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(54) HINGE ASSEMBLY FOR CONTROLLED FOLDING OF AN ELECTRONIC DEVICE

SCHARNIERANORDNUNG ZUM KONTROLLIERTEN ZUSAMMENKLAPPEN EINER ELEKTRONISCHEN VORRICHTUNG

ENSEMBLE CHARNIÈRE POUR LE PLIAGE COMMANDÉ D'UN DISPOSITIF ÉLECTRONIQUE

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DescriptionTECHNICAL FIELD

[0001] The disclosure relates to a hinge assembly for an electronic device, the hinge assembly being moveable between an unfolded position and at least a first folded end position, and comprising at least one linear actuator.

BACKGROUND

[0002] The size of electronic devices, such as tablets and mobile phones, is an important consideration when designing electronic devices. The user oftentimes requests the outer dimensions of the device to be as small as possible while still providing a display which is as large as possible.

[0003] This problem may be solved, e.g., by means of a foldable electronic device comprising one or several support bodies, e.g. interconnected by means of hinges, covered by a display. The support body/bodies and the display can be folded together to provide an as small electronic device as possible, and unfolded to provide an as large display as possible.

[0004] However, as the electronic device is folded, the display and/or the support body/bodies will stretch on one side of the neutral axis and compress on the other side of the neutral axis. The neutral axis is the axis along which the display or the housing remains unchanged as it is folded, i.e. it neither stretches nor compresses.

[0005] One solution is to provide the electronic device with a resilient connection between the display and the support body, the resilient connection taking up any stretching and compression. However, the resilient connection and the configuration of the hinges still affects the appearance of the display, leaving the surface of the display uneven.

[0006] Document US 10 209 743 B1 relates to a flexible display device which includes a base support, a flexible display, and at least one positioning mechanism. The base support includes a first support plate extending lengthwise to terminate at a left end and a right end, a second support plate extending lengthwise to terminate at a left end and a right end, and a support rib unit including a plurality of support ribs which are juxtaposed to each other, and which are configured to be associated with each other to permit the support rib unit to be structurally flexible. The support rib unit is flanked by and configured to loosely interconnect the first and second support plates so as to permit the base support to be structurally flexible between a normal position and a bent position. Each of the support ribs extends lengthwise to terminate at a left end and a right end. The flexible display is supported by the base support to be bendable with the base support. The positioning mechanism is disposed leftward or rightward of the base support, and which includes a first mount, a second mount, a plurality of hinge bodies, a leaf spring unit, a sliding block, and a

spring-loaded unit. The first mount is mounted to a corresponding one of the left and right ends of the first support plate to permit the first mount to move with the first support plate, and includes a camming wall with a camming surface, and an abutment wall that is spaced apart from the camming wall to define a first cavity. The second mount is mounted to a corresponding one of the left and right ends of the second support plate to permit the second mount to move with the second support plate, and defines therein a second cavity. The hinge bodies are chained to each other along a chain line. Each of the hinge bodies has a through bore and is configured to be in interference engagement with a corresponding one of the left and right ends of the respective support rib so as to permit the hinge bodies to be structurally flexible with the support rib unit. The through bores of the hinge bodies are arranged in tandem along the chain line. Each of the hinge bodies has a cover wall, and a base wall which is spaced apart from the cover wall to define the through bore, and which has a floor segment and an elevated cantilever segment. The base wall is configured to permit the elevated cantilever segment of one of the hinge bodies to overlie and to slidably engage with the floor segment of an adjacent one of the hinge bodies. The leaf spring unit extends along the chain line to pass through the through bores of the hinge bodies to terminate at a first spring end which is to be disposed in the first cavity, and a second spring end secured in the second cavity. The sliding block is fitted in the first cavity, and is slidable from a distal position corresponding to the normal position, to a proximate position corresponding to the bent position. The sliding block has a retaining segment distal from the second mount, and a securing segment which is proximate to the second mount, and which is configured to secure the first spring end thereto. The retaining segment has a first segment wall and a second segment wall. The first segment wall confronts the camming wall, and has a first opening. The second segment wall confronts the abutment wall, and is spaced apart from the first segment wall to define an accommodation space. The spring-loaded unit is disposed in the accommodation space, and includes a pin stem and a biasing member. The pin stem is disposed in the accommodation space, and extends through the first opening to terminate at a first stem end. The biasing member is disposed to bias the first stem end into frictional engagement with the camming surface of the camming wall such that once a force applied to move the sliding block against a biasing force of the biasing member between the distal and proximate positions ceases to be applied, the sliding block is kept retained between the distal and proximate positions.

SUMMARY

[0007] It is an object to provide an improved foldable electronic device. The foregoing and other objects are achieved by the features of the independent claim.

Further implementation forms are apparent from the dependent claims, the description, and the figures. Thus, the present invention is set out by the set of appended claims.

[0008] According to a first aspect, there is provided a hinge assembly for an electronic device, the hinge assembly being moveable between an unfolded position and at least a first folded end position, the hinge assembly comprising a row of interconnected and abutting hinge blades and at least one linear actuator, the hinge blades being aligned in a common plane when the hinge assembly is in the unfolded position, each hinge blade being rotated relative to neighboring hinge blades around a first hinge assembly rotation axis, when the hinge assembly is moved to the first folded end position, the linear actuator comprising a rotation shaft and a plurality of linear drive arrangements having different lengths, the rotation shaft extending in parallel with the first hinge assembly rotation axis and comprising sections having different diameters, a first end of each linear drive arrangement being interconnected with a section of the rotation shaft having one diameter, a second, opposite end of each linear drive arrangement being connected to one hinge blade, an actuator axis extending between the first and second ends of each linear drive arrangement and perpendicular to the first hinge assembly rotation axis, wherein actuation of the linear actuator along the actuator axis urges each hinge blade to rotate relative neighboring hinge blades around the first hinge assembly rotation axis.

[0009] Such a solution allows for a hinge assembly which has as small outer dimensions as possible, while having a range of motion which allows, e.g., two components interconnected by the hinge assembly, such as two electronic device frame sections, to be moved between an unfolded position, in which the frame sections extend to provide a maximum electronic device width, and a folded position in which the two sections are superimposed onto each other such that they extend to provide only a minimum electronic device width. Furthermore, the solution provides support to any components which extend the two interconnected components across the hinge assembly. Furthermore, each hinge blade has its own manufacturing and rotation tolerance, however, with this solution the different tolerances do not stack up and hence, the impact on the display is minimized.

[0010] In a possible implementation form of the first aspect, rotation of the neighboring hinge blades is initiated successively in response to the differing diameters of the rotation shaft. Such a solution allows rotation of neighboring hinge blades to be initiated successively in response to the differing diameters of the linear drive arrangements. The smaller the diameter, the less the linear drive arrangement will move and the less the hinge blade will rotate. Hence, the desired turning profile is set for each hinge blade.

[0011] In a further possible implementation form of the first aspect, the hinge assembly comprises at least a first linear actuator and a second linear actuator, the first

linear actuator comprising a first rotation shaft and plurality of first linear drive arrangements, the second linear actuator comprising a second rotation shaft and plurality of second linear drive arrangements, the first rotation shaft and the second rotation shaft extending in parallel, the first linear drive arrangements and the second linear drive arrangements extending in parallel. This allows the smallest diameter to be increased for the hinge blades which rotate the least.

[0012] In a further possible implementation form of the first aspect, one of the first linear drive arrangements and one of the second linear drive arrangements are connected to the same hinge blade, synchronizing the actuation of the first linear actuator and the second linear actuator, keeping the movement of all rotation shafts and hinge blades synchronized.

[0013] In a further possible implementation form of the first aspect, a first dimension of a first outer surface of the hinge assembly is larger than a corresponding second dimension of a second outer surface of the hinge assembly when the hinge assembly is in the first folded end position, the first linear actuator and/or the second linear actuator being actuated by a difference between the first dimension and the second dimension. This allows for a hinge assembly which has as small outer dimensions as possible, while having a range of motion which allows, e.g., the first frame section and the second frame section to be moved between the unfolded position, in which the bodies extend to provide a maximum electronic device width, and a folded position in which the two bodies are superimposed onto each other such that they extend to provide only a minimum electronic device width.

[0014] In a further possible implementation form of the first aspect, the linear drive arrangement comprises a chain or a wire.

[0015] In a further possible implementation form of the first aspect, the hinge assembly comprises a neutral axis, a first end of the linear drive arrangement engaging the rotation shaft, and a second end of the linear drive arrangement engaging a first location and a second location of an individual hinge blade, the first location and the second location being located on opposite sides of, and with equidistant spacing from, the neutral axis, the linear drive arrangement extending through any hinge blades located in a first area between the individual hinge blade and the rotation shaft, the linear drive arrangement comprising a first section and a second section extending on opposite sides of, and with equidistant spacing from, the neutral axis, a first rotation of the rotation shaft rotating the linear drive arrangement in a first direction, and a second rotation of the rotation shaft rotating the linear drive arrangement in a second direction. As a result, the movement generated by the linear actuator is synchronized on both sides of the neutral axis.

[0016] In a further possible implementation form of the first aspect, the linear drive arrangement comprises a wire partially wound around the rotation shaft, providing a secure, simple, and reliable linear actuation.

[0017] In a further possible implementation form of the first aspect, the hinge assembly comprises a neutral axis, and the linear drive arrangement comprises a first section and a second section extending through an individual hinge blade and engaging the rotation shaft at a first end of the linear drive arrangement, the first section and the second section extending partially on opposite sides of, and with equidistant spacing from, the neutral axis, the first section extending in a first area between the first end and the individual hinge blade, on a first side of the neutral axis, and the second section extending in the first area on a second side of the neutral axis, the first section and the second section furthermore engaging the individual hinge blade by extending through the individual hinge blade such that the first section extends from the first side of the neutral axis to the second side of the neutral axis, and the second section extends from the second side of the neutral axis to the first side of the neutral axis, the first section extending, in a second area between the individual hinge blade and a second end of the linear drive arrangement, on the first side of the neutral axis and the second section extending, in the second area, on the first side of the neutral axis, allowing any hinge blades located in the second area to be pivoted in a first direction around the first hinge assembly rotation axis, and, simultaneously, allowing any hinge blades located in the first area to be pivoted in an opposite, second direction around a second hinge assembly rotation axis extending in parallel with the first hinge assembly rotation axis. This facilitates a hinge assembly which has an as small width as possible while still allowing the hinge to fold the components, which the hinge assembly interconnects, completely together.

[0018] In a further possible implementation form of the first aspect, the first section and the second section furthermore engage a second individual hinge blade by extending through the second individual hinge blade such that the first section extends back from the second side of the neutral axis to the first side of the neutral axis, and the second section extends back from the first side of the neutral axis to the second side of the neutral axis, the first section extending, in a third area between the second individual hinge blade and the second end of the linear drive arrangement, on the first side of the neutral axis, and the second section extending, in the third area, on the second side of the neutral axis, allowing any hinge blades located in the third area to be pivoted in the opposite, second direction around a third hinge assembly rotation axis extending in parallel with the first hinge assembly rotation axis.

[0019] According to a second aspect, there is provided an electronic device comprising a first frame section, a second frame section, a display connected to at least one of the first frame section and the second frame section, and a hinge assembly according to the above interconnecting the first frame section and the second frame section such that the first frame section and the second frame section are pivotable, relative each other, between

an unfolded position and a first folded end position, the first frame section and the second frame section being aligned in a common plane when in the unfolded position, the second frame section being superimposed on the first frame section when in the first folded end position. This facilitates an electronic device having a range of motion which allows, e.g., two components interconnected by the hinge assembly, such as two electronic device frame sections, to be moved between an unfolded position, in which the frame sections extend to provide a maximum electronic device width, and a folded position in which the two sections are superimposed onto each other such that they extend to provide only a minimum electronic device width. Furthermore, each hinge blade of the hinge assembly has its own manufacturing and rotation tolerances, which tolerances do not stack up leaving the impact on the display minimal.

[0020] In a possible implementation form of the second aspect, the hinge assembly interconnects the first frame section and the second frame section such that the first frame section and the second frame section are pivotable, relative each other, between an unfolded position and a second folded end position, the first frame section being superimposed on the second frame section when in the second folded end position.

[0021] This and other aspects will be apparent from and the embodiments described below.

BRIEF DESCRIPTION OF THE DRAWINGS

[0022] In the following detailed portion of the present disclosure, the aspects, embodiments and implementations will be explained in more detail with reference to the example embodiments shown in the drawings, in which:

Fig. 1a shows a simplified perspective view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in a folded position;

Fig. 1b shows a schematic side view of the embodiment of Fig. 1a, wherein the hinge assembly is in an unfolded position as well as in both folded end positions;

Fig. 1c shows a schematic side view of a hinge assembly in accordance with a further embodiment of the present disclosure, wherein the hinge assembly is in an unfolded position and in a folded end position;

Fig. 2 shows a cross-sectional side view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in a folded position;

Fig. 3 shows a partial perspective view of a hinge assembly in accordance with one embodiment of the

present disclosure, wherein the hinge assembly is in a folded position;

Fig. 4 shows a more detailed view of the embodiment of Fig. 3;

Fig. 5 shows a perspective view of a linear actuator of a hinge assembly in accordance with one embodiment of the present disclosure;

Fig. 6 shows a partial perspective view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in a folded position;

Fig. 7 shows a cross-sectional side view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in a folded position;

Fig. 8 shows a perspective view of a rotation shaft of a hinge assembly in accordance with one embodiment of the present disclosure;

Fig. 9a shows a partial perspective view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in a folded end position;

Fig. 9b shows a partial side view of a hinge assembly in accordance with one embodiment of the present disclosure, wherein the hinge assembly is in an unfolded position;

Fig. 9c shows a partial side view of the embodiment of Fig. 9b, wherein the hinge assembly is in a folded end position;

Fig. 10a shows a cross-sectional side view of an electronic device in accordance with one embodiment of the present disclosure, wherein the electronic device is in an unfolded position as well as in both folded end positions;

Fig. 10b shows a cross-sectional side view of an electronic device in accordance with one embodiment of the present disclosure, wherein the electronic device is in an unfolded position as well as in both folded end positions.

DETAILED DESCRIPTION

[0023] Figs. 10a and 10b show an electronic device 14 comprising a first frame section 4, a second frame section 5, and a display 2 connected to at least one of the first frame section 4 and the second frame section 5. A hinge assembly 1 interconnects the first frame section 4 and the second frame section 5 such that the first frame section 4

and the second frame section 5 are pivotable, relative each other, between an unfolded position P1 and at least a first folded end position P2a around the first hinge assembly rotation axis A1a. In a further embodiment, the first frame section 4 and the second frame section 5 are also pivotable, relative each other, between an unfolded position P1 and a second folded end position P2b. As the hinge assembly 1 is folded, the electronic device 14 is also folded from an unfolded position to a folded end position.

[0024] The first frame section 4 and the second frame section 5 are aligned in a common plane when in the unfolded position P1, as shown in the center drawings of Figs. 10a and 10b.

[0025] Furthermore, the second frame section 5 is superimposed on top of the first frame section 4 when in the first folded end position P2a, as shown in the top drawings of Figs. 10a and 10b. In a further embodiment, the first frame section 4 is superimposed on top of the second frame section 5 when in the second folded end position P2b, as shown in the bottom drawings of Figs. 10a and 10b.

[0026] Fig. 1a shows a simplified perspective view of an embodiment of the hinge assembly 1. The hinge assembly 1 is moveable between the unfolded position P1 and at least one folded end position, preferably between the unfolded position P1, a first folded end position P2a, and a second folded end position P2b.

[0027] The hinge assembly 1 comprises a row of interconnected and abutting hinge blades 9 and at least one linear actuator 6, 7. The hinge blades 9 are at least partially tapered and interconnected by means of an elongated connection element 10 extending along the actuator axis A2, as shown in Figs. 1b and 9b. The hinge blades 9 may be tapered in one direction, as shown in Fig. 1c, or in two directions, as shown in Fig. 1b. One-directional tapering allows the hinge assembly 1 to fold in only one direction, e.g. to first folded end position P2a, while bi-directional tapering allows the hinge assembly 1 to fold in two directions, i.e. to first folded end position P2a as well as second folded end position P2b.

[0028] Each linear actuator 6, 7 comprises a rotation shaft 12 and a plurality of linear drive arrangements 13 having different lengths 10, as shown in Figs. 2 to 6. The rotation shaft 12 extends in parallel with the first hinge assembly rotation axis A1a and comprises a plurality of sections 3 having different diameters 11, as shown in Fig. 8. The rotation shaft 12 may extend within the first frame section 4 or the second frame section 5, for ease of reading the rotation shaft 12 is shown as located within the second frame section 5 in the Figs. and in the text below.

[0029] A first end 13a of each linear drive arrangement 13 is interconnected with one section 3 of the rotation shaft 12 having one diameter 11, and a second, opposite end of each linear drive arrangement 13 is connected to one hinge blade 9, as shown in Fig. 4. The actuator axis A2 extends between the first and second ends 13b of the

linear drive arrangement 13 and perpendicular to the first hinge assembly rotation axis A1a. The connection may be releasable or fixed using, e.g., adhesive or fasteners such as screws.

[0030] Since the smallest diameter 11 on the rotation shaft 12 might be too small for the hinge blades 9 which rotate the least, i.e. the hinge blades 9 located nearest to the second frame section 5, and hence the rotation shaft 12, the smallest diameter 11 may be increased by providing two or more linear actuators 6, 7, i.e. a first rotation shaft 12a connected to a first plurality of linear drive arrangements 13 and a second rotation shaft 12b connected to a second plurality of linear drive arrangements 13. In order to keep all rotation shafts and hinge blades synchronized, one linear drive arrangement 13 of the first linear actuator 6 and one linear drive arrangement 13 of the second linear actuator 7 are connected to the same hinge blade 9.

[0031] In one embodiment, the first rotation shaft 12a and the second rotation shaft 12b extend in parallel, and the first linear drive arrangements 13 and the second linear drive arrangements 13 extend in parallel, as indicated by Fig. 6.

[0032] The hinge blades 9 are aligned in a common plane when the hinge assembly 1 is in the unfolded position P1, and each hinge blade 9 is rotated relative neighboring hinge blades 9 around the first hinge assembly rotation axis A1a, when the hinge assembly 1 is moved to the first folded end position P2a or to the second folded end position P2b.

[0033] Actuation of the linear actuator 6, 7 along the actuator axis A2 may urge each hinge blade 9 to rotate relative neighboring hinge blades 9 around the first hinge assembly rotation axis A1a. Rotation of the neighboring hinge blades 9 is initiated successively in response to the differing diameters 11 of the linear drive arrangements 13. The smaller the diameter, the less the linear drive arrangement 13 will move, and the less the hinge blade 9 will rotate. Hence, the desired turning profile is set for each hinge blade 9.

[0034] In one embodiment, pivoting of the first frame section 4 and/or the second frame section 5 around the first hinge assembly rotation axis A1a actuates the first linear actuator 6 and the second linear actuator 7, such that one of the display 2 and the second frame section 5 are urged to move, in relation to the hinge assembly 1, along the actuator axis A2. Movement of the display 2 in relation to the hinge assembly 1 is shown in Fig. 10a. Movement of the second frame section 5 in relation to the hinge assembly 1 is shown in Fig. 10b.

[0035] In a further embodiment the hinge assembly 1 comprises a foldable back cover, the linear actuator 6 being connected to the display and the linear actuator 7 being connected to the back cover (not shown). In such an embodiment, the linear actuator 7 urges the back cover to move, in relation to the hinge assembly 1, along the actuator axis A2 but in a direction opposite to that of the display 2. In one embodiment, the display 2 moves in

a first direction and the back cover moves in an opposite, second direction along the actuator axis A2. This opposite movement is indicated in Fig. 9c by means of arrows.

[0036] A first dimension of a first outer surface 8a of the hinge assembly 1, i.e. the outer circumference of the folded hinge assembly 1, is larger than a corresponding second dimension of a second outer surface 8b of the pivot hinge 15 the inner circumference of the folded hinge assembly 1, when the hinge assembly 1 is in a folded end position, as shown in Fig. 9c. The linear actuator 6, 7 is actuated by the difference between the first dimension and the second dimension. As the hinge assembly 1 is folded to end position P2a, the dimensions of the first outer surface 8a increases and the linear drive arrangement 13 is pulled in one direction, as is shown in the lowermost drawing of Figs. 1b, 10a, and 10b. Correspondingly, as the hinge assembly 1 is folded to the opposite end position P2b, the dimensions of the first outer surface 8a decreases and the linear drive arrangement 13 is pulled in the opposite direction, as is shown in the uppermost drawing of Figs. 1b, 10a, and 10b.

[0037] In one embodiment, the hinge assembly 1 comprises a neutral axis N as indicated in Fig. 1c. A first end 13a of the linear drive arrangements 13 engages the rotation shaft 12, and a second end 13b of each linear drive arrangement 13 engages a first location and a second location of an individual hinge blade 9a. The first location and the second location are located on opposite sides of, and with equidistant spacing from, the neutral axis N. Each linear drive arrangement 13 extends through any hinge blades 9b located in a first area between the individual hinge blade 9a and the rotation shaft 12. In other words, each linear drive arrangement 13 comprises a first section 13c and a second section 13d extending on opposite sides of, and with equidistant spacing from, the neutral axis N, see e.g. Figs. 3 and 5. A first rotation of the rotation shaft 12 rotates the linear drive arrangements 13 in a first direction, and a second opposite rotation of the rotation shaft 12 rotates the linear drive arrangements 13 in a second opposite direction. The center axis of the rotation shaft 12 intersects the neutral axis N.

[0038] In a further embodiment, the hinge assembly 1 comprises a neutral axis N, and the linear drive arrangements 13 comprise a first section 13c and a second section 13d extending through an individual hinge blade 9a and engaging the rotation shaft 12 at a first end 13a of the linear drive arrangement 13. The first section 13c and the second section 13d extend partially on opposite sides of, and with equidistant spacing from, the neutral axis N. The first section 13c extends in a first area between the first end 13a of the linear drive arrangement 13 and the individual hinge blade 9a, on a first side of the neutral axis N, and the second section 13d extends in the first area between the first end 13a of the linear drive arrangement 13 and the individual hinge blade 9a, on a second side of the neutral axis N, as indicated in Fig. 7. The first section 13c and the second section 13d may furthermore engage

the individual hinge blade 9a by extending through the individual hinge blade 9a such that the first section 13c extends from the first side of the neutral axis N to the second side of the neutral axis N, and the second section 13d extends from the second side of the neutral axis N to the first side of the neutral axis N, the first section 13c and the second section 13d effectively crossing each other in the area of the individual hinge blade 9a. The first section 13c may subsequently extend, in a second area between the individual hinge blade 9a and the second end 13b of the linear drive arrangement 13, on the second side of the neutral axis N, and the second section 13d extend, in the second area, on the first side of the neutral axis N between the individual hinge blade 9a and the second end 13b of the linear drive arrangement 13.

[0039] The first section 13c and the second section 13d may furthermore engage a second individual hinge blade 9d and extend through the second individual hinge blade 9d such that the first section 13c extends back from the second side of the neutral axis N to the first side of the neutral axis N, and the second section 13d extends back from the first side of the neutral axis N to the second side of the neutral axis N, the first section 13c and the second section 13d effectively crossing each other in the area of the second individual hinge blade 9d. The first section 13c may thereafter extend, in a third area between the second individual hinge blade 9d and the second end 13b of the linear drive arrangement 13, on the first side of the neutral axis N, and the second section 13d extend, in the third area, on the second side of the neutral axis N between the second individual hinge blade 9d and the second end 13b of the linear drive arrangement 13.

[0040] This allows any hinge blades 9c located in the second area to be pivoted in a first direction around the first hinge assembly rotation axis A1a, and, simultaneously, allows any hinge blades 9b located in the first area to be pivoted in an opposite, second direction around a second hinge assembly rotation axis A1b, and any hinge blades 9e located in the third area to be pivoted in the opposite, second direction around a third hinge assembly rotation axis A1c, the second hinge assembly rotation axis A1b and the third hinge assembly rotation axis A1c both extending in parallel with the first hinge assembly rotation axis A1a.

[0041] The linear drive arrangement 13 may comprise a chain (not shown) or a wire, as shown in Figs. 2 to 7.

[0042] When the linear drive arrangement 13 comprises a wire, it may be partially wound around the rotation shaft 12, as shown in Fig. 5, and extend through the hinge assembly along the actuator axis A2. A first rotation of the rotation shaft 12 rotates the linear drive arrangement 13 in a first direction, and an opposite, second rotation of the rotation shaft 12 rotates the linear drive arrangement 13 in a second direction. The wire may comprise two separate wire sections 13a, 13b extending in parallel between the first frame section 4 and the second frame section 5, or the wire may comprise an uninterrupted loop.

[0043] The linear drive arrangement 13 may furthermore comprise at least one chain, as shown in Figs. 9a to 9c. The linear drive arrangement 13 may comprise two separate chain sections extending in parallel between the first frame section 4 and the second frame section 5. In one embodiment, the rotation shaft 12 comprises at least one pinion and the linear drive arrangement 13 furthermore comprises at least a first rack connected to the chain and engaging the pinion at a first location. A first rotation of the rotation shaft 12 and the pinion moves the rack in a first direction along the actuator axis A2, hence pulling the chain in the first direction, and an opposite, second rotation of the rotation shaft 12 and the pinion moves the rack in a second direction along the actuator axis A2, hence pushing the chain in the second direction. The linear drive arrangement 13 may further comprise a second rack connected to the chain and engaging the pinion at a second location opposite the first location and extending along the actuator axis A2. A first rotation of the rotation shaft 12 and the pinion simultaneously moves the first rack in the first direction and the second rack in the second direction, such that the first rack pulls the chain in the first direction and the second rack, simultaneously, pushes the chain in the first direction. An opposite, second rotation of the rotation shaft 12 and the pinion simultaneously moves the first rack in the second direction and the second rack in the first direction, such that the first rack pushes the chain in the second direction and the second rack, simultaneously, pulls the chain in the second direction. The first rack may be connected to the display 2 while the second rack is connected to the back cover, such that the display 2 and the back cover are moved simultaneously in opposite directions, along the actuator axis A2, when the linear actuator 6, 7 is actuated.

[0044] As previously mentioned, the present disclosure also relates to an electronic device 14, shown in Figs. 10a and 10b, comprising the above described hinge assembly 1. In one embodiment, the display 2 and/or the back cover of the electronic device are fixedly connected to the first frame section 4, and pivoting the first frame section 4 or the second frame section 5 will actuate the linear actuator 6, 7. The linear actuator 6, 7 urges the display 2 and/or the back cover to slide in relation to the hinge assembly 1 such that an overlap between the display 2 and/or the back cover and the second frame section 5 varies, as shown in, e.g., Fig. 10a. The overlap between the display 2 and the second frame section 5 is at a minimum when the hinge assembly 1 is in the first folded end position P2a. The overlap between the display 2 and the second frame section 5 is at a maximum when the hinge assembly 1 is in the second folded end position P2b.

[0045] In a further embodiment, the display 2 or the back cover is fixedly connected to the first frame section 4 and second frame section 5. The hinge assembly 1 comprises sliding rails interconnecting the hinge assembly 1 and the second frame section 5, and pivoting the first

frame section 4 or the second frame section 5 actuates the linear actuator 6, 7. The linear actuator 6, 7 urges the second frame section 5 to slide, on the sliding rails 11, in relation to the hinge assembly such that the distance between the hinge assembly 1 and the second frame section 5 varies, as shown in Fig. 10b. The distance between the hinge assembly 1 and the second frame section 5 is at a minimum when the hinge assembly 1 is in the first folded end position P2a. The hinge assembly 1 may, correspondingly, be moveable between an unfolded position P1 and a second folded end position P2b, the distance between the hinge assembly 1 and the second frame section 5 being at a maximum when the hinge assembly 1 is in the second folded end position P2b.

[0046] The various aspects and implementations have been described in conjunction with various embodiments herein. In the claims, the word "comprising" does not exclude other elements or steps, and the indefinite article "a" or "an" does not exclude a plurality. The mere fact that certain measures are recited in mutually different dependent claims does not indicate that a combination of these measured cannot be used to advantage.

Claims

1. A hinge assembly (1) for an electronic device (14), said hinge assembly (1) being moveable between an unfolded position (P1) and at least a first folded end position (P2a),

said hinge assembly (1) comprising a row of interconnected and abutting hinge blades (9) and at least one linear actuator (6, 7), said hinge blades (9) being aligned in a common plane when said hinge assembly (1) is in said unfolded position (P1), each hinge blade (9) being rotated relative to neighboring hinge blades (9) around a first hinge assembly rotation axis (A1a), when said hinge assembly (1) is moved to said first folded end position (P2a), said linear actuator (6, 7) comprising a rotation shaft (12) and a plurality of linear drive arrangements (13) having different lengths (10), said rotation shaft (12) extending in parallel with said first hinge assembly rotation axis (A1a) and comprising sections (3) having different diameters (11), a first end (13a) of each linear drive arrangement (13) being interconnected with a section (3) of said rotation shaft (12) having one diameter (11), a second, opposite end (13b) of each linear drive arrangement (13) being connected to one hinge blade (9), an actuator axis (A2) extending between said first and second ends (13a, 13b) of each linear drive arrangement and perpendicular to said first hinge assembly rotation axis (A1a),

wherein actuation of said linear actuator (6, 7) along said actuator axis (A2) is configured to urge each hinge blade (9) to rotate relative neighboring hinge blades (9) around said first hinge assembly rotation axis (A1a).

2. The hinge assembly (1) according to claim 1, wherein rotation of said hinge blades (9) is initiated successively in response to said differing diameters (11) of said rotation shaft (12).

3. The hinge assembly (1) according to claim 1 or 2, wherein said hinge assembly (1) comprises at least a first linear actuator (6) and a second linear actuator (7),

said first linear actuator (6) comprising a first rotation shaft (12a) and plurality of first linear drive arrangements (13), said second linear actuator (7) comprising a second rotation shaft (12b) and plurality of second linear drive arrangements (13),

said first rotation shaft (12a) and said second rotation shaft (12b) extending in parallel, said first linear drive arrangements (13) and said second linear drive arrangements (13) extending in parallel.

4. The hinge assembly (1) according to claim 3, wherein one of said first linear drive arrangements (13) and one of said second linear drive arrangements (13) are connected to the same hinge blade (9), synchronizing the actuation of said first linear actuator (6) and said second linear actuator (7).

5. The hinge assembly (1) according to any one of the previous claims, wherein a first dimension of a first outer surface (8a) of said hinge assembly (1) is larger than a corresponding second dimension of a second outer surface (8b) of said hinge assembly (1) when said hinge assembly (1) is in said first folded end position (P2a), said first linear actuator (6) and/or said second linear actuator (7) being actuated by a difference between said first dimension and said second dimension.

6. The hinge assembly (1) according to any one of the previous claims, wherein said linear drive arrangement (13) comprises a chain or a wire.

7. The hinge assembly (1) according to any one of the previous claims, wherein said hinge assembly (1) comprises a neutral axis (N),

said first end (13a) of said linear drive arrangement (13) engaging said rotation shaft (12), and said second end (13b) of said linear drive arrangement (13) engaging a first location and a

second location of an individual hinge blade (9a),
 said first location and said second location being located on opposite sides of, and with equidistant spacing from, said neutral axis (N),
 said linear drive arrangement (13) extending through any hinge blades (9b) located in a first area between said individual hinge blade (9a) and said rotation shaft (12),
 said linear drive arrangement (13) comprising a first section (13c) and a second section (13d) extending on opposite sides of, and with equidistant spacing from, said neutral axis (N),
 a first rotation of said rotation shaft (12) rotating said linear drive arrangement (13) in a first direction, and a second rotation of said rotation shaft (12) rotating said linear drive arrangement (13) in a second direction.

8. The hinge assembly (1) according to claim 7, wherein said linear drive arrangement (13) comprises a wire partially wound around said rotation shaft (12).
9. The hinge assembly (1) according to any one of claims 1 to 6, wherein said hinge assembly (1) comprises a neutral axis (N), and

said linear drive arrangement (13) comprises a first section (13c) and a second section (13d) extending through an individual hinge blade (9a) and engaging said rotation shaft (12) at said first end (13a) of said linear drive arrangement (13), said first section (13c) and said second section (13d) extending partially on opposite sides of, and with equidistant spacing from, said neutral axis (N),
 said first section (13c) extending in a first area between said first end (13a) and said individual hinge blade (9a), on a first side of said neutral axis (N), and said second section (13d) extending in said first area on a second side of said neutral axis (N),
 said first section (13c) and said second section (13d) furthermore engaging said individual hinge blade (9a) by extending through said individual hinge blade (9a) such that said first section (13c) extends from said first side of said neutral axis (N) to said second side of said neutral axis (N), and said second section (13d) extends from said second side of said neutral axis (N) to said first side of said neutral axis (N),
 said first section (13c) extending, in a second area between said individual hinge blade (9a) and said second end (13b) of said linear drive arrangement (13), on said second side of said neutral axis (N) and said second section (13d) extending, in said second area, on said first side

of said neutral axis (N),
 allowing any hinge blades (9c) located in said second area to be pivoted in a first direction around said first hinge assembly rotation axis (A1a), and, simultaneously, allowing any hinge blades (9b) located in said first area to be pivoted in an opposite, second direction around a second hinge assembly rotation axis (A1b) extending in parallel with said first hinge assembly rotation axis (A1a).

10. The hinge assembly (1) according to claim 9, wherein said first section (13c) and said second section (13d) furthermore engage a second individual hinge blade (9d) by extending through said second individual hinge blade (9d) such that said first section (13c) extends back from said second side of said neutral axis (N) to said first side of said neutral axis (N), and said second section (13d) extends back from said first side of said neutral axis (N) to said second side of said neutral axis (N),

said first section (13c) extending, in a third area between said second individual hinge blade (9d) and said second end (13b) of said linear drive arrangement (13), on said first side of said neutral axis (N), and said second section (13d) extending, in said third area, on said second side of said neutral axis (N),
 allowing any hinge blades (9e) located in said third area to be pivoted in said opposite, second direction around a third hinge assembly rotation axis (A1c) extending in parallel with said first hinge assembly rotation axis (A1a).

11. An electronic device (14) comprising a first frame section (4), a second frame section (5), a display (2)

connected to at least one of said first frame section (4) and said second frame section (5), and a hinge assembly (1) according to any one of claims 1 to 10 interconnecting said first frame section (4) and said second frame section (5) such that said first frame section (4) and said second frame section (5) are pivotable, relative each other, between an unfolded position (P1) and a first folded end position (P2a),
 said first frame section (4) and said second frame section (5) being aligned in a common plane when in said unfolded position (P1),
 said second frame section (5) being superimposed on said first frame section (4) when in said first folded end position (P2a).

12. The electronic device (14) according to claim 11, wherein said hinge assembly (1) interconnects said first frame section (4) and said second frame section (5) such that said first frame section (4) and said

second frame section (5) are pivotable, relative each other, between an unfolded position (P1) and a second folded end position (P2b), said first frame section (4) being superimposed on said second frame section (5) when in said second folded end position (P2b).

Patentansprüche

1. Scharnieranordnung (1) für eine elektronische Vorrichtung (14), wobei die Scharnieranordnung (1) zwischen einer ausgeklappten Position (P1) und mindestens einer ersten zusammengeklappten Endposition (P2a) bewegbar ist,

wobei die Scharnieranordnung (1) eine Reihe miteinander verbundener und aneinanderstoßender Scharnierblätter (9) und mindestens einen Linearantrieb (6, 7) umfasst,

wobei die Scharnierblätter (9) in einer gemeinsamen Ebene ausgerichtet sind, wenn sich die Scharnieranordnung (1) in der ausgeklappten Position (P1) befindet, wobei jedes Scharnierblatt (9) relativ zu benachbarten Scharnierblättern (9) um eine erste Scharnieranordnungs-Drehachse (A1a) gedreht wird, wenn die Scharnieranordnung (1) in die erste zusammengeklappte Endposition (P2a) bewegt wird, wobei der Linearantrieb (6, 7) eine Drehwelle (12) und eine Vielzahl von Linearantriebsanordnungen (13) mit unterschiedlichen Längen (10) umfasst,

wobei die Drehwelle (12) parallel zu der Drehachse (A1a) der ersten Scharnieranordnung verläuft und Abschnitte (3) mit unterschiedlichen Durchmessern (11) aufweist,

wobei ein erstes Ende (13a) jeder Linearantriebsanordnung (13) mit einem Abschnitt (3) der Drehwelle (12) verbunden ist, der einen Durchmesser (11) aufweist,

ein zweites, gegenüberliegendes Ende (13b) jeder Linearantriebsanordnung (13) mit einem Scharnierblatt (9) verbunden ist, wobei eine Aktorachse (A2) zwischen dem ersten und zweiten Ende (13a, 13b) jeder Linearantriebsanordnung und senkrecht zur ersten Drehachse (A1a) der Scharnieranordnung verläuft,

wobei die Betätigung des Linearantriebs (6, 7) entlang der Antriebsachse (A2) dazu ausgebildet ist, jedes Scharnierblatt (9) dazu zu zwingen, relativ benachbarte Scharnierblätter (9) um die erste Scharnieranordnungs-Drehachse (A1a) zu drehen.

2. Scharnieranordnung (1) nach Anspruch 1, wobei die Drehung der Scharnierblätter (9) nacheinander als Reaktion auf die unterschiedlichen Durchmesser

(11) der Drehwelle (12) eingeleitet wird.

3. Scharnieranordnung (1) nach Anspruch 1 oder 2, wobei die Scharnieranordnung (1) mindestens einen ersten Linearantrieb (6) und einen zweiten Linearantrieb (7) umfasst,

wobei der erste Linearantrieb (6) eine erste Drehwelle (12a) und eine Vielzahl von ersten Linearantriebsanordnungen (13) umfasst, wobei der zweite Linearantrieb (7) eine zweite Drehwelle (12b) und eine Vielzahl von zweiten Linearantriebsanordnungen (13) umfasst, wobei die erste Drehwelle (12a) und die zweite Drehwelle (12b) parallel verlaufen, wobei die ersten Linearantriebsanordnungen (13) und die zweiten Linearantriebsanordnungen (13) parallel verlaufen.

4. Scharnieranordnung (1) nach Anspruch 3, wobei eine der ersten Linearantriebsanordnungen (13) und eine der zweiten Linearantriebsanordnungen (13) mit demselben Scharnierblatt (9) verbunden sind, wodurch die Betätigung des ersten Linearaktors (6) und des zweiten Linearaktors (7) synchronisiert wird.

5. Scharnieranordnung (1) nach einem der vorhergehenden Ansprüche, wobei eine erste Abmessung einer ersten Außenfläche (8a) der Scharnieranordnung (1) größer ist als eine entsprechende zweite Abmessung einer zweiten Außenfläche (8b) der Scharnieranordnung (1), wenn sich die Scharnieranordnung (1) in der ersten zusammengeklappten Endposition (P2a) befindet,

wobei der erste Linearaktor (6) und/oder der zweite Linearaktor (7) durch eine Differenz zwischen der ersten Dimension und der zweiten Dimension betätigt werden.

6. Scharnieranordnung (1) nach einem der vorhergehenden Ansprüche, wobei die Linearantriebsanordnung (13) eine Kette oder einen Draht umfasst.

7. Scharnieranordnung (1) nach einem der vorhergehenden Ansprüche, wobei die Scharnieranordnung (1) eine neutrale Achse (N) umfasst, wobei das erste Ende (13a) der Linearantriebsanordnung (13) mit der Drehwelle (12) in Eingriff steht, und

wobei das zweite Ende (13b) der Linearantriebsanordnung (13) an einer ersten Stelle und einer zweiten Stelle eines einzelnen Scharnierblattes (9a) angreift,

wobei sich der erste Ort und der zweite Ort auf gegenüberliegenden Seiten und mit gleichem Abstand von der neutralen Achse (N) befinden, wobei sich die Linearantriebsanordnung (13) durch alle Scharnierblätter (9b) erstreckt, die sich in einem ersten Bereich zwischen dem ein-

zelen Scharnierblatt (9a) und der Drehwelle (12) befinden, wobei die Linearantriebsanordnung (13) einen ersten Abschnitt (13c) und einen zweiten Abschnitt (13d) umfasst, die auf gegenüberliegenden Seiten der neutralen Achse (N) und mit gleichem Abstand von dieser verlaufen, eine erste Drehung der Drehwelle (12) die Linearantriebsanordnung (13) in eine erste Richtung dreht, und eine zweite Drehung der Drehwelle (12) die Linearantriebsanordnung (13) in eine zweite Richtung dreht.

8. Scharnieranordnung (1) nach Anspruch 7, wobei die Linearantriebsanordnung (13) einen Draht umfasst, der teilweise um die Drehwelle (12) gewickelt ist.

9. Scharnieranordnung (1) nach einem der Ansprüche 1 bis 6, wobei die Scharnieranordnung (1) eine neutrale Achse (N) umfasst, und die Linearantriebsanordnung (13) einen ersten Abschnitt (13c) und einen zweiten Abschnitt (13d) umfasst, die sich durch ein einzelnes Scharnierblatt (9a) erstrecken und die Drehwelle (12) an dem ersten Ende (13a) der Linearantriebsanordnung (13) in Eingriff nehmen,

wobei der erste Abschnitt (13c) und der zweite Abschnitt (13d) teilweise auf gegenüberliegenden Seiten der neutralen Achse (N) und mit gleichem Abstand von dieser verlaufen, wobei der erste Abschnitt (13c) sich in einem ersten Bereich zwischen dem ersten Ende (13a) und dem einzelnen Scharnierblatt (9a) auf einer ersten Seite der neutralen Achse (N) erstreckt, und wobei der zweite Abschnitt (13d) sich in dem ersten Bereich auf einer zweiten Seite der neutralen Achse (N) erstreckt, wobei der erste Abschnitt (13c) und der zweite Abschnitt (13d) außerdem mit dem einzelnen Scharnierblatt (9a) in Eingriff stehen, indem sie sich durch das einzelne Scharnierblatt (9a) erstrecken, so dass der erste Abschnitt (13c) von der ersten Seite der neutralen Achse (N) zu der zweiten Seite der neutralen Achse (N) verläuft und der zweite Abschnitt (13d) von der zweiten Seite der neutralen Achse (N) zu der ersten Seite der neutralen Achse (N) verläuft, wobei der erste Abschnitt (13c) in einem zweiten Bereich zwischen dem einzelnen Scharnierblatt (9a) und dem zweiten Ende (13b) der Linearantriebsanordnung (13) auf der zweiten Seite der neutralen Achse (N) verläuft und der zweite Abschnitt (13d) in dem zweiten Bereich auf der ersten Seite der neutralen Achse (N) verläuft, Ermöglichen, dass alle in dem zweiten Bereich angeordneten Scharnierblätter (9c) in eine erste Richtung um die erste Scharnieranordnungsdrehachse (A1a) geschwenkt werden, und

gleichzeitig Ermöglichen, dass alle in dem ersten Bereich angeordneten Scharnierblätter (9b) in eine entgegengesetzte, zweite Richtung um eine zweite Scharnieranordnungsdrehachse (A1b) geschwenkt werden, die parallel zu der ersten Scharnieranordnungsdrehachse (A1a) verläuft.

10. Scharnieranordnung (1) nach Anspruch 9, wobei der erste Abschnitt (13c) und der zweite Abschnitt (13d) außerdem mit einem zweiten einzelnen Scharnierblatt (9d) in Eingriff stehen, indem sie sich durch das zweite einzelne Scharnierblatt (9d) erstrecken, so dass sich der erste Abschnitt (13c) von der zweiten Seite der neutralen Achse (N) zurück zu der ersten Seite der neutralen Achse (N) erstreckt und sich der zweite Abschnitt (13d) von der ersten Seite der neutralen Achse (N) zurück zu der zweiten Seite der neutralen Achse (N) erstreckt,

wobei der erste Abschnitt (13c) in einem dritten Bereich zwischen dem zweiten einzelnen Scharnierblatt (9d) und dem zweiten Ende (13b) der Linearantriebsanordnung (13) auf der ersten Seite der neutralen Achse (N) verläuft und der zweite Abschnitt (13d) in dem dritten Bereich auf der zweiten Seite der neutralen Achse (N) verläuft,

Ermöglichen, dass alle in dem dritten Bereich angeordneten Scharnierblätter (9e) in die entgegengesetzte zweite Richtung um eine dritte Scharnieranordnungsdrehachse (A1c) geschwenkt werden können, die parallel zu der ersten Scharnieranordnungsdrehachse (A1a) verläuft.

11. Elektronische Vorrichtung (14), die einen ersten Rahmenabschnitt (4), einen zweiten Rahmenabschnitt (5), ein Display (2), das mit mindestens einem der ersten Rahmenabschnitte (4) und des zweiten Rahmenabschnitts (5) verbunden ist, und eine Scharnieranordnung (1) gemäß einem der Ansprüche 1 bis 10 umfasst, die den ersten Rahmenabschnitt (4) und den zweiten Rahmenabschnitt (5) so miteinander verbindet, dass der erste Rahmenabschnitt (4) und der zweite Rahmenabschnitt (5) relativ zueinander zwischen einer aufgeklappten Position (P1) und einer ersten zusammengeklappten Endposition (P2a) schwenkbar sind,

wobei der erste Rahmenabschnitt (4) und der zweite Rahmenabschnitt (5) in der ausgeklappten Position (P1) in einer gemeinsamen Ebene ausgerichtet sind,

wobei der zweite Rahmenabschnitt (5) in der ersten zusammengeklappten Endposition (P2a) auf dem ersten Rahmenabschnitt (4) liegt.

12. Elektronische Vorrichtung (14) nach Anspruch 11, wobei die Scharnieranordnung (1) den ersten Rahmenabschnitt (4) und den zweiten Rahmenabschnitt (5) so miteinander verbindet, dass der erste Rahmenabschnitt (4) und der zweite Rahmenabschnitt (5) relativ zueinander zwischen einer aufgeklappten Position (P1) und einer zweiten zusammengeklappten Endposition (P2b) schwenkbar sind, wobei der erste Rahmenabschnitt (5) in der zweiten zusammengeklappten Endposition (P2b) auf dem zweiten Rahmenabschnitt (4) liegt.

Revendications

1. Ensemble charnière (1) pour un dispositif électronique (14), ledit ensemble charnière (1) étant mobile entre une position dépliée (P1) et au moins une première position d'extrémité pliée (P2a),

ledit ensemble charnière (1) comprenant une rangée de lames de charnière interconnectées et en butée (9) et au moins un actionneur linéaire (6, 7),

lesdites lames de charnière (9) étant alignées dans un plan commun lorsque ledit ensemble charnière (1) est dans ladite position dépliée (P1), chaque lame de charnière (9) étant tournée par rapport à des lames de charnière voisines (9) autour d'un premier axe de rotation d'ensemble charnière (A1a), lorsque ledit ensemble charnière (1) est déplacé vers ladite première position d'extrémité pliée (P2a),

ledit actionneur linéaire (6, 7) comprenant un arbre de rotation (12) et une pluralité d'agencements d'entraînement linéaire (13) ayant différentes longueurs (10),

ledit arbre de rotation (12) se prolongeant parallèlement audit premier axe de rotation d'ensemble charnière (A1a) et comprenant des sections (3) ayant des diamètres différents (11), une première extrémité (13a) de chaque agencement d'entraînement linéaire (13) étant interconnectée avec une section (3) dudit arbre de rotation (12) ayant un diamètre (11),

une seconde extrémité opposée (13b) de chaque agencement d'entraînement linéaire (13) étant connectée à une lame de charnière (9), un axe d'actionneur (A2) se prolongeant entre lesdites première et seconde extrémités (13a, 13b) de chaque agencement d'entraînement linéaire et perpendiculaire audit axe de rotation du premier axe de rotation d'ensemble charnière (A1a),

dans lequel l'actionnement dudit actionneur linéaire (6, 7) le long dudit axe d'actionneur (A2) est configuré pour pousser chaque lame de charnière (9) à tourner par rapport à des lames

de charnière voisines (9) autour dudit premier axe de rotation d'ensemble charnière (A1a).

2. Ensemble charnière (1) selon la revendication 1, dans lequel la rotation desdites lames de charnière (9) est initiée successivement en réponse auxdits diamètres différents (11) dudit arbre de rotation (12).

3. Ensemble charnière (1) selon la revendication 1 ou 2, dans lequel ledit ensemble charnière (1) comprend au moins un premier actionneur linéaire (6) et un second actionneur linéaire (7),

ledit premier actionneur linéaire (6) comprenant un premier arbre de rotation (12a) et une pluralité de premiers agencements d'entraînement linéaire (13), ledit second actionneur linéaire (7) comprenant un second arbre de rotation (12b) et une pluralité de seconds agencements d'entraînement linéaire (13),

ledit premier arbre de rotation (12a) et ledit second arbre de rotation (12b) se prolongeant en parallèle, lesdits premiers agencements d'entraînement linéaire (13) et lesdits seconds agencements d'entraînement linéaire (13) se prolongeant en parallèle.

4. Ensemble charnière (1) selon la revendication 3, dans lequel l'un desdits premiers agencements d'entraînement linéaire (13) et l'un desdits seconds agencements d'entraînement linéaire (13) sont connectés à la même lame de charnière (9), synchronisant l'actionnement dudit premier actionneur linéaire (6) et dudit second actionneur linéaire (7).

5. Ensemble charnière (1) selon l'une quelconque des revendications précédentes, dans lequel une première dimension d'une première surface externe (8a) dudit ensemble charnière (1) est plus grande qu'une seconde dimension correspondante d'une seconde surface externe (8b) dudit ensemble charnière (1) lorsque ledit ensemble charnière (1) est dans ladite première position d'extrémité pliée (P2a), ledit premier actionneur linéaire (6) et/ou ledit second actionneur linéaire (7) étant actionnés par une différence entre ladite première dimension et ladite seconde dimension.

6. Ensemble charnière (1) selon l'une quelconque des revendications précédentes, dans lequel ledit agencement d'entraînement linéaire (13) comprend une chaîne ou un fil.

7. Ensemble charnière (1) selon l'une quelconque des revendications précédentes, dans lequel ledit ensemble charnière (1) comprend un axe neutre (N),

ladite première extrémité (13a) dudit agence-

ment d'entraînement linéaire (13) entrant en prise avec ledit arbre de rotation (12), et ladite seconde extrémité (13b) dudit agencement d'entraînement linéaire (13) entrant en prise avec un premier emplacement et un second emplacement d'une lame de charnière individuelle (9a),
 ledit premier emplacement et ledit second emplacement étant situés sur des côtés opposés et à un espacement équidistant dudit axe neutre (N),
 ledit agencement d'entraînement linéaire (13) se prolongeant à travers toutes lames de charnière (9b) situées dans une première zone entre ladite lame de charnière individuelle (9a) et ledit arbre de rotation (12),
 ledit agencement d'entraînement linéaire (13) comprenant une première section (13c) et une seconde section (13d) se prolongeant sur des côtés opposés et à un espacement équidistant dudit axe neutre (N),
 une première rotation dudit arbre de rotation (12) faisant tourner ledit agencement d'entraînement linéaire (13) dans une première direction, et une seconde rotation dudit arbre de rotation (12) faisant tourner ledit agencement d'entraînement linéaire (13) dans une seconde direction.

8. Ensemble charnière (1) selon la revendication 7, dans lequel ledit agencement d'entraînement linéaire (13) comprend un fil partiellement enroulé autour dudit arbre de rotation (12).

9. Ensemble charnière (1) selon l'une quelconque des revendications 1 à 6, dans lequel ledit ensemble charnière (1) comprend un axe neutre (N), et

ledit agencement d'entraînement linéaire (13) comprend une première section (13c) et une seconde section (13d) se prolongeant à travers une lame de charnière individuelle (9a) et entrant en prise avec ledit arbre de rotation (12) au niveau de ladite première extrémité (13a) dudit agencement d'entraînement linéaire (13),
 ladite première section (13c) et ladite seconde section (13d) se prolongeant partiellement sur des côtés opposés et à un espacement équidistant dudit axe neutre (N),
 ladite première section (13c) se prolongeant dans une première zone entre ladite première extrémité (13a) et ladite lame de charnière individuelle (9a), sur un premier côté dudit axe neutre (N), et ladite seconde section (13d) se prolongeant dans ladite première zone sur un second côté dudit axe neutre (N),
 ladite première section (13c) et ladite seconde section (13d) entrent également en prise avec

ladite lame de charnière individuelle (9a) en se prolongeant à travers ladite lame de charnière individuelle (9a) de sorte que ladite première section (13c) se prolonge à partir dudit premier côté dudit axe neutre (N) jusqu'audit second côté dudit axe neutre (N), et ladite seconde section (13d) se prolonge à partir dudit second côté dudit axe neutre (N) jusqu'audit premier côté dudit axe neutre (N),
 ladite première section (13c) se prolongeant, dans une deuxième zone entre ladite lame de charnière individuelle (9a) et ladite seconde extrémité (13b) dudit agencement d'entraînement linéaire (13), sur ledit second côté dudit axe neutre (N) et ladite seconde section (13d) se prolongeant, dans ladite deuxième zone, sur ledit premier côté dudit axe neutre (N), permettant à toutes lames de charnière (9c) situées dans ladite deuxième zone de pivoter dans une première direction autour dudit premier axe de rotation d'ensemble charnière (A1a), et, simultanément, permettant à toutes lames de charnière (9b) situées dans ladite première zone de pivoter dans une seconde direction opposée autour d'un deuxième axe de rotation d'ensemble charnière (A1b) se prolongeant parallèlement audit premier axe de rotation d'ensemble charnière (A1a).

10. Ensemble charnière (1) selon la revendication 9, dans lequel ladite première section (13c) et ladite seconde section (13d) entrent également en prise avec une seconde lame de charnière individuelle (9d) en se prolongeant à travers ladite seconde lame de charnière individuelle (9d) de sorte que ladite première section (13c) se prolonge à nouveau à partir dudit second côté dudit axe neutre (N) jusqu'audit premier côté dudit axe neutre (N), et ladite seconde section (13d) se prolonge à nouveau à partir dudit premier côté dudit axe neutre (N) jusqu'audit second côté dudit axe neutre (N),

ladite première section (13c) se prolongeant, dans une troisième zone entre ladite seconde lame de charnière individuelle (9d) et ladite seconde extrémité (13b) dudit agencement d'entraînement linéaire (13), sur ledit premier côté dudit axe neutre (N), et ladite seconde section (13d) se prolongeant, dans ladite troisième zone, sur ledit second côté dudit axe neutre (N), permettant à toutes lames de charnière (9e) situées dans ladite troisième zone de pivoter dans ladite seconde direction opposée autour d'un troisième axe de rotation d'ensemble charnière (A1c) se prolongeant parallèlement audit premier axe de rotation d'ensemble charnière (A1a).

11. Dispositif électronique (14) comprenant une première section de cadre (4), une seconde section de cadre (5), un affichage (2) connecté à au moins l'une de ladite première section de cadre (4) et de ladite seconde section de cadre (5), et un ensemble charnière (1) selon l'une quelconque des revendications 1 à 10 interconnectant ladite première section de cadre (4) et ladite seconde section de cadre (5) de sorte que ladite première section de cadre (4) et ladite seconde section de cadre (5) peuvent pivoter, l'une par rapport à l'autre, entre une position dépliée (P1) et une première position d'extrémité pliée (P2a),

ladite première section de cadre (4) et ladite seconde section de cadre (5) étant alignées dans un plan commun lorsqu'elles sont dans ladite position dépliée (P1),

ladite seconde section de cadre (5) étant superposée à ladite première section de cadre (4) lorsqu'elle se trouve dans ladite première position d'extrémité pliée (P2a).

12. Dispositif électronique (14) selon la revendication 11, dans lequel ledit ensemble charnière (1) interconnecte ladite première section de cadre (4) et ladite seconde section de cadre (5) de sorte que ladite première section de cadre (4) et ladite seconde section de cadre (5) peuvent pivoter, l'une par rapport à l'autre, entre une position dépliée (P1) et une seconde position d'extrémité pliée (P2b), ladite première section de cadre (4) étant superposée à ladite seconde section de cadre (5) lorsqu'elle se trouve dans ladite seconde position d'extrémité pliée (P2b).

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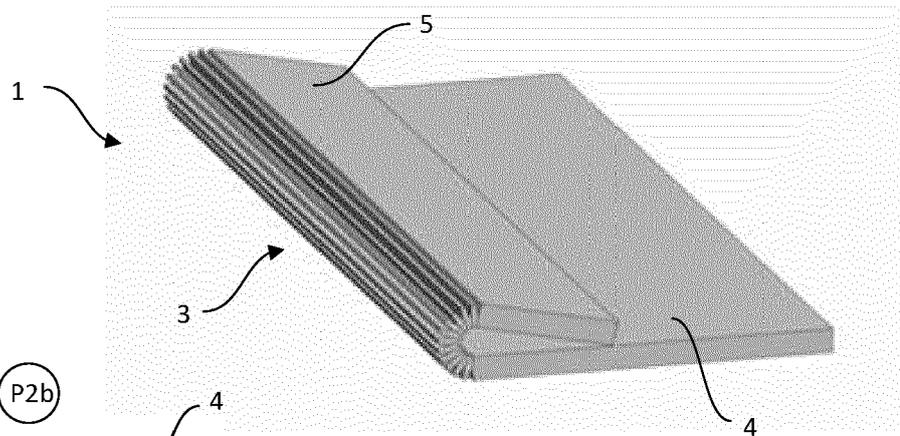


Fig. 1a

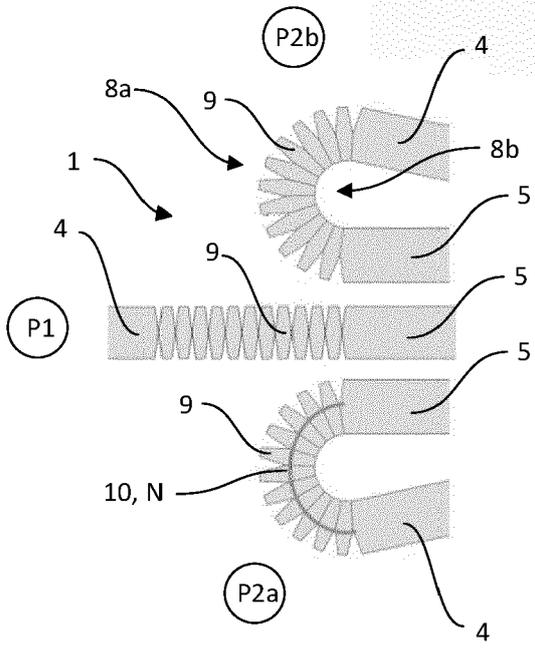


Fig. 1b

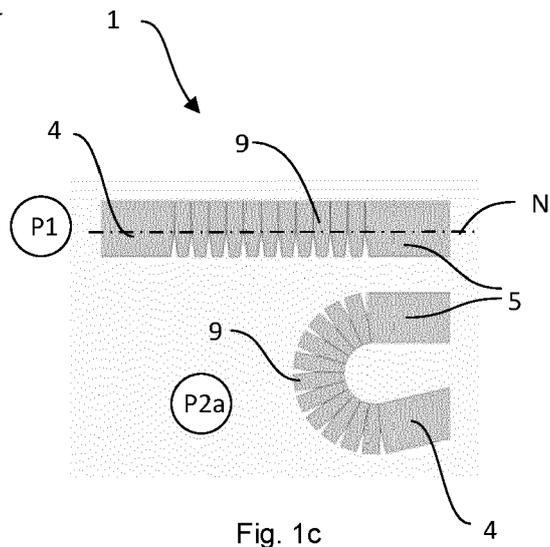


Fig. 1c

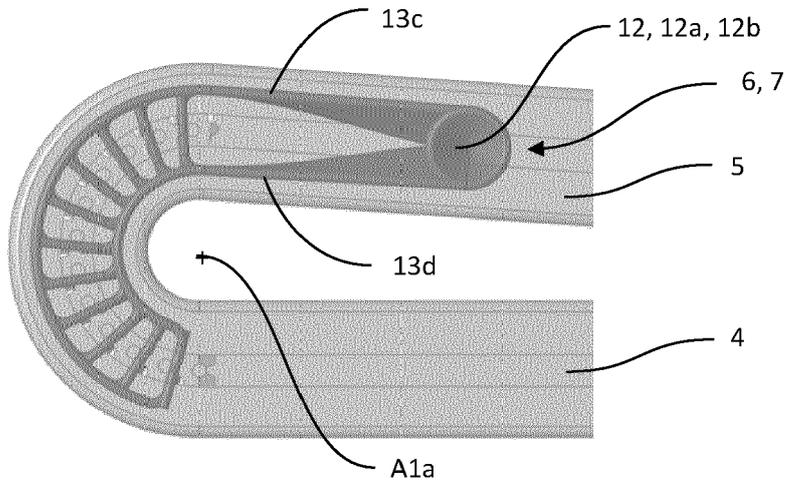


Fig. 2

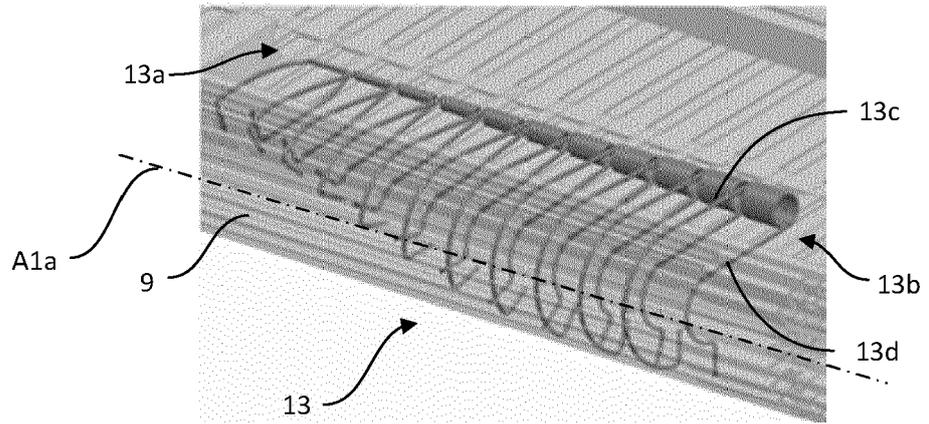


Fig. 3

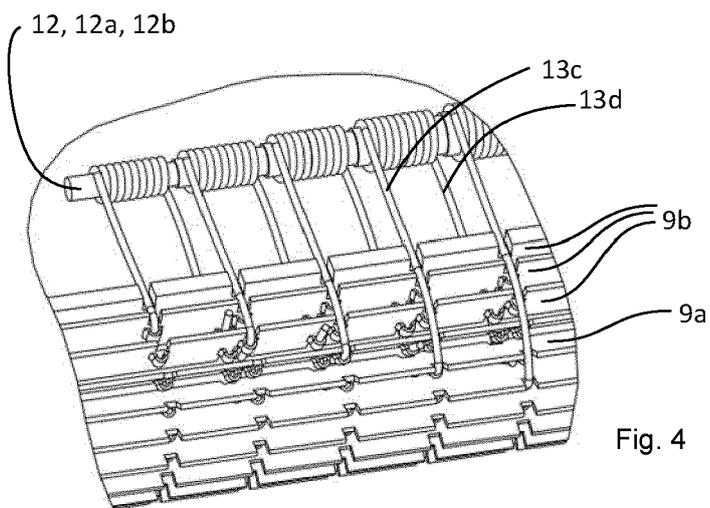
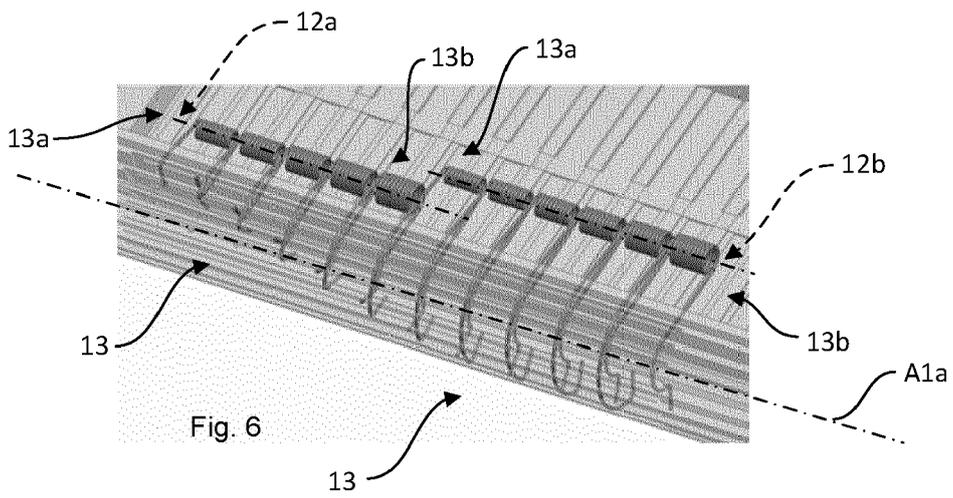
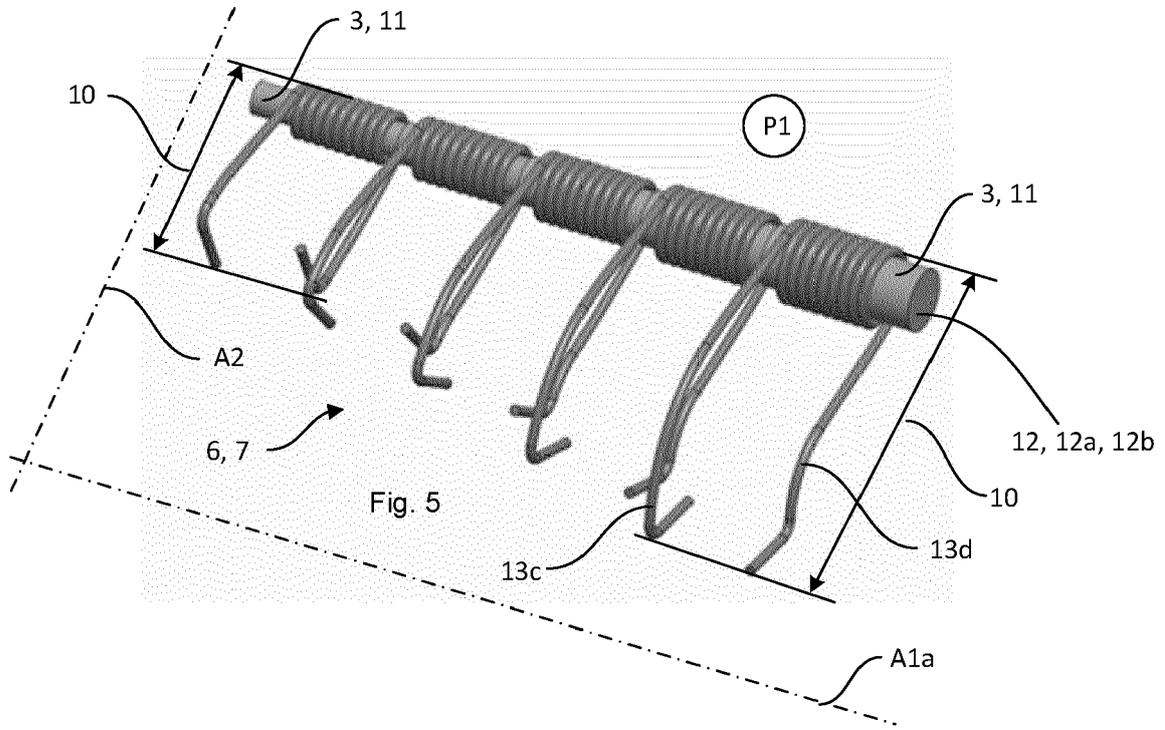
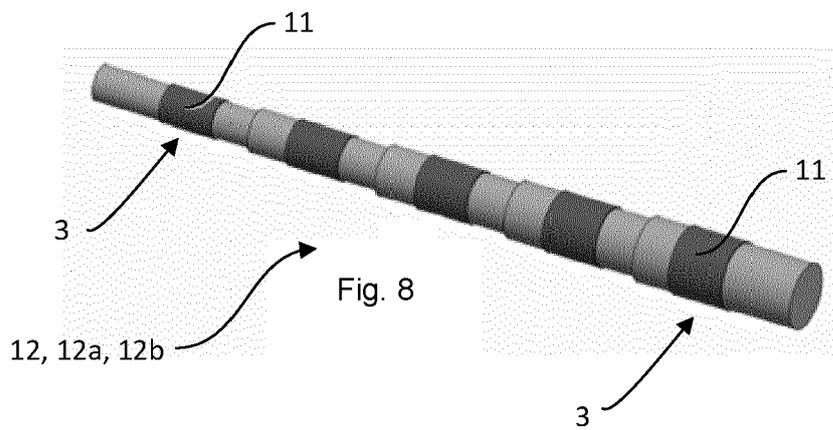
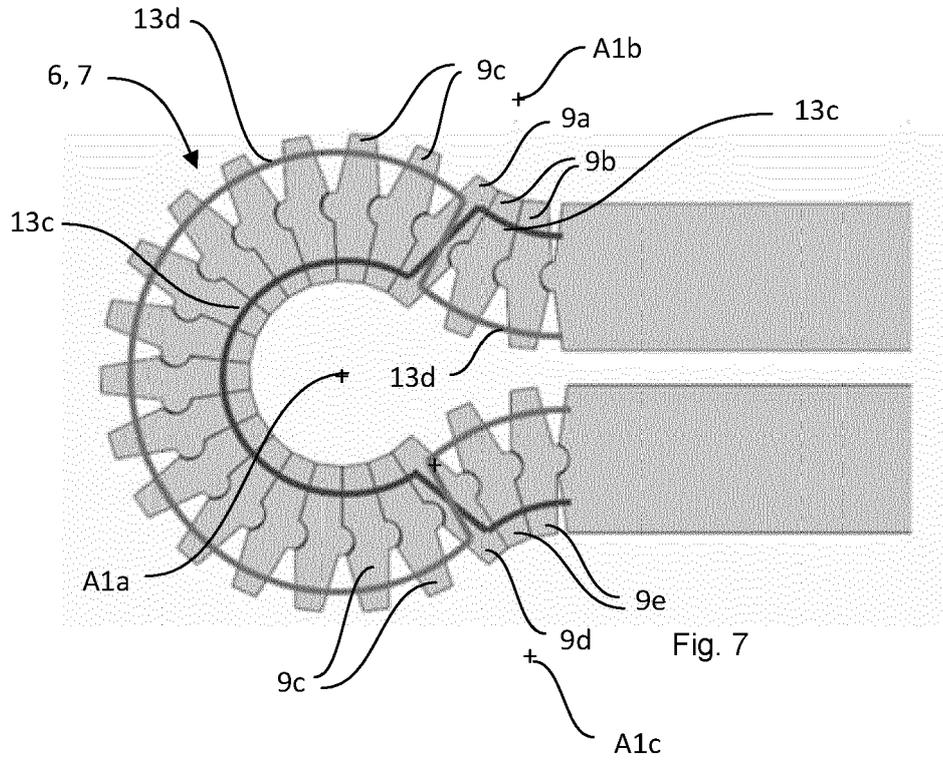
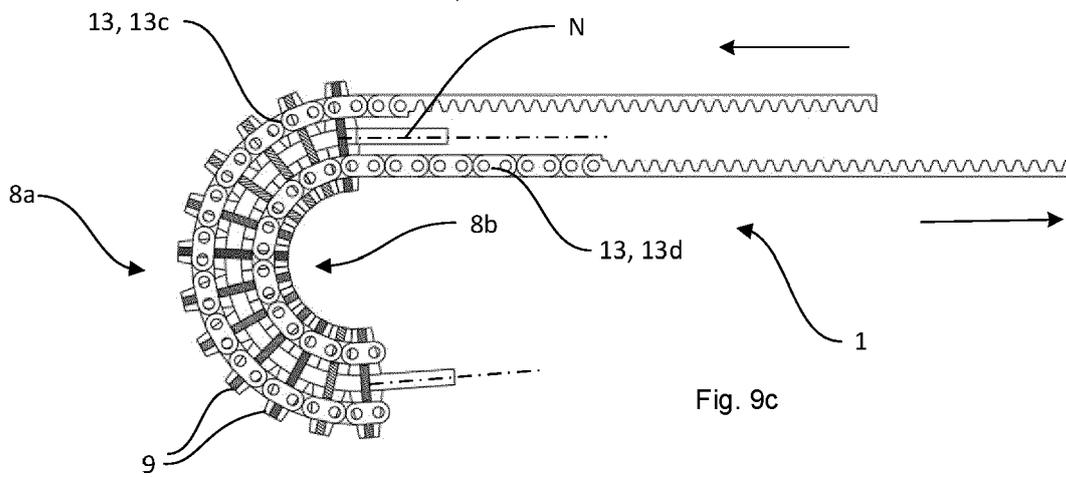
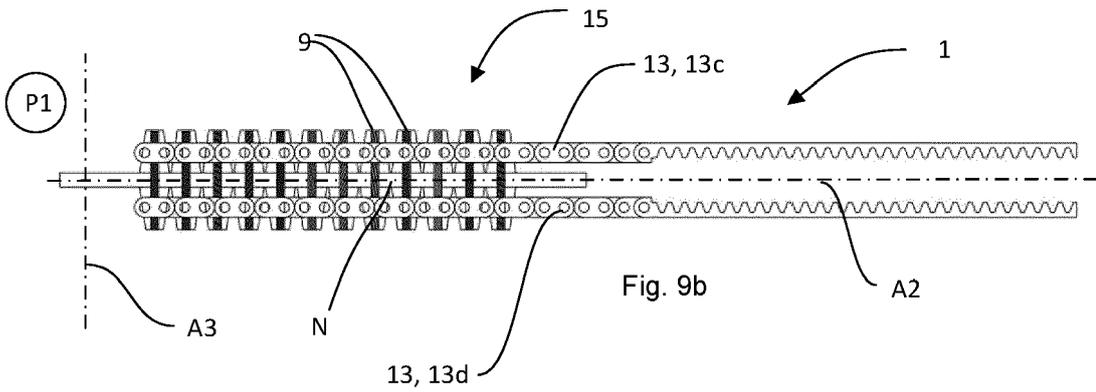
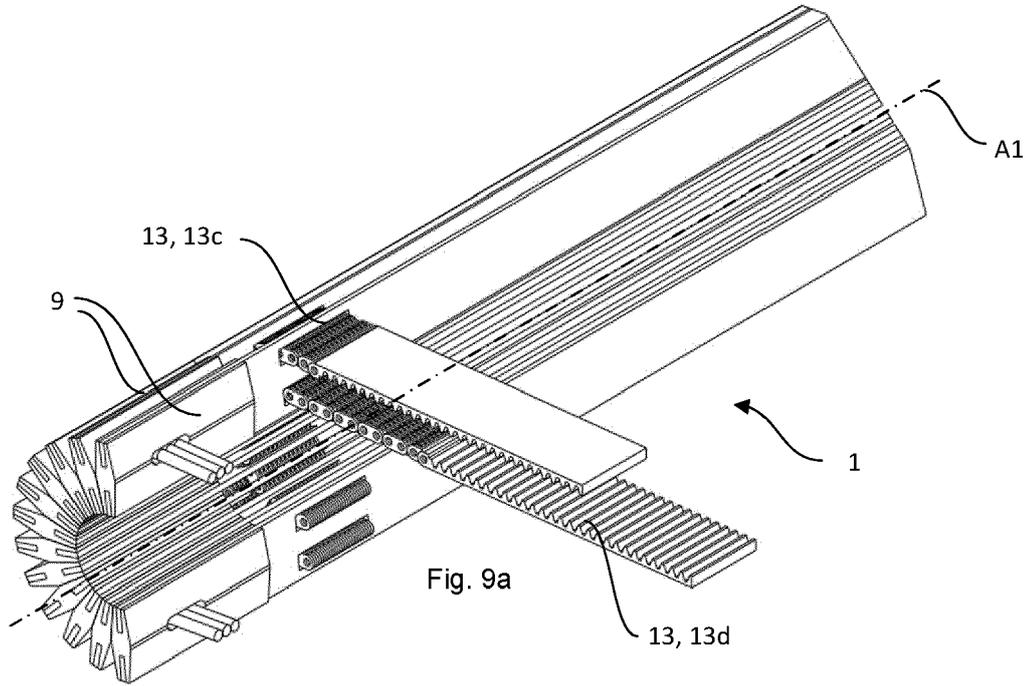
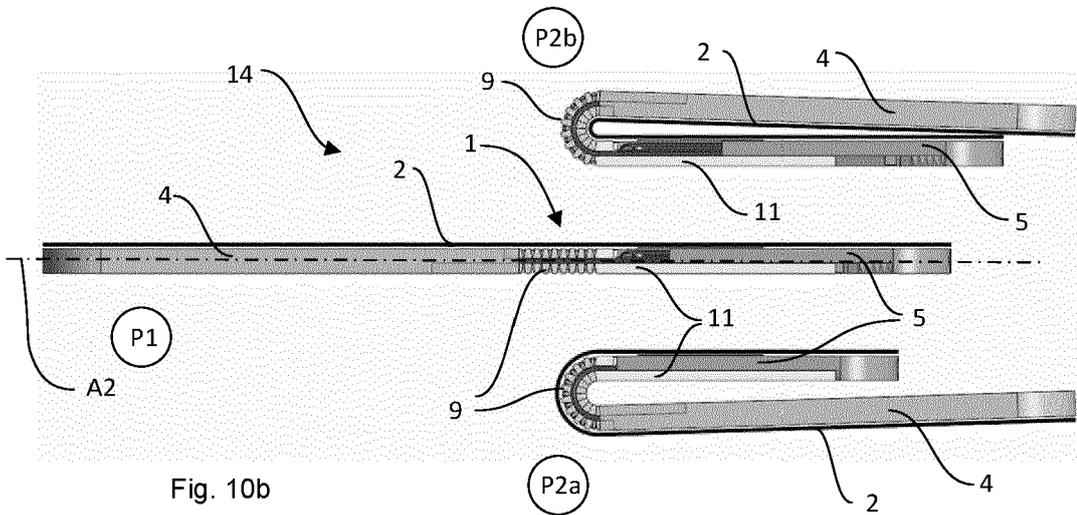
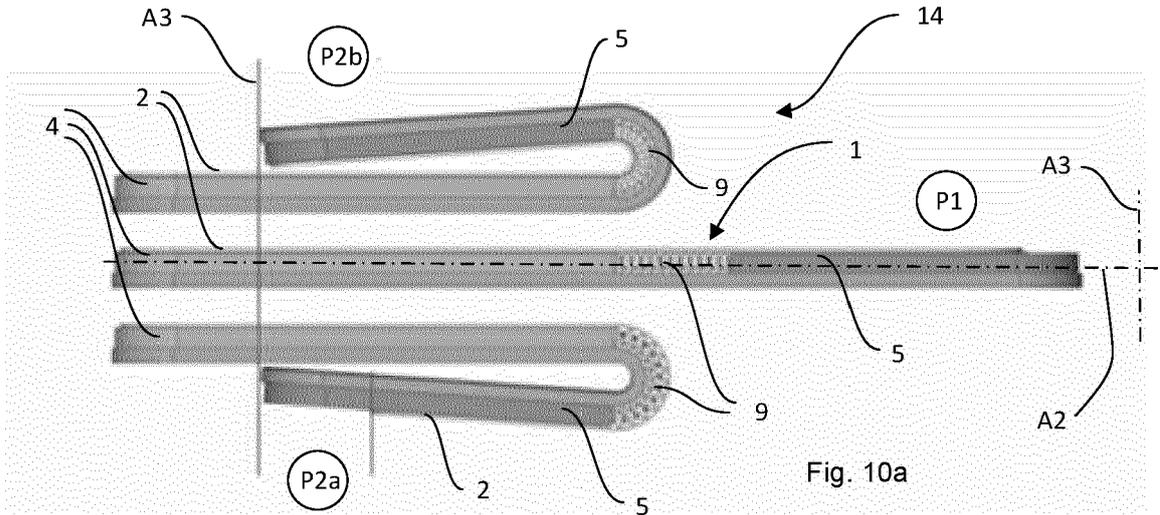


Fig. 4









REFERENCES CITED IN THE DESCRIPTION

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Patent documents cited in the description

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