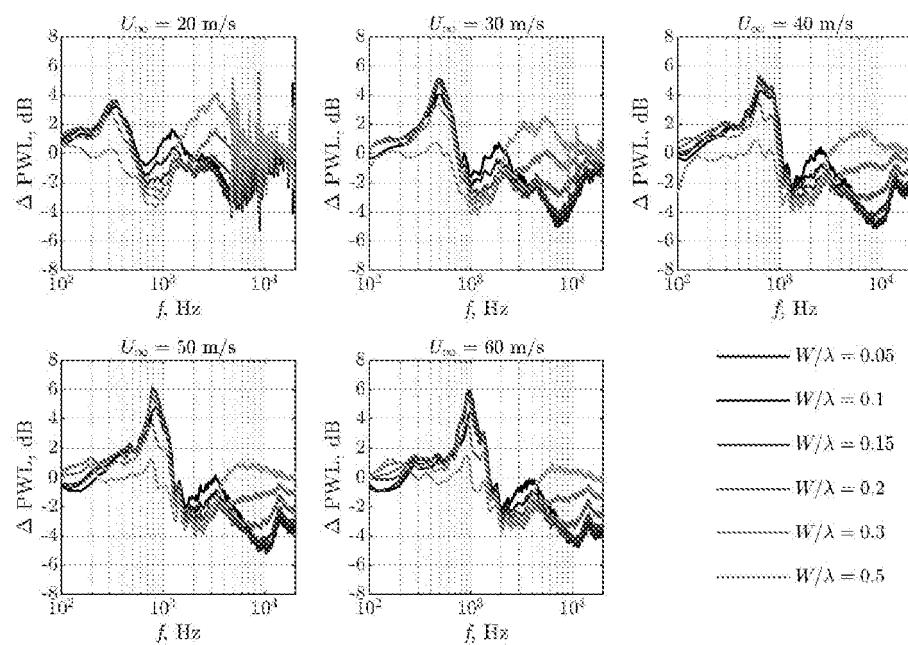


Fig. 5

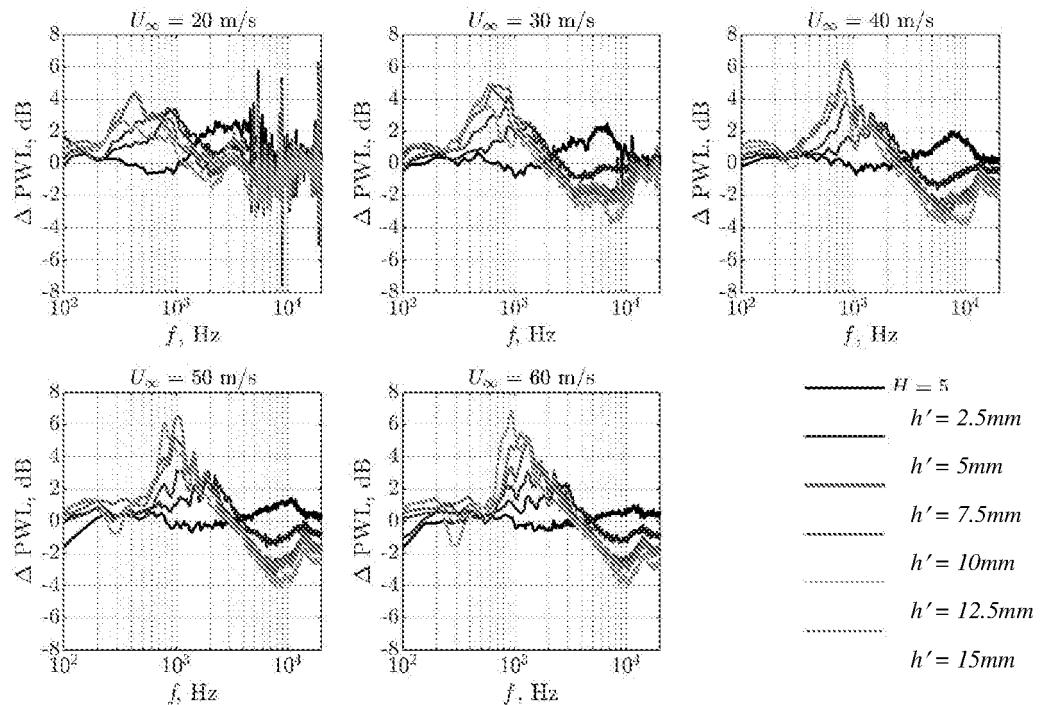


Fig. 6

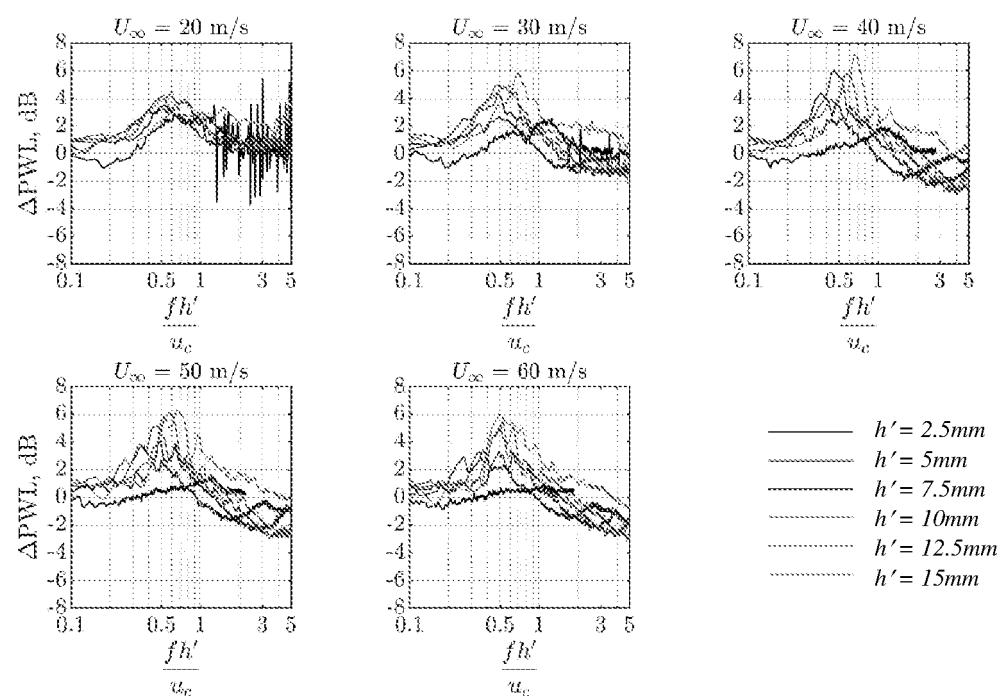


Fig. 7

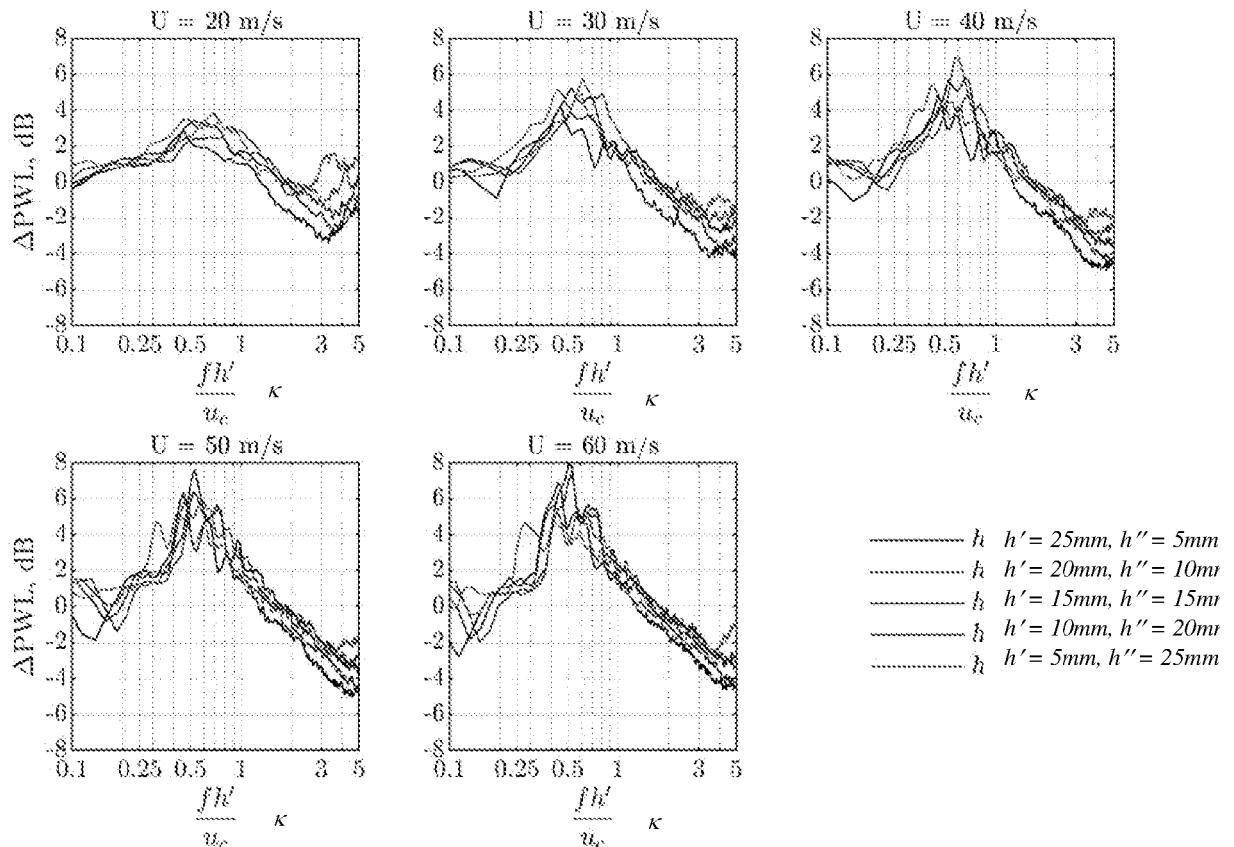


Fig. 8

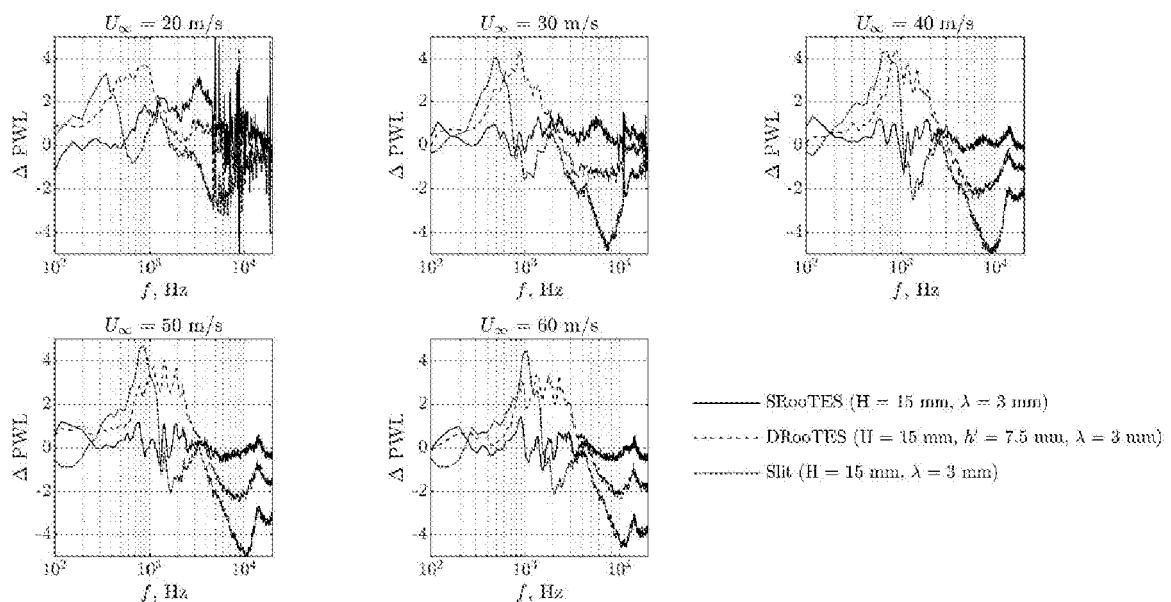


Fig. 9

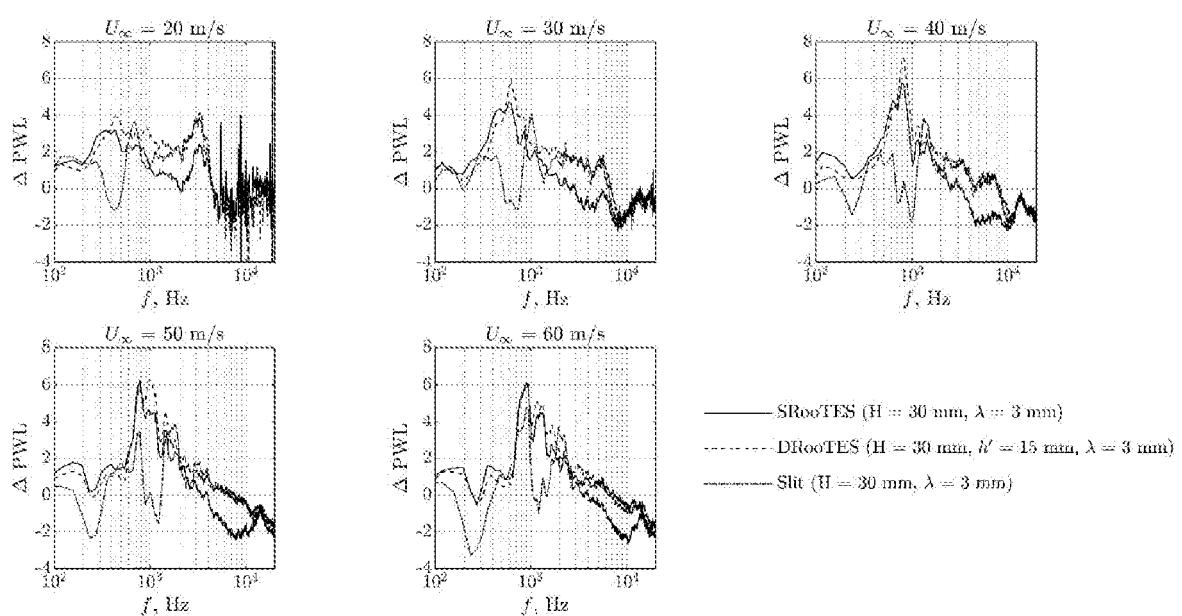


Figure 10

REFERENCES CITED IN THE DESCRIPTION

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